

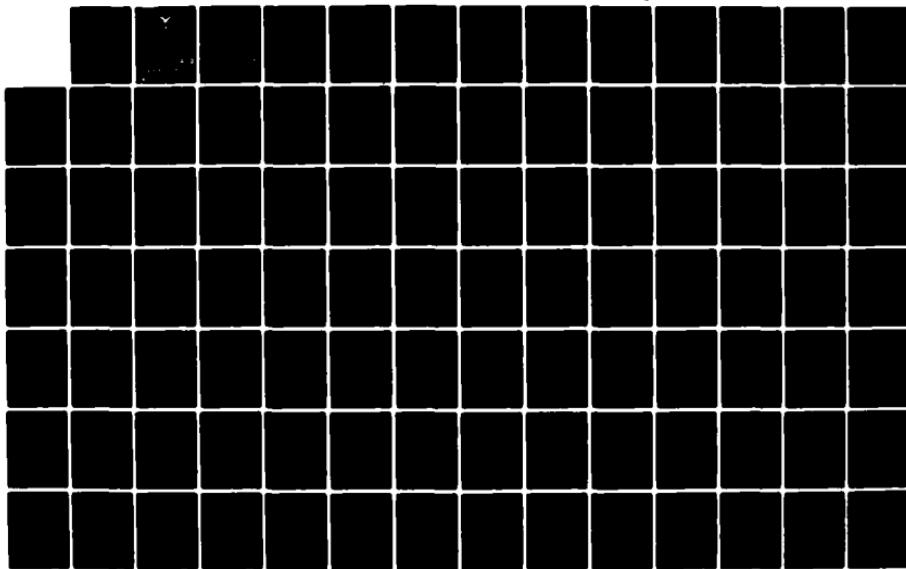
AD-A124 700 DEVELOPMENT OF AN OCULOMETER DATA COLLECTION SUBSYSTEM 1/2  
(U) AIR FORCE INST OF TECH WRIGHT-PATTERSON AFB OH  
SCHOOL OF ENGINEERING N L WOOD DEC 82

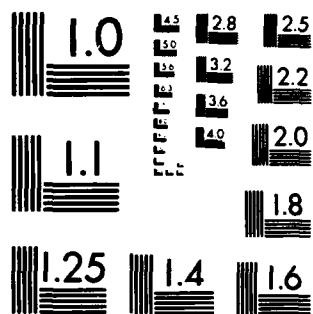
UNCLASSIFIED

AFIT/GE/EE/82D-72

F/G 9/2

NL





MICROCOPY RESOLUTION TEST CHART  
NATIONAL BUREAU OF STANDARDS-1963-A

ADA 124700



3-D  
SELECTED  
ITEMS

C

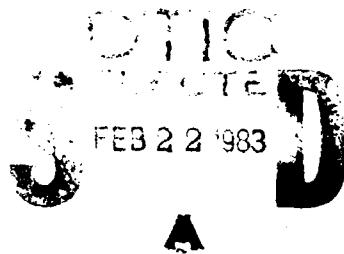
30

AFIT/GE/EE/82D-72

DEVELOPMENT OF AN OCULOMETER  
DATA COLLECTION SUBSYSTEM

THESIS

AFIT/GE/EE      Nancy L. Wood  
                  Capt      USAF



Approved for public release; distribution unlimited

DEVELOPMENT OF AN OCULOMETER  
DATA COLLECTION SUBSYSTEM

THESIS

Presented to the Faculty of the School of Engineering  
of the Air Force Institute of Technology  
Air University  
in Partial Fulfillment of the  
Requirements for the Degree of  
Master of Science

by

Nancy L. Wood, B.S.  
Capt USAF

Graduate Electrical Engineering

Dec 1982



Accession For	
NTIS	CE131
DTIC	TSB
Unsponsored	
Justification	
Ref.	
Distribution/	
Availability Status	
Avail	Number
Dist	Serial
A	

Approved for public release: distribution unlimited

### Preface

The Flight Dynamics Lab at Wright-Patterson AFB had procured an oculometer and two SYM-1's and various support equipment to collect data from the oculometer and present the reduced data in readable form. One SYM-1 system had been set up and initially tested but the oculometer was marginally operational. They needed someone to get acquainted with the SYM-1 and write the necessary software for the oculometer data collection subsystem. The project was ideal, because I wanted to do my thesis with the Flight Dynamics Lab and I also desired a software oriented thesis.

It was unknown from the start of the thesis whether the oculometer would be operating correctly or not. Because it was not operating correctly at thesis completion, the software was developed using simulated oculometer data. The data was as realistic as possible and the software written to be easily integrated into a system using the actual oculometer.

I would like to thank the Flight Dynamics Lab, specifically Mr. Bill Klotzback, for making the thesis possible and providing all the support and equipment I needed. Thanks also to Lt Jay Kirchoff and especially Lt Rick Benken, without whose encouragement, advice, and help the SYM-1 wouldn't have been so cooperative and those rough spots would have been a lot rougher.

My deepest thanks and gratitude go to my fiancee, Bruce Crowley, for listening to all my ravings when everything was going wrong and supported me through it all. Thank-you, Bruce.

## Contents

Preface . . . . .	ii
List of Figures . . . . .	vi
List of Tables . . . . .	vii
Abstract . . . . .	viii
I. Introduction . . . . .	1
Background . . . . .	1
Problem . . . . .	4
Scope . . . . .	5
Assumptions . . . . .	6
General Approach . . . . .	6
Sequence of Presentation . . . . .	7
II. Equipment . . . . .	8
III. Development of the Program . . . . .	10
General Development . . . . .	10
Module: Main Subsystem . . . . .	15
Module: Initialization . . . . .	15
Module: Store Data . . . . .	18
Module: Add Timing . . . . .	19
Module: Determine Instrument Number . . . . .	21
Module: Compare Data Samples . . . . .	23
Module: Create Table . . . . .	24
Module: Print Results . . . . .	27
IV. Module Validation . . . . .	29
Module: Main Subsystem . . . . .	31
Module: Initialization . . . . .	31
Module: Store Data . . . . .	32
Module: Add Timing . . . . .	32
Module: Determine Instrument Number . . . . .	33
Module: Compare Data Samples . . . . .	33
Module: Create Table . . . . .	34
Module: Print Results . . . . .	34
V. Subsystem Validation . . . . .	36
VI. Subsystem Timing . . . . .	38
VII. Users Guide . . . . .	39

VIII. Recommendations . . . . .	47
Bibliography . . . . .	48
Appendix A: SYM-1 Memory Map . . . . .	50
Appendix B: Oculometer Connector for Digital Data Output . . . . .	51
Appendix C: Pascal-Like Description of Modules . . . . .	52
Appendix D: Assembly Language Implementation of Modules . . . . .	64
Appendix E: Module Validation Data . . . . .	125
Appendix F: Simulated Oculometer Input for Subsystem Validation . . . . .	132
Appendix G: Final Data Tables and Outputs . . . . .	134

## List of Figures

<u>Figure</u>		<u>Page</u>
1	Subsystem Data Flow Diagram .. . . . .	1
2	Structure Chart for Main Module . . . . .	13
3	Structure Chart for Print Results Module ..	14
4	Instrument Boundaries . . . . . . . . .	22
5	Simulated Instrument Boundaries for Subsystem Validation . . . . . . . . .	37
6	Test Instrument Boundaries . . . . . . .	127

## List of Tables

<u>Table</u>		<u>Page</u>
1	Subsystem Variable Initialization . . . . .	17
2	Final Data Table Row Organization . . . . .	25
3	Final Data Table Column Organization . . . .	25
4	Module Worst Case Timing . . . . . . . . .	38
5	Division Validation Data . . . . . . . . .	125
6	Add Timing Validation Data . . . . . . . . .	126
7	Determine Instrument Number Validation Data .	127
8	Compare Data Samples Validation Data . . . .	128
9	Create Table Validation Data . . . . . . .	129
10	Create Table Validation Results . . . . . .	130

### Abstract

A SYM-1 microprocessor with dual 5 1/4 inch disk drives was used to develop software to gather and reduce data from a Cubic-Foot Remote Oculometer built by Honeywell, Inc. The primary function of the oculometer is to measure the look direction of a pilot's eye in a ground cockpit simulator. The output of the oculometer used for this effort is eye lookpoint in azimuth and elevation and whether the oculometer is tracking the eye or not. The line-of-sight measurement covers a viewing field of plus and minus 30 degrees in azimuth and zero to plus 30 degrees in elevation. This viewing field is broken into instruments whose boundaries are defined by the data collection subsystem.

The following performance measures are printed out at the end of the data mission:

1. Total dwell time on each instrument.
2. Mean dwell time on each instrument.
3. Proportion of dwell time on each instrument.
4. Proportion of fixations on each instrument.
5. Transition probability from one instrument to another.
6. Number of fixes per minute for each instrument.

The software for the SYM-1 was developed modularly with each module tested separately and then the whole subsystem tested. Simulated oculometer data was used to test the

software. The data collection subsystem was designed to run with minimal knowledge and interaction required by the user.

## I. Introduction

### Background

This thesis involves the development of software to gather and reduce the output of a device called an oculometer. This is accomplished with a SYM-1 microprocessor system. The following paragraphs briefly describe the operation and uses of the oculometer, and the specific application addressed by the thesis.

An oculometer is an electro-optical device that tracks the eye line-of-sight in two axes without interfering with the subject. The subject, for Air Force applications, is a pilot. The oculometer can be used either in a ground simulator or in an actual aircraft in flight. Uses of the oculometer include two-dimensional tracking where the eye line-of-sight is used for fire control system control, the evaluation of different types of cockpit landing displays, quantifying pilot scan patterns during various phases of flight, and testing and evaluating different types of aircraft cockpit displays.

The oculometer used for this thesis was the "Cubic-Foot Remote Oculometer" built by Honeywell, Inc of Lexington Massachusetts (Ref 1).

The primary function of the oculometer is to measure the look direction of the subjects eye without interfering

with any of his activities. Information on pupil diameter and blink rate can also be obtained.

A sensing subsystem illuminates the subject's eye and collects information on the eye's orientation. A near-infrared (IR) illumination source and an IR-sensitive TV camera are used to obtain a video signal which contains the necessary information about the eye. The IR illumination causes no physical discomfort to the eye and does not cause the pupil diameter to decrease appreciably.

The measurement principle of the eye lookpoint is based on the fact that the angular direction of the eye is proportional to the position of the corneal reflection of the IR light source relative to the center of the pupil. The oculometer can locate the eye and track it throughout a one cubic foot motion box.

The line-of-sight measurement of the oculometer covers a viewing field of plus and minus 30 degrees in azimuth and zero to plus 30 degrees in elevation. The average error in eye tracking is approximately one degree. The oculometer must be calibrated for each subject to eliminate nonlinearities in the viewing field. The parameters for up to six pilots can be stored, so the subject can be tested again without full calibration of the oculometer.

The output of the oculometer is eye lookpoint in azimuth and elevation, pupil diameter, and whether the oculometer is tracking the eye or not. The oculometer loses track of the eye when the pilot moves his eye out of the

range of the tracking equipment. For example, the oculometer will lose track of the eye if the pilot looks behind him. This loss of track is called an out-of-track condition. If the eye image is lost, automatic search procedures are initiated to reacquire it (Ref 2,3).

Oculometer measurements are useful in testing integrated aircraft displays and, coupled with flight path and control input data, to detect subtle differences in piloting techniques during simulated flight (Ref 4). Another use for the oculometer is in the placement of cockpit instruments. Ground and/or flight data can be collected which indicates which instrument needs to be in the center of the pilot's field of view (i.e. the instrument most often looked at) and which instruments need to be in close proximity (i.e. two instruments which have a high number of transitions from one to the other) (Ref 5). The oculometer has been used to evaluate individual displays in the cockpit, and to evaluate changes in displays (Ref 6,7).

The Flight Dynamics Lab at Wright-Patterson Air Force Base, Ohio would like to use the oculometer during 12-18 minute ground data missions in flight simulators to gather data on the pilots lookpoint with respect to cockpit instruments, or segments of instruments. The data will be collected and analyzed by an oculometer data collection subsystem. This data will be used for cockpit design and analysis. Presently, the oculometer data is not being

gathered or reduced. The lab requires thesis completion before the oculometer output can be utilized.

Problem

The problem is to develop an oculometer data collection subsystem that will collect, reduce, print out, and store the data from a data mission.

The following performance measures need to be calculated and stored for each mission:

1. Total dwell time on each instrument or instrument section.
2. Mean dwell time on each instrument or instrument section.
3. Proportion of dwell time spent on each instrument or instrument section.
4. Proportion of fixations on each instrument or instrument section.
5. Transition probability from one instrument to another.
6. Number of fixes per minute for each instrument or instrument section.

The performance measures will be printed out between data missions.

## Scope

The oculometer data collection subsystems is to be used in a ground environment in a cockpit simulator. The use of the subsystem in the airborne environment is not addressed.

The cockpit can be subdivided into rectangular or square subsections which can be instruments, segments of instruments, or any area within the viewing field of the oculometer. The subsections are defined by specifying two diagonal corners. The oculometer subsystem design allows for a maximum of 24 instrument subsections to be defined. For an additional seven subsections to be defined, there would be a 25 percent increase in memory space required and in program complexity. Another consideration is that the amount of time between oculometer inputs is 16.67 msec. The more instrument subsections defined, the longer is the time to determine the instrument number for each oculometer input.

The data runs are planned to be from 12-18 minutes long. The data runs are broken into time increments, with each time increment equalling one millisecond. One millisecond was chosen because it was small enough to allow accurate timing of the time between oculometer data samples, which is a minimum of 16.67 milliseconds. A data run of 18 minutes requires  $1.08 \times 10^5$  time increments. This requires a minimum of three SYM-1 eight bit words, or bytes. Therefore, three bytes were used for the storage of timing information. These three bytes allow for data missions up

to 279 minutes long (3 bytes = 16,777215 time increments = 279 minutes).

#### Assumptions

The assumptions are that the oculometer used will be the Honeywell Cubic Foot Oculometer with a digital X and Y direction and track/no track outputs, and that the data collection subsystem is to be used in a ground cockpit simulator.

#### General Approach

Two SYM-1 single board microprocessors were available for the data collection subsystem. The original concept was to have one SYM-1 gather the data from the oculometer, do some preliminary data reduction, and pass the data to the second SYM-1. This SYM-1 would complete the data reduction to produce the final tabular form. As the algorithms were developed, it became apparent that there was adequate time available between data inputs from the oculometer to do all data reduction. There was also enough random access memory (RAM) available on one SYM to store the data reduction programs and the final reduced data table. Therefore, one SYM-1 was used for the data collection subsystem.

The data collection subsystem algorithms were designed using the concepts of structured design. Structured design is a disciplined approach to algorithm design which

simplifies system design by partitioning the system into "black boxes" and organizes these boxes hierarchically. Structured design produces systems that are easy to understand, reliable, flexible, long-lasting, and efficient to operate (Ref 8).

Good design uses the concepts of partitioning and organizing the pieces of the system. Partitioning refers to the division of the problem into small subproblems. Highly interrelated parts of the problem should be in a single black box. A black box is a component with known inputs, known outputs, and generally, a known transform but the contents of the box don't have to be known (Ref 9). The modules were tested with simulated data, since the oculometer was not operational.

#### Sequence of Presentation

Chapter II describes the equipment used and the configuration of the equipment. The memory map for the SYM-1 is discussed. Chapter III describes how the subsystem was developed using Pascal-like statements, a data flow diagram for the overall program and a structure chart. Each program module is discussed. Chapter IV details the data used to test each module and Chapter V describes the testing of the overall data collection subsystems. Chapter VI describes subsystem timing. Chapter VII details the users guide for operation of the subsystem during ground data missions.

## II. Equipment

The following equipment was used to develop the oculometer data collection subsystem:

- One SYM-1 single board microprocessor
- One Hudson Digital Electronics (HDE) 15 slot 19 inch cage with power supply
- Four HDE 8K RAM boards
- One HDE 8K EPROM board
- One parallel input/output board
- One HDE dual 5-1/4 inch disk drive unit
- One Hazeltine 1500 CRT terminal

### Software:

- Editor/assembler in ROM
- Disk operating system
- Editor on disk

This equipment was purchased for the subsystem before thesis start. Appendix A shows the memory map of the SYM-1.

The unassembled modules are loaded into the Resident Assembler/Editor from disk at memory locations 0200 (hex) to 14FF (hex). When assembled, the modules reside at memory locations 0000 (hex) to 002F hex), 1500 (hex) to 224C (hex) and 6000 (hex) to 7000 (hex). The final data table is from 6000 (hex) to 63FF (hex), and the simulated oculometer input data starts at 6490 (hex). The Resident Assembler Editor and the SYM-1 stack uses memory locations 0A00 (hex) to

0F00 (hex). The memory locations used from 0000 (hex) to 0024 (hex) are used for zero page addressing. The actual program is not stored here. The modules were placed back-to-back, with approximately 20 (hex) memory locations between them.

There is unused memory from 224D (hex) to 5FFF (hex), 7000 (hex) to 7FFF (hex), and 9000 (hex) to 9FFF (hex).

### III. Development of the Program

#### General Development

This section describes the overall subsystem logic and each module. The program was developed by breaking it down into a series of modules, and developing each module into a subroutine. Therefore, the main program is merely a series of calls to subroutines.

The data flow diagram (DFD) is used to partition a system and is a major tool of structured analysis. A DFD is a network representation of a system showing the active components and the data interfaces (Ref 8). The DFD is a tool used to define the proposed logical system. It is useful in identifying the functions of a system and the resultant data transformations (Ref 9).

The basic elements of a DFD are called transforms and are represented by circles. A transform represents transformations of data from one form to another. The data elements themselves are labeled arrows going into the transforms (Ref 10).

Figure 1 shows a data flow diagram for the subsystem. Each module is represented by a transform with the data passed between modules represented by the data elements.

Structure charts are an integral part of structured design methodology. A structure chart shows the partitioning of a system into modules, the hierarchy and

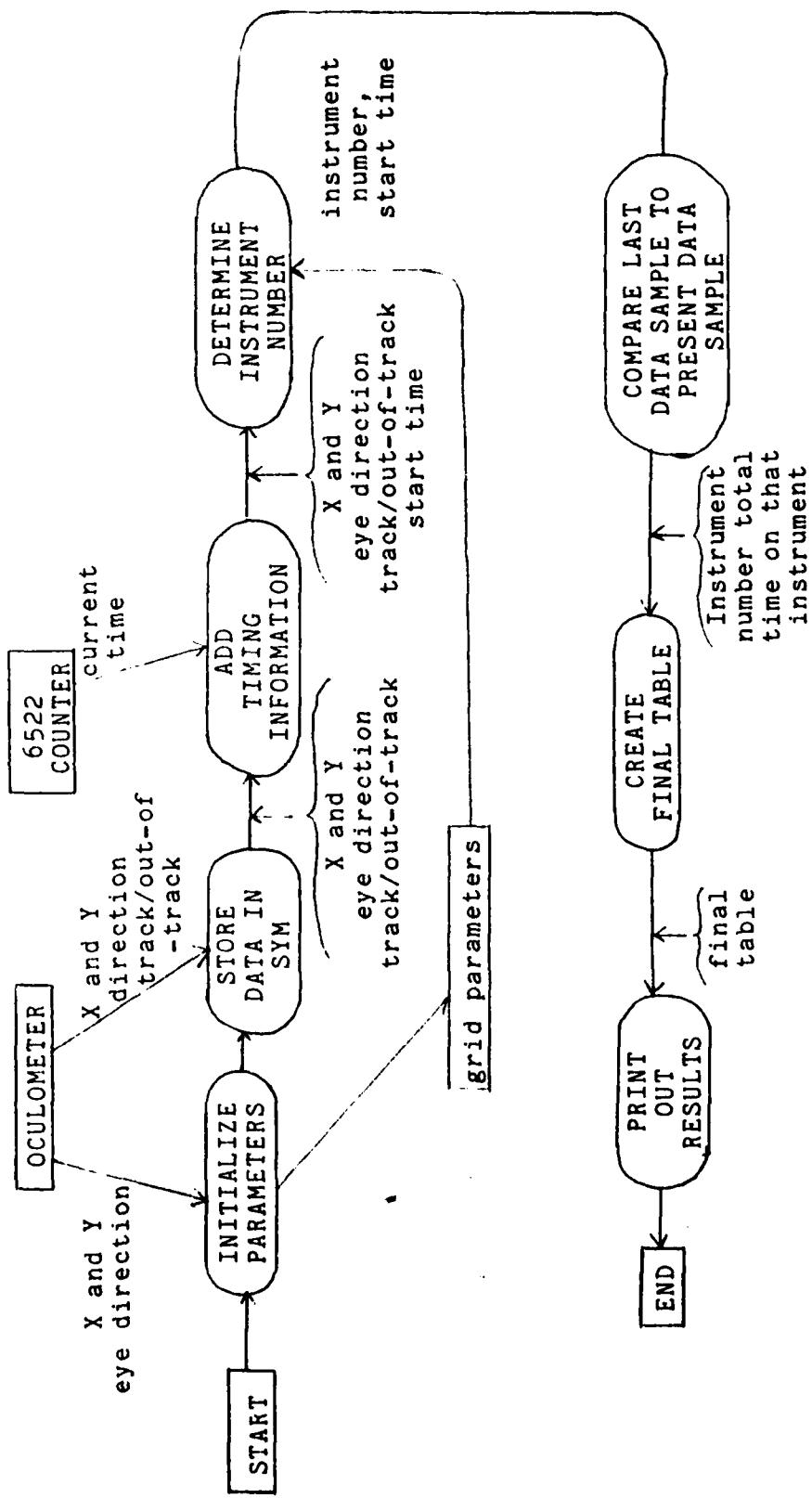


Fig 1. Subsystem Data Flow Diagram

organization of modules, the communication between modules, and the functions of the modules (Ref 8,11).

Each module is represented by a rectangle identified by a name. Modules are connected by arrows. A data element passed between two modules is shown by an arrow with an open circle, and control communication by an arrow with a solid circle. A major decision between two or more modules is designated by a diamond, and a major loop by a semicircle.

Figures 2 and 3 are the structure charts for the Main module and the Print Results module.

A data dictionary is used, among other things to establish a glossary of terms, to provide standard terminology and define all terms, to provide cross-reference capability, and to resolve problems associated with aliases and acronyms (Ref 11). The Initialization module defines the address for all variables used by two or more modules called by the Main module. The remaining variables are declared locally in the declaration section of each module. Therefore, the declaration section of each module serves as a data dictionary.

Each module is discussed, with a Pascal-like description in Appendix C and the assembly language implementation in Appendix D.

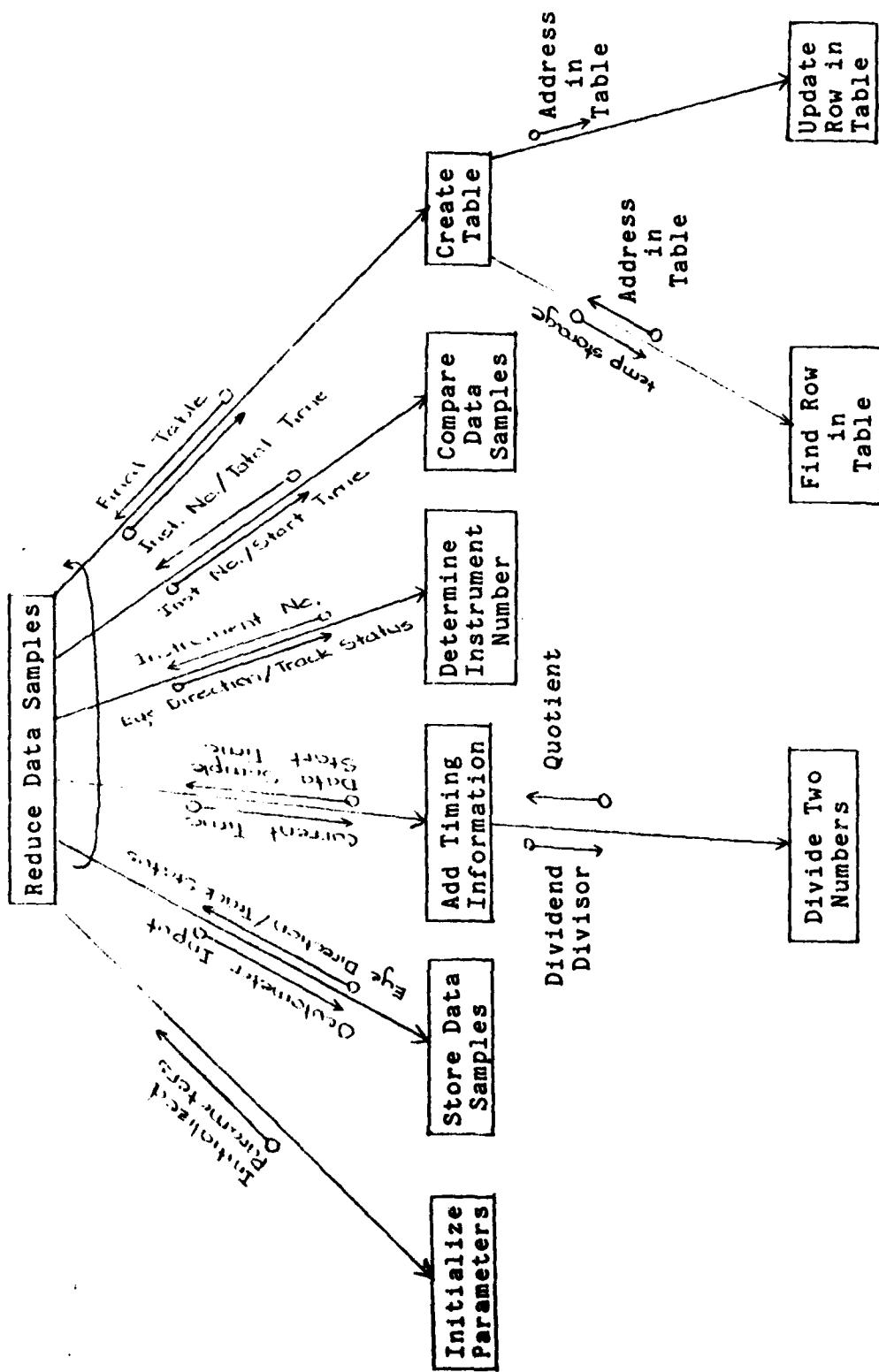


Fig 2. Structure Chart For Main Module

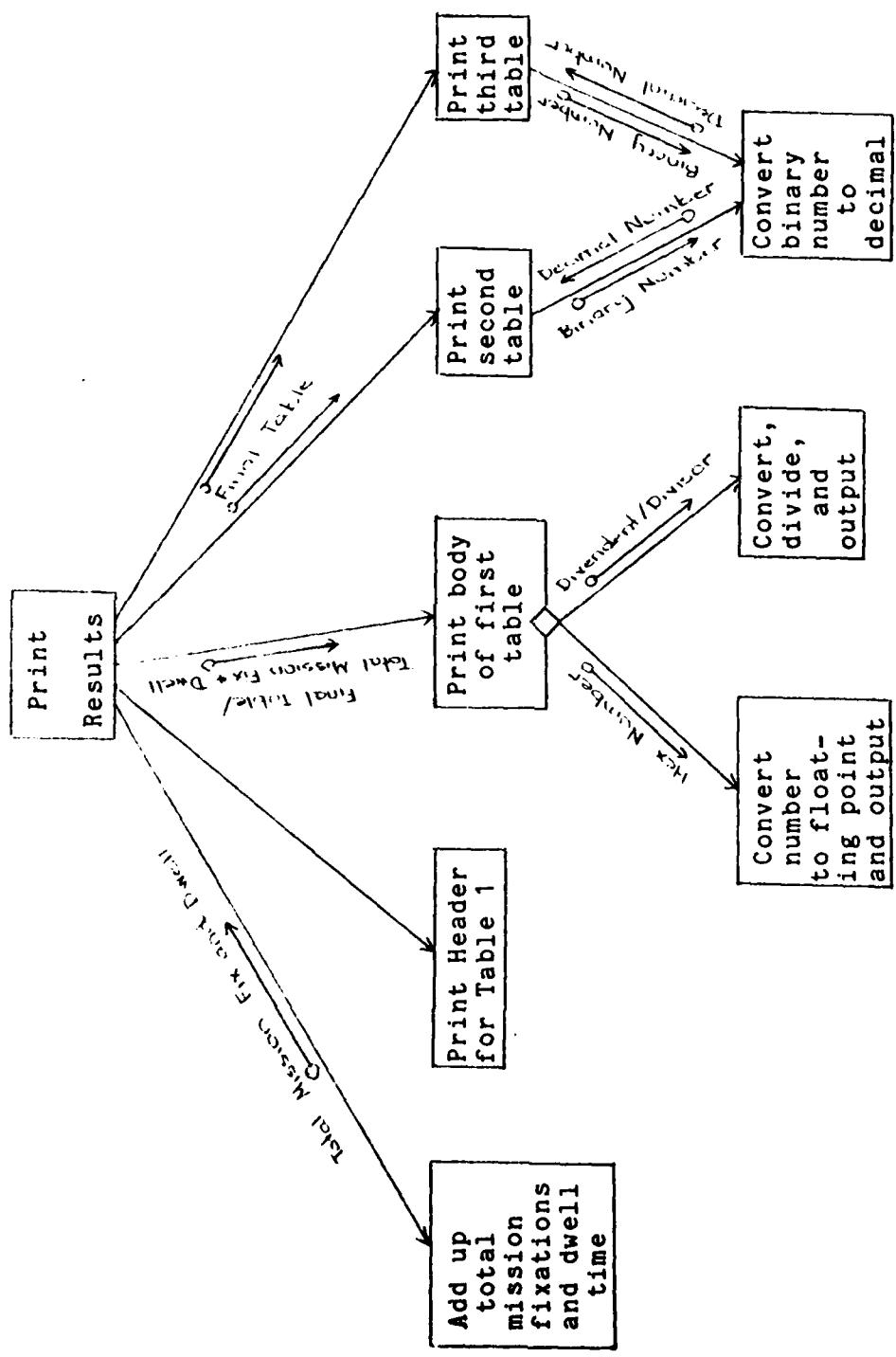


Fig 3. Structure Chart for Print Results Module

### Main Subsystem Module

The Initiation module is called by the Main module once at the start of the data mission. Modules Store Data, Add Timing, Determine Instrument Number, Compare Data Samples, and Create Table are called by the Main module each time a data sample comes from the oculometer. Module Print Results is run separately when the data mission is complete. The Main module also has a timing loop to simulate the time between oculometer data samples. The timing loop is approximately 20 milliseconds long. At the end of the loop, the Store Data (Simulated) module is called, followed by Add Timing, Determine Instrument Number, Compare Data Samples and Create Table. Then the Main module checks to see if it is at the end of the array containing the simulated oculometer inputs (see module Store Data). If not, the timing loop is executed again and the process repeated.

Appendix C describes the module in Pascal-like statements. Appendix D lists the assembly language implementation of the module.

### Module: Initialize Parameters

This module is called by the Main module before the actual data mission begins. It initializes parameters used in various modules and creates a "grid" of values that defines the boundaries of the instruments, or segments of instruments. The grid parameters were simulated because

actual oculometer data were not available. If the oculometer was available, the grid parameters would be obtained by having the subject look at the four corners of each instrument, and storing the parameters with the associated instrument number.

Table 1 shows each of the parameters, or program variables, that are initialized, the module(s) that uses the parameter, and the value the parameter is initialized to. GRID represents the grid parameters that were simulated.

The SY6522 timer is initialized by the module and starts counting the number of time increments that have passed from the beginning of the data mission. The SY6522 is initialized so it interrupts every 65 milliseconds, or every 65 time increments. At each interrupt, 65 is added to LOTIM, MITIM, and HITIM. These are three bytes that represent the number of time increments from the beginning of the data mission to the last interrupt. The interrupt routine is in the module.

The module also establishes the addresses for all variables used by two or more modules. Variables used by only one module are declared inside that module.

Appendix C describes the module in Pascal-like statements. Appendix D lists the assembly language implementation of the module.

Table I			
Subsystem Variable Initialization			
<u>Variable</u>	<u>Module(s) That Use Variable</u>	<u>Initialization Value</u>	<u>Description</u>
LSTART1	Compare Data Samples		Start time of last data sample
LSTART2		00	
LSTART3			
LASTIN	Compare Data Samples	00	Last data sample instrument number
LOTIM	Add Timing Information	00	Number of time increments since beginning of data run
MITIM			
HITIM			
TABLE1	Create Table	00	Initialize final data table to zero
TABLE2			
TABLE3			
TABLE4			
OLDIN	Create Table	00	Last instrument number through create table

### Module: Store Data

This module is called by the Main module every time a data sample comes from the oculometer. Because the oculometer data is simulated, the Main module calls the Store Data module using a timing loop.

The oculometer output is X eye direction (10 bits), Y eye direction (10 bits), and track/out-of-track status (1 bit). This output is called the current data sample.

When the oculometer is used, the X and Y eye direction is obtained from a connector on the back of the oculometer. Appendix B is the pin connections for the connector. The outputs for pupil diameter are not used.

The oculometer is considered to be "in track" if it is tracking the eye. If the oculometer loses track of the light reflection off the back of the eye, either due to the pilot blinking or moving his eyes outside the tracking area of the oculometer, the oculometer is out-of-track. An out-of-track condition is a logic 0 on the track/out-of-track status line. When the oculometer is out-of-track, the X and Y eye direction remains the same as the last output before the oculometer went out-of-track.

The X direction is stored as 2 bytes, Y direction as 2 bytes, and track/out-of-track status as 1 byte. The oculometer represents negative numbers in two's complement form. Therefore, if the 10th bit from the oculometer is a

zero, the number is positive, and if the 10th bit is one, the number is negative.

Two Store Data modules were developed. Store Data (Oculometer) was designed to be used with the actual oculometer. This module stores X and Y eye direction in 4 bytes by filling in bits 11 through 16 of the high byte of each with either one's or zero's, depending on whether the number is positive or negative. It also stores track/out-of-track status as a one or a zero. These 5 bytes of information are passed to the next module, Add Timing.

The second module is Store Data (Simulated). This module reads simulated X and Y eye direction data and track/out-of-track status from memory and stores them in the same 5 bytes as the Store Data (Oculometer) module.

Appendix C describes both modules in Pascal-like statements. Appendix D lists the assembly language implementation of Store Data (Simulated).

#### Module: Add Timing

This module adds the necessary timing information to the X and Y eye direction and track/out-of-track status from the Store Data module. The timing information which is added is three bytes that represent the number of time intervals that have elapsed from the beginning of the data mission to the time of the data sample. One time interval is equal to 1 millisecond.

A SY6522, Versatile Interface Adapter, is used for the timing of the data mission. The device is programmed to interrupt the SYM every 65 milliseconds. The SY6522 is initialized in the Initialization module and started at the beginning of the data mission. Every time the SY6522 interrupts, 65 is added to three bytes that represent the number of time intervals that have elapsed since the start of the data mission. These three bytes are named LOTIM, MITIM, and HITIM.

When Add Timing is called, the current 2-byte value of the SY6522 counter is read. This counter counts down from 65000 to zero, interrupts at zero, and automatically reloads 65000 back into the counter and repeats the process. Each count down takes 1 microsecond, therefore the counter will interrupt every 65 milliseconds. Add Timing reads the 2-byte counter, divides the counter value by 1000, subtracts from 65 to get the number of milliseconds that have passed since the last SY6522 interrupt, adds this value to the three bytes LOTIM, MITIM, and HITIM, and stores the resultant 3 bytes with the X and Y direction information of the current data sample.

Therefore, at the end of the Add Timing module, the current data sample consists of X and Y eye direction, track/out-of-track status, and three bytes that represent the number of time intervals from the start of the mission to the current data sample.

Appendix C describes the module in Pascal-like statements. Appendix D lists the assembly language implementation of the module.

Module: Determine Instrument Number

This module takes the X and Y eye direction and track/out-of-track status of the current data sample and defines an instrument number for the sample. The timing information of the data sample remains unchanged.

A grid is created in the Initiation module that defines the boundaries for the cockpit instruments, or segments of instruments. Each instrument is defined by the coordinates of the four corners of the instrument. The grid has a format of upper X, lower X, upper Y, lower Y, and instrument number for each instrument (Fig. 2).

The coordinates are 2 bytes each. Each instrument's boundaries are defined in the grid. The order in which the instrument boundaries are stored in the grid is not important. If both the upper and lower values of X or Y are negative, the "lower" value is defined as the lower of the absolute values. For example, if the X coordinates of the instrument are -5 and -7, -5 is the upper X value and -7 is the lower X value. An instrument boundary cannot cross the Y axis. If an instrument does, the instrument must be broken into two sections.

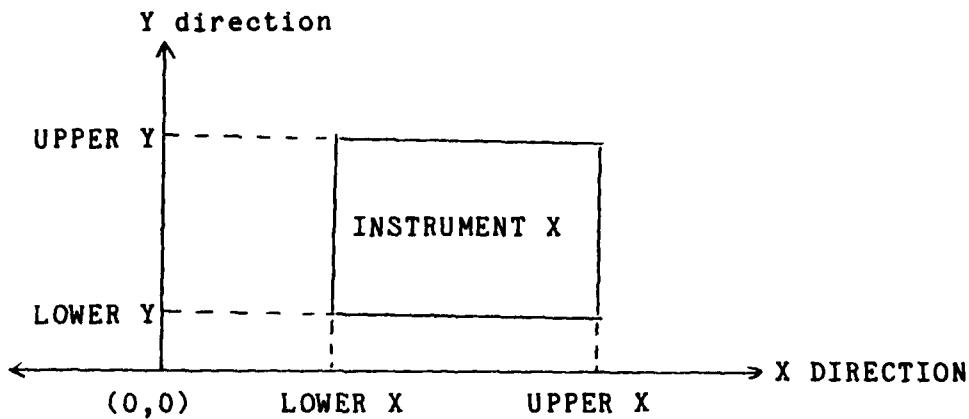


Fig 4. Instrument Boundaries

The instrument boundary coordinates are read and compared to the X and Y eye direction values to see if they are within that instrument. If they are, that instrument number is assigned to the current data sample. If not, the next instrument boundary coordinates in the grid are compared to the X and Y eye direction value. If the X and Y eye direction values are not within any of the defined instruments, the instrument number defined as no instrument is assigned to the present data sample.

If the present data sample is out-of-track, no instrument boundary comparisons are made and the instrument number for the present data sample is zero.

At the completion of the Determine Instrument Number module, the present data sample consists of an instrument

number (1 byte) and the timing information that represents the number of time intervals since the beginning of the data mission (3 bytes).

Appendix C describes the module in Pascal-like statements. Appendix D lists the assembly language implementation of the module.

#### Module: Compare Data Samples

This module compares the last data sample's instrument number to the present data sample's instrument number.

If the instrument numbers are the same, the current data sample is disregarded because the pilot is still on the same instrument.

If the two instrument numbers are different, the start time (3 bytes) of the last data sample is subtracted from the start time of the current data sample (3 bytes). The result is the total number of time increments spent on the instrument of the last data sample (3 bytes). This total number of time increments and the associated instrument number is sent to the Create Table module. Then the current data sample becomes the last data sample in preparation for the next data sample to go through the module.

Appendix C describes the module in Pascal-like statements. Appendix D lists the assembly language implementation of the module.

### Module: Create Table

This module takes each data sample and places the information in a final data table. The data sample consists of an instrument number (INSTNM) and the number of time increments spent on that instrument (TOTIM1, TOTIM2, TOTIM3).

The purpose of the table is to reduce the data to a form that enables the calculation of the performance parameters.

The table is divided into four sections: TABLE1, TABLE2, TABLE3, and TABLE4. Each table contains seven rows. Each row contains information for an instrument, blink, glitch, or data gone. A "glitch" is any data sample where the number of time increments is less than or equal to 50. A "blink" is a data sample with an instrument number of zero (an out-of-track condition) and the number of time increments between 50 and 183. "Data gone" is a data sample with an instrument number of zero and the total number of time increments greater than 183.

Table 2 shows the organization of the information in the data tables. Table 3 shows the format of each of the rows. A '\$' in front of a number means the number is in base 16. A "no instrument" condition is defined as instrument number 25. Therefore, 24 instruments can be defined. The total number of fixations is the number of times the instrument was looked at. The accumulated time is the total amount of time spent on that instrument.

Table II  
Final Data Table Row Organization

<u>Starting Memory Location</u>	<u>Contents</u>	<u>Starting Memory Location</u>	<u>Contents</u>
TABLE1 + 00	Glitch	TABLE3 + 00	Inst 12
TABLE1 + \$22	Blink	TABLE3 + \$22	Inst 13
TABLE1 + \$44	Data Gone	TABLE3 + \$44	Inst 14
TABLE1 + \$66	Inst 1	TABLE3 + \$66	Inst 15
TABLE1 + \$88	Inst 2	TABLE3 + \$88	Inst 16
TABLE1 + \$AA	Inst 3	TABLE3 + \$AA	Inst 17
TABLE1 + \$CC	Inst 4	TABLE3 + \$CC	Inst 18
TABLE2 + 00	Inst 5	TABLE4 + 00	Inst 19
TABLE2 + \$22	Inst 6	TABLE4 + \$22	Inst 20
TABLE2 + \$44	Inst 7	TABLE4 + \$44	Inst 21
TABLE2 + \$66	Inst 8	TABLE5 + \$66	Inst 22
TABLE2 + \$88	Inst 9	TABLE4 + \$88	Inst 23
TABLE2 + \$AA	Inst 10	TABLE4 + \$AA	Inst 24
TABLE2 + \$CC	Inst 11	TABLE4 + \$CC	Inst 25

Table III  
Final Data Table Column Organization

<u>Byte Number</u>	<u>Contents</u>
0	data gone
1 - 25	instruments 1 through 25
26, 27	unused
28	low byte of accumulated time
29	middle byte of accumulated time
30	high byte of accumulated time
31	low byte of total number of fixations
32	high byte of total number of fixations
33	unused

Appendix C describes the module in Pascal-like statements. The module first determines if the current data sample is a glitch. If it is, the glitch row is updated. If it is not a glitch, it next looks at the instrument number. If the instrument number is a zero, either the blink or data gone row is updated. If it was data gone, the instrument number of the current data sample becomes the "last instrument number" (OLDIN). OLDIN was the last instrument looked at. This is used so the probability of transitioning from one instrument to another can be calculated in the final module. If the instrument number was not zero (and it is not a glitch), the appropriate row for that instrument is updated and the instrument number of the current data sample becomes the last instrument number.

Updating a row consists of incrementing the number of fixations, incrementing the column that corresponds to the current last instrument, and adding the number of time increments of the current data sample to the accumulated time.

Appendix D lists the assembly language implementation of the module.

### Module: Print Results

This module prints our the performance measures using module prints out the performance measures using the data in the Final Data Table. In the following paragraphs, each of the performance measures are discussed.

1. Total dwell time on each instrument. The three byte accumulated time (byte numbers 28, 29 and 30, see Table 3) is printed out for instruments 1 through 25, data gone, blink and glitch.

2. Mean dwell time on each instrument. The accumulated time for an instrument is divided by the total number of fixations for that instrument. This value is the mean dwell time for that instrument. The mean dwell time is printed out for instruments 1 through 25, data gone, blink and glitch.

3. Proportion of dwell time on each instrument. The accumulated times for instruments 1 through 25 is added up and called total time (TOTIM1, 2 and 3). The accumulated time for an instrument is divided by total time to get the proportion of dwell time on an instrument.

4. Proportion of fixations on each instrument. The total number of fixations for instruments 1 through 25 is added up and called total fixations (TOTFIX1 and 2). The total number of fixations for an instrument is divided by

total fixations to get the proportion of fixations on an instrument.

5. Transitions from one instrument to another. For each instrument 1 through 25, data gone, glitch and blink, the number in the column for each instrument (columns 1 through 25, see Table 3) is printed.

6. Number of fixes per minute for each instrument. The total number of fixations for each instrument is divided by the total number of minutes in the mission.

Floating point routines are used for division and decimal output operations in performance measures 1,2,3,4 and 6. The routines used were derived from floating points routines found in Reference 12. Performance measure 5 requires the data in the table to be printed out in decimal format. The routine to convert from binary to decimal was found in Reference 13.

A description of the module in Pascal-like statements is in Appendix C with the assembly language implementation in Appendix E. Examples of the final printout are in Section V.

#### IV. Module Validation

The validation of each individual module is discussed in this section. A few of the modules were tested together, but most of the modules were developed and validated independently. The validation of the total subsystem is discussed in Section V.

Testing is an important part of any software development program. Testing is done with the intent of finding errors. There are two major categories of testing: black-box testing and white-box testing. In black-box testing, the tester views the program as a black box and is unconcerned with the internal structure of the program. It is also known as input/output driven testing because the tests are derived solely from the specifications. White-box testing uses knowledge of the internal structure of the program. The test cases examine the program's logic.

Because it is impossible to test every possible input case, a test of any program must be necessarily incomplete. Therefore, the test cases should try and detect the most errors possible. There are various methodologies used to intelligently select test cases. The methodologistics that were used in the thesis are described briefly below.

White-box testing is also called logic coverage testing. The logic coverage testing used is called decision/condition coverage. This type of testing ensures that:

1. every statement is executed at least once
2. each decision has a "true" and a "false" outcome at least once
3. each condition in a decision takes on all possible outcomes at least once.

Three types of black box testing were used: equivalence partitioning, boundary-value analysis and error guessing.

In equivalence partitioning, a subset of all inputs is chosen that has the highest probability of finding all errors. This is accomplished by picking test cases that reduce, by more than one, the number of test cases that must be developed, and that cover a large set of other possible test cases.

Boundary-value analysis examines input and output boundary conditions. The boundaries are near the edges of the input and output equivalence classes.

Error guessing is largely an intuitive process. Test cases are designed using intuition and experience to try and expose certain probable types of errors (Ref 14).

Decision/condition coverage was used to test all the modules. Other tests used are stated in the test descriptions of each module.

Module: Main

The Main module was tested with the Initialization and Store Data modules. The Main module prints out a prompt to start the data mission, calls all other modules (except Print Results) and executes a timing loop to simulate the time between data samples. Therefore, the validation of this module consisted of the following:

1. The proper response to the prompt is the letter 's'. Other letters were input to determine if only an 's' would start the data mission (boundary value testing and equivalence partitioning).
2. The timing loop was tested during the Timing module. The output of the Timing module was examined to determine if the timing loop was operating correctly.
3. The subroutine calls to each subroutine were added to Main one at a time. As each module was added, the output of that module was examined to determine if the module was operating correctly. The modules were added in the order they are called.

Module: Initialization

The Initialization module establishes addresses for variables used by two or more modules, initializes the SY6522 counter and initializes various variables to zero.

Equivalence partitioning and error guessing techniques were used.

For all variables initialized, the memory locations were examined to ensure their contents were correct.

Correct operation of the SY6522 Counter was examined in the Add Timing module.

#### Module: Store Data

This module merely stores the X and Y eye direction and track/out-of-track status. For the oculometer simulation, simulated data was stored at specified memory locations and read by the Store Data module. Equivalence partitioning was used. Verification of this module consisted of examining the memory locations for X and Y eye direction and track/out-of-track status to verify that the simulated data was being read correctly.

#### Module: Add Timing

The Add Timing module uses a division subroutine that divides a two-byte dividend by a two-byte divisor (which was 1000 for this application) to get a two-byte quotient and a two-byte remainder. Only the quotient is used by Add Timing. The divisor is 1000 because the timing information from the SY6522 is in microseconds, and the time increment desired is milliseconds.

The test cases for the division subroutine are shown in Appendix E. These cases use the equivalence partitioning technique. The division subroutine was developed and tested separately and then used in Add Timing.

Appendix E also shows the test data from Add Timing. An 18 msec loop was executed and at the end of the loop, the number of time increments from the beginning of the data mission was determined and stored and the timing loop was executed again. The module also tested the SY6522 counter interrupt routine. The SY6522 was started at the beginning of the module and kept track of the elapsed time intervals. These test cases were acquired from equivalence partitioning and error guessing techniques.

#### Module: Determine Instrument Number

This module determines an instrument number for each data sample from the X and Y eye direction data and the track/out-of-track status. Data samples were simulated and instrument numbers determined. Boundary value and equivalence partitioning tests were conducted. Appendix E contains the test data samples examined and the test instrument boundaries used.

#### Module: Compare Data Samples

This module compares the present data sample to the last data sample. If the two instrument numbers are the

same, nothing is done. If they are different, the total time on the last instrument is determined and this time and the last instrument number is sent to the Create Table module.

The module was tested by reading in simulated data samples consisting of an instrument number and the time of the data sample, and outputting instrument numbers and the total time on each instrument. Large and small time values were examined (boundary value testing) and random values of time were tested (equivalence partitioning). The test data is shown in Appendix E.

#### Module: Create Table

The Create Table module takes the information from the Compare Data Sample module and places the information in a table. The table is from address 6000 through 63FF in the SYM memory. Appendix E shows the data used to test the module. The simulated input data consisted of an instrument number and the time on that instrument. The output was the data in the table. The format of the table was described in Section III. Error guessing and equivalence partitioning were used.

#### Module: Print Results

This module takes the data from the final table and prints the results out in three tables. The information

printed out is described in Section III. Examples of the final data table are in Appendix G.

The module was tested by using the random numbers in memory locations 6000 (hex) to 6400 (hex). This is the location of the final data table. The values computed and printed were compared to the contents of the memory locations to verify correct module operation. This is equivalence partitioning testing.

## V. Subsystem Validation

The subsystem was validated using simulated oculometer input data and simulated parameters for the instrument boundaries. Figure 5 shows the simulated instrument boundaries used. The testing methodology used was equivalence partitioning. All instruments and out-of-track conditions were simulated. Various time increments on the instruments were examined. The final data table was examined for validity, and the three output tables were compared to the final data table. Appendix G is the actual SYM-1 output of the final data tables and the corresponding printed output.

One value in the three tables is incorrect. This is the number of fixations for glitch in Table 1. There is an error in the floating point routines. This error remained at thesis completion.

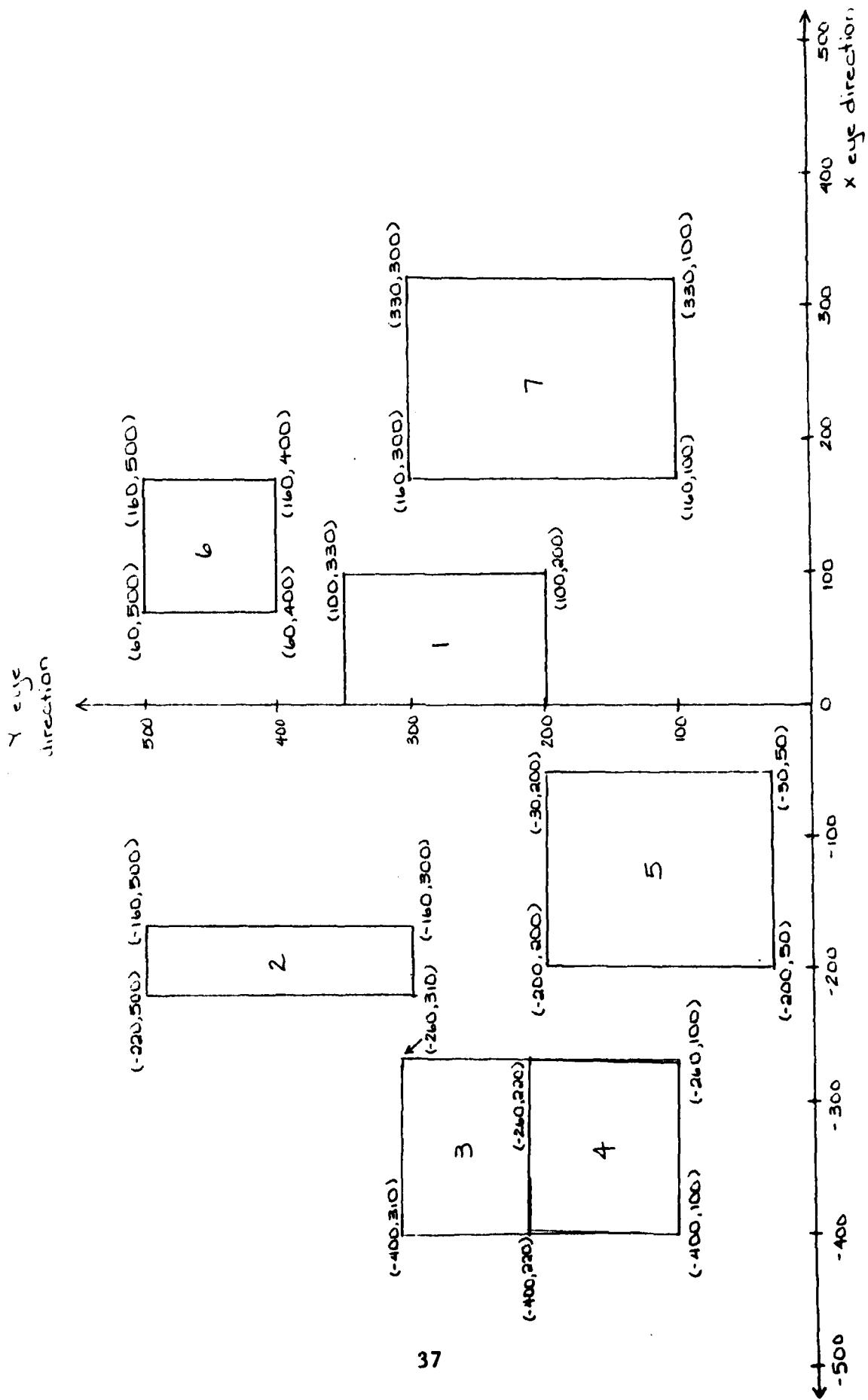


Fig 5. Simulated Instrument Boundaries for Subsystem Validation

## VI. Subsystem Timing

The timing of the five modules called by the Main module each time a data sample is input from the SYM is critical. The five modules are Store Data, Add Timing, Determine Instrument Number, Compare Data Samples, and Create Table. These five modules have to be completed in the amount of time between oculometer data sample. The minimum amount of time between data samples is 16.67 milliseconds.

Each module was examined for worst case timing. The worst case timing for each is shown in Table 5.

Table 4  
Module Worst Case Timing

<u>Module</u>	<u>Number of Machine Cycles</u>
Store	61
Interrupt	51
Add Timing	2561
Determine Instrument Number	7195
Compare Data Samples	135
Create Table	437
Main	49

The total number of machine cycles is 10489, or 10.489 msec. Therefore, there is more than adequate time between data samples for all six modules.

## VII. User's Guide

The following is a guide to using the oculometer data collection subsystem. Items underlined are responses by the SYM-1. Items capitalized are those input by the user. <cr> is a carriage return.

### 1. Power the SYM-1

When power is applied, the SYM-1 responds with a "beep"

### 2. Load disks

Put the diskette marked "System Disk" into the right hand disk drive and the diskette marked "oculometer subsystem" into the left hand disk drive

### 3. Assemble subsystem modules

Hit "Q" on the keyboard. The SYM-1 will respond with a period. Then key in the following sequence of events:

\_ G 5000 (Note: the space between "G" and "5000" is not keyed in by the user. It is automatically inserted by the SYM-1)

RAE V1.0

FODS COPYRIGHT (a) 1980 HDE INC

0200-0BEC 0C00-0EEC 0F00

0200 0C00

> SET \$0200 \$1100 \$1101 \$1300 <cr>

0200-1100 1101-1300 0F00

0200 0C00

≥ LOAD INIT <cr>

≥ AS <cr>

LL0000,3028,3028

≥ CL <cr>

≥ LOAD STORE <cr>

≥ AS <cr>

LL0000,1A94,1A94

≥ CL <cr>

≥ LOAD TIMDIV <cr>

≥ AS <cr>

LL0000,1B44,1B44

≥ CL <cr>

≥ LOAD TIMING <cr>

≥ AS <cr>

LL0000,1B8E,1B8E

≥ CL <cr>

> LOAD INSTNM <cr>

> AS <cr>

//0000,1C63,1C63

> CL <cr>

> LOAD COMPAR <cr>

> AS <cr>

//0000,1CDD,1CDD

> CL <cr>

> LOAD UPDAT <cr>

> AS <cr>

//0000,2115,2115

> CL <cr>

> LOAD INCR <cr>

> AS <cr>

//0000,2149,2149

> CL <cr>

> LOAD MASTER <cr>

```
> AS <cr>  
//0000,224B,224B  
> CL <cr>
```

```
> LOAD MAIN <cr>
```

```
> AS <cr>  
//0000,647A,647A  
>
```

#### 4. Start data mission

```
> RUN MAIN <cr>  
HIT S to START MISSION = S
```

Any other character than "S" will not start the simulated data mission and another prompt will be printed out. No other user intervention is required until the program is completed and a ">" is printed.

The program using the actual oculometer instead of simulated data will require a set-up program before the data mission starts. This set-up program will establish the instrument boundaries. The boundaries were hand entered for the simulated data runs. The data mission using the oculometer would be started the same way as the simulated data mission (by running the Main module). The actual data mission would end by hitting reset (RST) on the SYM-1 on-board keyboard. The remainder of the User's Guide is the

same for both the simulated and actual data missions.

5. Print out results.

$\geq$  SET \$0200 \$1300 \$1301 \$1500 <cr>

0200-1300 1301-1500 OF00

0200 0C00

$\geq$  CL <cr>

$\geq$  LOAD THREE <cr>

$\geq$  AS <cr>

110000,2028,2028

$\geq$  CL <cr>

$\geq$  LOAD SEVEN <cr>

$\geq$  AS <cr>

110000,20BB,20BB

$\geq$  CL <cr>

$\geq$  LOAD FPMUL <cr>

$\geq$  AS <cr>

110000,21CE,21CE

$\geq$  CL <cr>

≥ LOAD CONVE <cr>

≥ AS <cr>

LL 0000,223F,223F

≥ CL <cr>

≥ LOAD FPDIV <cr>

≥ AS <cr>

LL0000,2324,2324

≥ CL <cr>

≥ LOAD FPCOUT <cr>

≥ AS <cr>

LL0000,241F,241F

≥ CL <cr>

≥ LOAD PRINT <cr>

≥ AS <cr>

LL0000,2487,2487

≥ CL <cr>

≥ LOAD TOVAL <cr>

≥ AS <cr>

11000,283F,283F

≥ CL <cr>

≥ LOAD OUTPT <cr>

≥ AS

11000,2A1E,2A1E

≥ CL <cr>

>LOAD OUTTB <cr>

≥ AS <cr>

11000,2BB0,2BB0

≥ CL <cr>

≥ LOAD RESTB <cr>

≥ AS <cr>

11000,2D4F,2D4F

≥ CL <cr>

≥ LOAD OUTTC <cr>

≥ AS <cr>

11000,3730,3730

≥ CL <cr>

> LOAD OUTTD <cr>

> AS <cr>

//0000,3929,3929

> CL <cr>

> LOAD BINDEC <cr>

> AS <cr>

//0000,39D7,39D7

> CL <cr>

> LOAD FINAL <cr>

> AS <cr>

//0000,3A01,3A01

> RUN FINAL <cr>

All three final tables will print out.

## VIII. Recommendations

The oculometer data collection subsystem needs further development to be used with an oculometer. The following additional software is required:

1. Interface with the oculometer. The data from the oculometer needs to be accessed and stored in the SYM-1.
2. Establishment of instrument boundaries. Before the data mission is started, the pilot will look at two diagonal corners of each desired instrument. The X and Y eye direction values of the two corners are used to establish and store the instrument boundaries.
3. Generation of oculometer interrupt. Every time the oculometer generates a new data sample, the SYM-1 needs to be interrupted so the data can be stored by the SYM-1 and used.
4. Correction of the floating point error in Table 1.

### Bibliography

1. Merchant, J. and Morrissette, R. A Remote Oculometer Permitting Head Movement. Aerospace Medical Research Laboratory, Aerospace Medical Division, Air Force Systems Command, Wright-Patterson Air Force Base, Ohio, November 1973 (AD 776075).
2. Middleton, David B., George J. Hurt, Marlon A. Wise, and James D. Holt. Description and Flight Tests of an Oculometer. Langley Research Center, Hampton, Virginia, June 1977 (NASA TN D-8419).
3. Lambert, Robert H., Richard A. Monty, and Robert J. Hall. High-Speed Data Processing and Unobtrusive Monitoring of Eye Movements. US Army Human Engineering Laboratory, Aberdeen Proving Ground, Maryland, February 1975 (AD A006162).
4. Waller, Marvin C. Application of Pilot Scanning Behavior to Integrated Display Research. NASA Langley Research Center, Hampton, Virginia, August 1977.
5. Spady, Amos A. Airline Pilot Scanning Behavior During Approaches and Landing in a Boeing 737 Simulator. NASA Langley Research Center, Hampton, Virginia, October 1977.

6. Harris, R.L., M.C. Waller and S. Salmirs. Runway Texturing Requirements for a Head-Down Cathode Ray Tube Approach and Landing Display. NASA Langley Research Center, Hampton, Virginia, September 1978.
7. Waller, M.C., R.L. Harris, and S. Salmirs. An Evaluation of Some Display Parameters for an Advanced Landing Display. NASA Langley Research Center, Hampton, Virginia, August 1979.
8. Page-Jone, Meilir. The Practical Guide To Structured Systems Design. New York: Yourdon Press, 1980.
9. Yourdon, Edward and Larry L. Constantine. Structured Design. New York: Yourdon Press, 1978.
10. Weinberg, Victor. Structured Analysis. New York: Yourdon Press, 1980.
11. Peters, Lawrence J. Software Design: Methods and Techniques. New York: Yourdon Press, 1981.
12. Findley, Robert. 6502 Software Gourmet Guide and Cookbook. Connecticut: Scelbi Computer Consulting, Inc, 1979.
13. Leventhal, Lance A., Winthrop Saville. 6502 Assembly Language Subroutines. California: OSBORNE/McGraw-Hill, 1982.
14. Myers, Glenford J. The Art of Software Testing. New York: John Wiley & Sons, 1979.

APPENDIX A  
SYM-1 Memory Map

Memory Location

FFFF	-----	SYM-1 Operating System Locations
- EFFF	-----	
- DFFF	-----	Resident Assembler/Editor
- CFFF	-----	
- BFFF	-----	
- AFFF	-----	Resident Assembler/Editor
- 9FFF	-----	Disk controller
- 8FFF	-----	4K RAM
- 7FFF	-----	SUPERMON (SYN-1 Operating System)
- 6FFF	-----	8K RAM
- 5FFF	-----	
- 4FFF	-----	8K EPROM
- 3FFF	-----	
- 2FFF	-----	RAM
- 1FFF	-----	
--OFOO--	-----	Resident Assembler/Editor, Stack
--OA00--	-----	
0000	-----	RAM

## APPENDIX B

### Oculometer Connector for Digital Data Output

Connector type: ITT # KPT02E20 - 41S

<u>Pin Number</u>	<u>Pin Output</u>
1	bit 1 - MSB of X eye direction
2	bit 2
3	bit 3
4	bit 4
5	bit 5
6	bit 6
7	bit 7
8	ground
9	bit 8
10	bit 9
11	bit 10 - LSB of X eye direction
12	clock
13	+5 volts DC
14	bit 1 - MSB of Y eye direction
15	bit 2
16	bit 3
17	bit 4
18	bit 5
19	bit 6
20	bit 7
21	ground
22	bit 8
23	bit 9
24	bit 10 - LSB of Y eye direction
25	clock
26	+5 volts DC
27	bit 1 - LSB of pupil diameter
28	bit 2
29	bit 3
30	bit 4
31	bit 5
32	bit 6
33	bit 7
34	ground
35	bit 8
36	bit 9
37	bit 10 - LSB of pupil diameter
38	clock
39	+5 volts DC
40	not connected
41	not connected

## APPENDIX C

### Pascal-like Description of Modules

#### 1. Module Main Subsystem

Variable definitions:

INIT : location of Initialization module

STORE : location of Store Data module

TIMING : location of Add Timing module

DETPNUM : location of Determine Instrument Number module

COMPAR : location of Compare Data Samples module

TABLE : location of Create Table module

TIMING : a timing loop 20 msec long

WRITELN ('HIT S TO START MISSION')

READ(CHAR)

IF CHAR = S THEN (\* start the mission \*)

BEGIN

    INIT (\* call INIT module \*)

    COUNT : = 0 (\* look at beginning of array  
                  that holds simulated  
                  oculometer output \*)

    TIMLOOP (\* execute timing loop that is 20 msec  
              long \*)

    STORE (\* call STORE module \*)

    TIMING (\* call TIMING module \*)

    DETPNUM (\* call DETPNUM module \*)

    COMPAR (\*call COMPAR module \*)

```
TABLE (* call TABLE module *)  
IF we are at the end of simulated oculometer  
output THEN Main module is done  
ELSE go back to TIMING  
END  
ELSE (*character is not an S*) print out another prompt  
to start the mission
```

## 2. Module Initialization

Variable definitions:

LSTRT1, LSTRT2, LSTRT3 : start time of last data sample

LASTIN : instrument number of last data sample

LOTIM, MITIM, HITIM : number of time increments since beginning of data run

OLDIN : last instrument through create table

Declare all variables in two or more modules

LSTRT1 : = 0

LSTRT2 : = 0

LSTRT3 : = 0

LASTIN : = 0

LOTIM : = 0

MITIM : = 0

HITIM : = 0

OLDIN : = 0

Final Data Table : = 0

Initialize 6522 Counter

Store interrupt routine

### 3. Module Store Data (Simulated)

Variable definitions:

DATA[I] : array that contains simulated oculometer output in the format of XDIRH, XDIRL, YDIRH, YDIRL, TRACK. The end of the array is a 'D'.

XDIRH : high byte of X eye direction

XDIRL : low byte of X eye direction

YDIRH : high byte of Y eye direction

YDIRL : low byte of Y eye direction

TRACK : track/out-of-track status; = 0 if out-of-track

COUNT : pointer to keep track of where you are in the DATA array. It is initialized to zero in the Main module.

XDIRH : = DATA [COUNT]

COUNT : = COUNT + 1

YDIRL : = DATA [COUNT]

COUNT : = COUNT + 1

YDIRH : = DATA [COUNT]

COUNT : = COUNT + 1

YDIRL : = DATA [COUNT]

COUNT : = COUNT + 1

TRACK : = DATA [COUNT]

COUNT : = COUNT + 1

### Module Store Data (Oculometer)

Variable definitions:

XDIRL : low 8 bits of X direction

XDIRH : hi 8 bits of X direction

```
YDIRL : low 8 bits of Y direction
YDIRH : hi 8 bits of Y direction
TRACK : track/out-of-track status
READ bits 1-8 of X direction into bits 0-7 of XDIRL
READ bits 9-10 of X direction into bits 0-1 of XDIRH
READ bits 1-8 of Y direction into bits 0-7 of YDIRL
READ bits 9-10 of Y direction into bits 0-1 of YDIRH
IF bit 1 of XDIR = 1 THEN (* it was a negative
    number *) set bits 2-7 of XDIRH to 1
ELSE (* it was a positive number *) set bits 2-7 of
    XDIRH to 0
IF bit 1 of YDIRH = 1 THEN (* it was a negative
    number *) set bits 2-7 of YDIRH to 1
ELSE (*it was a positive number *) set bits 2-7 of
    YDIRH to 0
IF oculometer out-of-track THEN TRACK : = 0
ELSE (* oculometer is in track *) TRACK : = 1
```

#### 4. Module Add Timing

Variable definitions:

```
LOTIME : low byte of time intervals elapsed to the
        last 6522 interrupt
MITIME : middle byte of time intervals elapsed to the
        last 6522 intervals
HITIME : high byte of time intervals elapsed to the
        last 6522 interrupt
LCOUNT : low byte of 6522 counter
HCOUNT : high byte of 6522 counter
START1 : low byte of number of time intervals elapsed
        to the current data sample
```

START2 : middle byte of number of time intervals elapsed to the current data sample

START3 : high byte of number of time intervals elapsed to the current data sample

READ HCOUNT and LCOUNT

Divide HCOUNT, LCOUNT by 1000 and subtract from 65

Add this to LOTIME, MITIME, HITIME and store result in START1, START2, START3

## 5. Module Determine Instrument Number

Variable definitions:

XDIR : X eye direction of current data sample

YDIR : Y eye direction of current data sample

GRID[I] : array with instrument boundaries followed by the instrument number with a format of upper X, lower X, upper Y, lower Y, instrument number. There is an 'E' at the end of the array

NOINST : instrument number for no instrument

INST : the data sample's instrument number

TRACK : track/out-of-track status of current data sample. It is equal to zero if data sample is out-of-track

XH : storage for upper X boundary from GRID

XL : storage for lower X boundary from GRID

YH : storage for upper Y boundary from GRID

YL : storage for lower Y boundary from GRID

CURINS : storage for instrument number from GRID

```

I : = 1
IF TRACK = 0 THEN
    INST := 0
ELSE
    WHILE not at the end of GRID DO
        BEGIN
            XH : = GRID [I]
            I : = I + 1
            XL : = GRID [I]
            I : = I + 1
            YH : = GRID [I]
            I : = I + 1
            YL : = GRID [I]
            I : = I + 1
            CURINS : = GRID [I]
            I : = I + 1
            IF XH - XDIR < 0 THEN
                it cannot be in that instrument so
                go back to WHILE and get another
                set of instrument boundaries
            IF XL - XDIR > 0 THEN
                go back to WHILE and get another
                set of instrument boundaries
            IF YH - YDIR < 0 THEN
                go back to WHILE and get another
                set of instrument boundaries
            IF YL - YDIR > 0 THEN
                go back to WHILE and get another
                set of instrument boundaries
            (* If the data sample made it through
            all the tests, it was within that
            instrument's boundaries *)

```

```
INST : = CURINS  
END (* WHILE *)  
(* If reached the end of GRID and no instrument number  
was found, define the instrument as no instrument *)  
IF reached the end of GRID THEN INST : = NOINST
```

## 6. Module Compare Data Samples

Variable definitions:

```
INST : current data sample's instrument number  
LASTIN : last data sample's instrument number  
START : start time of current data sample  
LSTRT : start time of last data sample  
TOTIM : total number of time increments on LASTIN.  
This is sent to the next module  
INSTNM : instrument number sent to the next module  
with TOTIM
```

```
IF LASTIN ≠ INST THEN  
BEGIN  
    TOTIM : = START - LSTRT  
    INSTNM : = LASTIN  
    LASTIN : = INST  
    LSTRT : = START  
END  
(* ELSE if they are not equal, disregard the data  
sample *)
```

## 7. Module Create Table

Variable definitions:

INSTNM : instrument number of the current data sample

TOTIM : total number of time increments of the current current data sample

OLDIN : instrument number of the last data sample through the module if the sample was not a glitch or a blink.

GLITCH, BLINK, DATAGN, INS1..25 : each represents the starting address of a row in the table for that instrument. Each row is 33 bytes long.

IF TOTIM < 50 THEN (\* the data sample is a glitch \*)

BEGIN

increment GLITCH + 31, 32 (\* 31 and 32 are bytes for number of fixations \*)

increment GLITCH + OLDIN (\* determine which instrument was transitioned from \*)

add TOTIM to GLITCH + 28, 29, 30 (\* bytes 28, 29, and 30 represent the amount of time spent on that instrument \*)

END

ELSE (\*it is not a glitch\*)

IF INSTNM = 0 THEN (\* it is out-of-track \*)

IF TOTIM ≤ 183 THEN

(\* it is a blink \*)

BEGIN

increment BLINK + 31, 32

increment BLINK + OLDIN

add TOTIM to BLINK + 28, 29, 30

END

```
        ELSE (*it is data gone *)
        BEGIN
            increment DATAGN + 31, 32
            increment DATAGN + OL DIN
            add TOTIM to BLINK + 28, 29, 30
            OL DIN : = INSTNM
        END
        ELSE (*it is not out-of-track so it is an
              instrument*)
        BEGIN
            X : = INSTNM
            increment INSX + 31, 32
            increment INSX + OL DIN
            add TOTIM to INSX + 28, 29, 30
            OL DIN : = INSTNM
        END
```

#### 8. Module: Print Results

Variable definitions:

TABLE[I] : location of final data table

NEXTINST : difference in location between the same data  
in two instruments

ACCTIME : location of accumulated time

FIX : location of the total number of fixations for an  
instrument

TOTIME : total accumulated time for all instruments

TOTFIX : total number of fixations for all instruments

```
MINUTES : total number of minutes in a mission
FIXMIN : number of fixes per minute for an instrument
TRANS[I] : number of transitions from instrument I to
            the instrument you are examining
MEANDWL : mean dwell time for an instrument
PROPDWL : proportion of dwell time on an instrument
PROPFIX : proportion of fixations for an instrument
(*print out total dwell time on each instrument*)
DO WHILE there are instruments
    BEGIN
        WRITELN (TABLE[ACCTIME])
        (*go to the next instrument*)
        ACCTIME := ACCTIME + NEXTIN
    END
(*print out mean dwell time on each instrument*)
DO WHILE there are instruments
    BEGIN
        MEANDWL := TABLE[ACCTIME]/TABLE[FIX]
        WRITELN (MEANDWL)
        (*go to next instrument*)
        ACCTIME := ACCTIME + NEXTINST
        FIX := FIX + NEXTINST
    END
(*print proportion of dwell time on each instrument*)
DO WHILE there are instruments
```

```
BEGIN  
    TOTIME := TOTIME + TABLE[ACCTIME]  
    ACCTIME := ACCTIME + NEXTINST  
END  
  
DO WHILE there are instruments  
BEGIN  
    PROPDWL := TABLE[ACCTIME]/TOTIME  
    WRITELN(PROPDWL)  
    (*go to the next instrument*)  
    ACCTIME := ACCTIME + NEXTINST  
END  
(*print proportion of fixations on each instrument*)  
  
DO WHILE there are instruments  
BEGIN  
    TOTFIX := TOTFIX + TABLE[FIX]  
    FIX := FIX + NEXTINST  
END  
  
DO WHILE there are instruments  
BEGIN  
    PROPFIX := TABLE[FIX]/TOTFIX  
    WRITELN (PROPFIX)  
    (*go to next instrument*)  
    FIX := FIX + NEXTINST  
END  
(*print transition probabilities*)  
DO WHILE there are instruments
```

```
BEGIN
    FOR I := 1 to 25 DO
        WRITELN(TRANS[I])
        (*go to the next instrument*)
        FIX := FIX + NEXTIN
    END
    (*print number of fixes per minute for each instrument*)
    DO WHILE there are instruments
        BEGIN
            FIXMIN := TABLE[FIX]/MINUTES
            WRITELN(FIXMIN)
            (*go to next instrument*)
            FIX := FIX + NEXTINST
        END
```

## APPENDIX D

### Assembly Language Implementation of Modules

#### 1. Module: Initialization

M10MD INIT

```
0FF  
0010      .BA $1823  
0020      .DS  
0040 ;DEFINE ADDRESSES FOR ALL VARIABLES USED BY TWO MORE  
0050 ;MODULES. THE FOLLOWING ARE USED BY STORE DATA AND  
0051 ;DETERMINE INST NUM.  
0060 XDIRH    .DS 1      ;HI BYTE OF X EYE DIRECTION  
0070 XDIRL    .DS 1      ;LO BYTE OF X EYE DIRECTION  
0080 YDIRH    .DS 1      ;HI BYTE OF Y EYE DIRECTION  
0090 YDIDL    .DS 1      ;LO BYTE OF Y EYE DIRECTION  
0100 TFACE    .DS 1      ;TRACK/OUT-OF-TRACK STATUS  
0110 ;THE FOLLOWING ARE USED BY ADD TIMING AND COMPARE  
0120 TART1    .DS 1      ;3 BYTES OF TIMING INFORMATION  
0130 TART2    .DS 1      ;FOR CURRENT DATA SAMPLE  
0140 TART3    .DS 1 ;  
0150 ;THE FOLLOWING ARE USED BY INST NUM AND COMPARE  
0160 INSTNM   .DS 1      ;INST NUM SENT TO CREATE TABLE  
0161 ;THE FOLLOWING ARE USED BY TIMING AND CREATE TABLE  
0170 TOTIM1   .DS 1      ;TOTAL TIME SPENT  
0180 TOTIM2   .DS 1      ;ON INSTNM  
0190 TOTIM3   .DS 1 ;  
0200 ;THE FOLLOWING IS USED BY COMPARE AND CREATE TABLE  
0210 INST    .DS 1      ;INST NUM OF CURRENT DATA SAMPLE  
0220 ;THE FOLLOWING ARE USED BY INITIALIZATION AND COMPARE  
0231 ;AND CREATE TABLE  
0240 LSTPT1   .DS 1      ;START TIME OF  
0240 LSTPT2   .DS 1      ;LAST DATA SAMPLE  
0250 LSTPT3   .DS 1 ;  
0260 LASTIN   .DS 1      ;INST NUM OF LAST DATA SAMPLE  
0270 ;THE FOLLOWING ARE USED BY INITIALIZATION AND ADD TIMING  
0280 LOTIM    .DS 1      ;NUMBER OF TIME INCREMENTS  
0290 MITIM    .DS 1      ;SINCE BEGINNING OF  
0300 HITIM    .DS 1      ;DATA RUN  
0310 ;THE FOLLOWING ARE USED BY INITIALIZATION AND CREATE TABLE  
0320 LHT     .DS 1      ;LAST INST THROUGH CREATE TABLE  
0330 TABLE1   .DE $E000    ;STORAGE LOCATIONS  
0340 TABLE2   .DE $E100    ;FOR FINAL  
0350 TABLE3   .DE $E200    ;DATA TABLE  
0360 TABLE4   .DE $E300 ;  
0370 ;SIMULATED GRID WITH A FORMAT OF UPPER X, LOWER X, UPPER Y,  
0371 ;LOWER Y, INSTRUMENT NUMBER. AN INSTRUMENT CANNOT CROSS THE Y  
0372 ;AXIS. IF BOTH LOWER AND UPPER X ARE NEG, THE UPPER X IS THE  
0373 ;ONE CLOSEST TO THE Y AXIS.  
0380 SPID     .BY 00 $64 $00 $00 $01 $5E $00 $C8 01  
0390 SPID1    .BY $FF $60 $FF $24 $01 $F4 $01 $2C 02
```

0400	GRI2	.BY \$FE \$EC \$FE \$70 \$01 \$36 \$00 \$DC 03
0410	GRI3	.BY \$FE \$EC \$FE \$70 \$00 \$DC \$00 \$64 04
0420	GPI4	.BY \$FF \$E2 \$FF \$38 \$00 \$C8 \$00 \$32 05
0430	GPI5	.BY \$00 \$A0 \$00 \$3C \$01 \$F4 \$01 \$90 06
0440	GPI6	.BY \$01 \$4A \$00 \$A0 \$01 \$2C \$00 \$64 07 'E'
0444		.BA \$19D6
0450	;THE FOLLOWING ARE USED FOR INITIALIZATION THE 6522	
0460	ACR	.DE \$A00B ;6522 AUXILIARY CONTROL REGISTER
0470	LLATCH	.DE \$A006 ;6522 LO LATCH
0480	HLATCH	.DE \$A005 ;6522 HI LATCH AND COUNTER
0490	LCOUNT	.DE \$A004 ;6522 LO COUNTER
0500	IER	.DE \$A00E ;6522 INTERRUPT ENABLE REG
0510	IMOVEC	.DE \$A67E ;SYSTEM INTERRUPT VECTOR
0520	ACCESS	.DE \$8B86 ;UNPROTECT SYSTEM RAM
0530	LINT	.BY \$00 ;LO BYTE OF INTERRUPT LOCATION
0540	HINT	.BY \$30 ;HI BYTE OF INTERRUPT LOCATION
0550	:	
0560	INIT	LDA #00 ;INITIALIZE THE
0570		STA LSTRT1 ;NECESSARY
0580		STA LSTRT2 ;PARAMETERS TO
0590		STA LSTRT3 ;ZERO
0600		STA LASTIN
0610		STA LOTIM
0620		STA MITIM
0630		STA HITIM
0640		STA LAST
0650	;INITIALIZE FINAL DATA TABLE TO ZERO.	
0660		LDY #00
0670	G01	LDA #00
0680		STA TABLE1,Y
0690		INY
0700		CPY #\$FF
0710		BNE G01
0720		LDY #00
0730	G02	LDA #00
0740		STA TABLE2,Y
0750		INY
0760		CPY #\$FF
0770		BNE G02
0780		LDY #00
0790	G03	LDA #00
0800		STA TABLE3,Y
0810		INY
0820		CPY #\$FF
0830		BNE G03
0840		LDY #00
0850	G04	LDA #00
0860		STA TABLE4,Y
0870		INY
0880		CPY #\$FF
0890		BNE G04
0900		LDY #00
0910		LDA #00
0920		STA TABLE1,Y
0930		STA TABLE2,Y
0940		STA TABLE3,Y

```

1050 STA TABLE4,Y
1060 ;INITIALIZE 6522 COUNTER
1070 JSR ACCESS
1080 SEI
1090 LDA LINT
1100 STA IRQVEC ;LOAD ADDRESS OF
1110 LDA HINT
1120 STA IRQVEC+1 ; INTERRUPT ROUTINE
1130 LDA #$C0
1140 STA IER ;INITIALIZE IER
1150 LDA #$40
1160 STA ACR ;INITIALIZE ACR
1170 LDA #$E8 ;LOAD 65000 INTO
1180 STA LLATCH ; TIMER. TIMER
1190 LDA #$FD ; IS NOW RUNNING
1200 STA HLATCH
1210 CLI ;ENABLE INTERRUPTS
1220 RTS
1230 ;INTERRUPT ROUTINE TO ADD 65 TO THE CURRENT
1240 ;NUMBER OF TIME INTERVALS ELAPSED
1250 .BA $3000
1260 PHA
1270 LDA #$41
1280 CLC
1290 ADC LOTIM
1300 STA LOTIM
1310 LDA #$00
1320 ADC MITIM
1330 STA MITIM
1340 LDA #00
1350 ADC HITIM
1360 STA HITIM
1370 LDA LCOUNT ;CLEAR 6522 INTERRUPTS
1380 CLI ;ENABLE SYM INTERRUPTS
1390 PLA
1400 RTI
1410 .EN

```

## 2. Module: Store Data

ALOHD STORE

```
>FF  
0010      .BA $6490  
0020      .OS  
0040  $:SIMULATED OCULOMETER INPUT DATA IN FORM OF TRACK,X,Y  
0050  DATA     .BY 01 00 $3C 01 $2C 01 00 $3C 01 $2C 01 00 04 01 $2C  
0060  DATA1    .BY 01 00 04 01 $2C 01 00 04 01 $2C 01 00 04 01 $2C  
0070  DATA2    .BY 01 00 04 01 $2C 01 00 04 01 $2C 01 00 04 01 $90  
0080  DATA3    .BY 01 00 00 01 $90 01 00 00 01 $90 01 00 00 01 $90  
0090  DATA4    .BY 01 $FF $9C 00 $3C 01 $FF $9C 00 $3C 01 $FF $9C 00 $3C  
0100  DATA5    .BY 01 $FF $9C 00 $3C 01 $FF $9C 00 $3C 01 $FF $9C 00 $3C  
0110  DATA6    .BY 01 $FF $9C 00 $3C 00 $FF $9C 00 $3C 00 $FF $9C 00 $3C  
0120  DATA7    .BY 00 $FF $9C 00 $3C 01 $FF $9C 00 $64 01 $FF $9C 00 $64  
0130  DATA8    .BY 01 $FF $9C 00 $64 01 $FF $9C 00 $64 01 $FE $D4 00 $C8  
0140  DATA9    .BY 01 $FE $D4 00 $C8 01 $FE $D4 00 $C8 01 $FE $D4 $01 $2C  
0150  DATA10   .BY 01 $FE $D4 $01 $2C 01 $FE $D4 $01 $2C 01 $FE $D4 $01 $2C  
0160  DATA11   .BY 01 $FE $D4 $01 $2C 01 $FE $D4 $01 $2C 01 00 00 01 $90  
0170  DATA12   .BY 01 00 00 01 $90 01 00 00 01 $90 01 00 00 01 $90  
0180  DATA13   .BY 01 00 00 01 $90 01 00 $64 00 $64 01 00 $64 00 $64  
0190  DATA14   .BY 01 00 $64 00 $64 01 00 $64 00 $64 00 00 01 $90 01 'D'  
0200      .BA $1A70  
0210  XDIRH   .DE $1823  
0220  XDIRL   .DE $1824  
0230  YDIRH   .DE $1825  
0240  YDIRL   .DE $1826  
0250  TRACK    .DE $1827  
0260  STORE    LDA DATA,Y  
0270          STA TRACK  
0280          INY  
0290          LDA DATA,Y  
0300          STA XDIRH  
0310          INY  
0320          LDA DATA,Y  
0330          STA XDIRL  
0340          INY  
0350          LDA DATA,Y  
0360          STA YDIRH  
0370          INY  
0380          LDA DATA,Y  
0390          STA YDIRL  
0400          INY  
0410          RTS  
0420          .EN
```

### 3. Division routine called by Add Timing module

```
>LOAD TIMDIV
>PP
0010      .BA $1AA4
0020      .DS
0040 DIVHI   .DS 1      ;HIGH BYTE OF DIVISOR
0050 DIVLO   .DS 1      ;LOW BYTE OF DIVISOR
0060 REMHI   .DS 1      ;HI BYTE OF REMAINDER
0070 REMLO   .DS 1      ;LO BYTE OF REMAINDER
0080 QUDHI   .DS 1      ;HI BYTE OF DIVIDEND/QUOTIENT
0090 QUDLO   .DS 1      ;LO BYTE OF DIVIDEND/QUOTIENT
0091 COUNT   .DS 1
0100 ; THIS ROUTINE DIVIDES A TWO-BYTE DIVIDEND BY A
0110 ; 2-BYTE DIVISOR TO GET A 2-BYTE QUOTIENT AND A 2-BYTE
0120 ; REMAINDER
0130 START    LDA #00      ;INITIALIZE ALL VARIABLES
0140         STA REMHI
0150         STA REMLO
0151         STA COUNT
0160         LDA #$03
0170         STA DIVHI
0180         LDA #$E8
0190         STA DIVLO
0195 JSR SHIFT
0200 LOOP     SEC
0201         LDA REMLO
0202         SBC DIVLO
0203         STA REMLO
0204         LDA REMHI      ;REM-DIV
0205         SBC DIVHI
0206         STA REMHI
0207         BCS POS      ;IF CARRY=1, RESULT WAS POS
0208         LDA REMLO
0209         ADC DIVLO
0210         STA REMLO
0211         LDA REMHI
0212         ADC DIVHI
0213         STA REMHI
0214         JSR SHIFT
0215         JMP GO
0216 POS      LDA #01
0217         ORA QUDLO
0218         STA QUDLO
0219         JSR SHIFT
0220 GO       INC COUNT
0221         LDA #15
0222         CMP COUNT
0223         BNE LOOP
0224         RTS
0225 ; SUBROUTINE TO SHIFT THREE BYTES LEFT
0226 SHIFT    ASL QUDLO      ;SHIFT LEFT-0 INTO LSB
```

0510	BCC ONE	; IF CARRY=0, DON'T NEED
0520	ASL QU0HI	; TO BRING BIT OVER
0530	LDA #01	
0540	DRA QU0HI	
0550	STA QU0HI	; BRING CARRY OVER
0560	JMP TWO	
0570	ONE	ASL QU0HI
0580	TWO	BCC THREE
0590		ASL REMLO
0600		LDA #01
0610		DRA REMLO
0620		STA REMLO
0630		JMP FOUR
0640	THREE	ASL REMLO
0650	FOUR	BCC FIVE
0660		ASL REMHI
0670		LDA #01
0680		DRA REMHI
0690		STA REMHI
0700		JMP SIX
0710	FIVE	ASL REMHI
0720	SIX	DEC
0721		RTS
0730		.EN

#### 4. Module: Add Timing

##### LOAD TIMING

```
>FF  
0010      .BA $1B50  
0020      .DS  
0040  DIVIS    .DE $1AAB ;ROUTINE TO DIVIDE  
0050  QUOHI    .DE $1AA8 ;HI BYTE OF DIVIDEND/QUOTIENT  
0060  QUOLO    .DE $1AA9 ;LO BYTE OF DIVIDEND/QUOTIENT  
0070  LOTIME    .DE $1834 ;LO BYTE OF NUM OF TIME INTERVALS  
0080  MITIME    .DE $1835 ;MIDDLE BYTE OF TIME INTERVALS  
0090  HITIME    .DE $1836 ;HI BYTE OF TIME INTERVALS  
0100  HLATCH    .DE $A005 ;6522 HI LATCH  
0110  LCOUNT    .DE $A004 ;6522 LO COUNTER  
0120  START1    .DE $1828  
0130  START2    .DE $1829  
0140  START3    .DE $182A  
0150  TIMING    SEI  
0151 ;THIS MODULE DETERMINES THE NUMBER OF TIME INTERVALS THAT HAVE  
0152 ;ELAPSED FROM THE BEGINNING OF THE DATA RUN TO THE CURRENT  
0153 ;DATA SAMPLE. IT CALLS DIVIS, WHICH DIVIDES TWO BYTES BY TWO  
0154 ;BYTES.  
0160      LDA HLATCH ;READ HI BYTE OF COUNTER  
0170      STA QUOHI  
0180      LDA LCOUNT ;READ LO BYTE OF COUNTER  
0190      STA QUOLO  
0200      JER DIVIS ;DIVIDE COUNT BY 1000  
0210 ;SUBTRACT RESULT FROM 65 TO FIND  
0220 ;NUMBER OF TIME INTERVALS ELAPSED  
0230      SEC  
0240      LDA #$41 ;LO BYTE OF 65  
0250      SBC QUOLO ;$41-QUOLO  
0260      STA QUOLO  
0270      LDA #$00 ;HI BYTE OF 65  
0280      SBC QUOHI  
0290      STA QUOHI  
0300 ;NOW ADD TO THE CURRENT NUMBER  
0310 ;OF TIME INTERVALS ELAPSED  
0320      LDA LOTIME  
0330      CLC  
0340      ADC QUOLO  
0350      STA START1 ;START TIME OF CURRENT DATA SAMPLE  
0360      LDA MITIME  
0370      ADC QUOHI  
0380      STA START2  
0390      LDA #$00  
0400      ADC HITIME  
0410      STA START3  
0420      CLI  
0430      RTS  
0440      .EN
```

## 7. Module: Determine Instrument Number

>LOAD INSTRNM

```
>PP
0010 ;FIND INSTRUMENT NUMBER
0020 ;
0030 ; THIS SUBROUTINE WILL TAKE THE X AND Y DATA AND TRACK
0040 ;DATA FROM THE CURRENT DATA SAMPLE AND DEFINE THE
0050 ;INSTRUMENT NUMBER OF THE DATA SAMPLE.
0060 ; THE X DATA IS TWO BYTES AND IS CALLED XDIRH (HIGH
0070 ;ORDER BYTE) AND XDIRL (LOW ORDER BYTE). THE Y DATA
0080 ;IS YDIRL AND YDIRH. THE INSTRUMENTS ARE
0090 ;DEFINED BY THE X AND Y VALUES OF THE DIAGONAL CORNERS,
0100 ;CALLED UPPER AND LOWER X VALUES AND UPPER AND LOWER
0110 ;Y VALUES. THESE 4 VALUES ARE TWO BYTES EACH AND ARE
0120 ;STORED IN THE GRID.
0130 ;
0140         .BA $1B80
0160         .DS
0250 COMH    .DS 1
0260 COML    .DS 1
0270 GRIDH   .DS 1
0280 GRIDL   .DS 1
0290 RESH    .DS 1      ;DEFINED IN SUBTRACT SUBROUTINE
0300 RESL    .DS 1
0310 E       .BY 'E'
0320 GRID    .DE $1838
0330 INST    .DE $182B ;INST NUM THAT IS DETERMINED
0340 XDIRH   .DE $1823 ;X EYE DIRECTION OF
0350 XDIRL   .DE $1824 ;CURRENT DATA SAMPLE
0360 YDIRH   .DE $1825 ;Y EYE DIRECTION OF
0370 YDIRL   .DE $1826 ;CURRENT DATA SAMPLE
0371 TRACK   .DE $1827 ;TRACK/OUT-OF-TRACK STATUS
0380 NOINST  .BY 25    ;INST NUM OF NO INSTRUMENT
0390 BUFFER  .DE $3500
0430 ;
0530 ; FIND THE INSTRUMENT NUMBER
0540 ; DETERMINE IF IT IS OUT-OF-TRACK
0541 TXA
0542 PHA ;SAVE X REGISTER FOR BUFFER LOCATION
0550 LDX #00  ;INITIALIZE X
0560 LDA TRACK ;PUT TRACK BYTE IN A
0570 BNE FIND ;IF ZERO, SET INST NUM TO ZERO
0580 LDA #00
0590 STA INST
0600 JMP END
0610 FIND    LDA GRID,X ;GET HIGH BYTE OF
0620 STA GRIDH ;UPPER X VALUE
0630 INX
0640 LDA GRID,X ;GET LOW BYTE OF
0650 STA GRIDL ;UPPER X VALUE
0660 LDA XDIRH ;COMH=XDIRH
```

```

0070      STA COMH
0080      LDA XDIRL    ;COML=XDIRL
0090      STA COML
00A0      JSR SUBTRA  ;XH-X
00B0      BCC BACK1  ;NOT IN GRID IF RESULT NEG
00C0      ; GET TWO BYTES OF LOWER X VALUE
00D0      INX
00E0      LDA GRID,X  ;GET HIGH BYTE OF
00F0      STA GRIDH    ; LOWER X VALUE
0100      INX
0110      LDA GRID,X  ;GET LOW BYTE OF
0120      STA GRIDL    ;LOWER X VALUE
0130      ; ALREADY HAVE XDIRL IN COML AND XDIRH IN COMH
0140      JSR SUBTRA  ;XL-X
0150      BCC BACK2  ;NOT IN GRID IF RESULT POS
0160      ; GET TWO BYTES OF UPPER Y VALUE
0170      INX
0180      LDA GRID,X  ;HIGH BYTE OF
0190      STA GRIDH    ;UPPER Y VALUE
0200      INX
0210      LDA GRID,X  ;LOW BYTE OF
0220      STA GRIDL    ; UPPER Y VALUE
0230      LDA YDIRH    ;COMH=YDIRH
0240      STA COMH
0250      LDA YDIRL    ;COML=YDIRL
0260      STA COML
0270      JSR SUBTRA  ;YL-Y
0280      BCC BACK3  ;NOT IN GRID IF REULT NEG
0290      ; GET TWO BYTES OF LOWER Y VALUE
0300      INX
0310      LDA GRID,X  ;HIGH BYTE OF
0320      STA GRIDH    ; LOWER Y VALUE
0330      INX
0340      LDA GRID,X  ;LOW BYTE OF
0350      STA GRIDL    ; LOWER Y VALUE
0360      JSR SUBTRA  ;YL-Y
0370      BCC BACK4  ;NOT IN GRID IF RESULT POS
0380      ; HAVE FOUND THE INSTRUMENT
0390      INX
0400      LDA GRID,X
0410      STA INST
0420      JMP END
0430      BACK1      INX
0440      INX
0450      BACK2      INX
0460      INX
0470      BACK3      INX
0480      INX
0490      INX
0500      ; STILL NEED TO FIND INSTRUMENT NUMBER
0510      BACK4      INX ;LOOK AT INSTR NUM
0520      INX ;LOOK AT NEXT NUMBER
0530      LDA GRID,X
0540      CMP E
0550      BNE FIND    ;BACK TO BEGINNING IF NOT AN E
0560      LDA NOINST
0570      STA INST

```

```
1420 END      PLA
1421          TAX
1440          RTS
1450 ;
1460 ;SUBROUTINE SUBTRACT
1470 ; NEED THE FOLLOWING VARIABLES FOR THIS SUBROUTINE:
1480 ;COMH - HIGH BYTE OF DATA SAMPLE
1490 ;COML - LOW BYTE OF DATA SAMPLE
1500 ;GRIDH - HIGH BYTE OF GRID PARAMETER
1510 ;GRIDL - LOW BYTE OF GRID PARAMETER
1520 ;
1530 SUBTRA    SEC    ;SET CARRY
1540          LDA GRIDL
1550          SBC COML    ;SUBTRACT LOW ORDER BYTES
1560          STA RESL    ;STORE RESULT
1570          LDA GRIDH
1580          SBC COMH    ;SUBTRACT HIGH ORDER BYTES
1590          STA RESH    ;STORE RESULT
1600          RTS
1610          .EN
```

## S. Module: Compare Data Samples

LOAD COMPAR

```
PR  
0010 ; PROGRAM COMPARE  
0020 ; THIS PROGRAM WILL COMPARE THE LAST DATA SAMPLE TO THE  
0030 ; PRESENT DATA SAMPLE. IF THE INSTRUMENT NUMBER IS THE SAME, DO  
0040 ; NOTHING. IF THEY ARE DIFFERENT, SET THE STOP TIME OF THE  
0050 ; LAST DATA SAMPLE EQUAL TO THE START TIME OF THE CURRENT DATA  
0060 ; SAMPLE AND SEND THE LAST DATA SAMPLE TO THE BUFFER. THE  
0070 ; CURRENT DATA SAMPLE BECOMES THE LAST DATA SAMPLE.  
0080 ;  
0090 .BR $1C80  
0100 .DS  
0111 INSTNM .DE $1828 ;INST NUM INTO COMPARE  
0120 INST .DE $182F ;INST NUM TO CREATE TABLE  
0130 START1 .DE $1828 ;CURRENT DATA SAMPLE  
0140 START2 .DE $1829 ;  
0150 START3 .DE $182A ; TIMING INFORMATION  
0160 LASTIN .DE $1833 ;LAST DATA SAMPLE INST NUM  
0170 LSTRT1 .DE $1830 ;START TIME OF LAST  
0180 LSTRT2 .DE $1831 ; DATA SAMPLE  
0190 LSTRT3 .DE $1832 ;  
0200 TOTIM1 .DE $182C ;TOTAL TIME SPENT  
0210 TOTIM2 .DE $182D ; ON INSTNM  
0220 TOTIM3 .DE $182E  
0230 BUFFER .DE $3500  
0240 TEST .DE $6410 ;TEST BYTE USED IN MAIN MODULE  
0250 ;  
0260 ;COMPARE LAST DATA SAMPLE TO PRESENT DATA SAMPLE  
0270 ;  
0271 LDA #00  
0272 STA TEST  
0280 LDA INSTNM  
0290 CMP LASTIN ;IS INST=LASTIN?  
0300 BEQ END  
0310 LDA LASTIN ;IF NO, SEND INFO TO BUFFER  
0311 STA INST  
0320 STA BUFFER,X  
0330 INX  
0340 ;  
0350 ;SUBTRACT TO FIND TOTAL TIME AND SEND INFO TO BUFFER.  
0360 ;3-BYTE SUBTRACT: START-LSTRT1, TO GET TOTAL TIME ON  
0370 ;THAT INSTRUMENT.  
0380 ;  
0390 SEC ;SET CARRY  
0400 LDA START1  
0410 SBC LSTRT1 ;SUBTRACT LOW ORDER BYTES  
0420 STA TOTIM1  
0430 STA BUFFER,X ;STORE RESULT IN BUFFER  
0440 INX
```

0450 LDA START2  
0460 SBC LSTRT2 ;SUBTRACT MIDDLE BYTES  
0470 STA TOTIM2  
0480 STA BUFFER,X ;STORE RESULT IN BUFFER  
0490 INX  
0500 LDA START3  
0510 SBC LSTRT3 ;SUBTRACT HI ORDER BYTES  
0520 STA TOTIM3  
0530 STA BUFFER,X ;STORE RESULT IN BUFFER  
0540 INX  
0560 ;SET NEW LAST DATA SAMPLE  
0570 ;  
0580 LDA INSTNM ;LASTIN=INSTNM  
0590 STA LASTIN  
0600 LDA START1 ;LSTART1=START1  
0610 STA LSTART1  
0620 LDA START2 ;LSTART2=START2  
0630 STA LSTART2  
0640 LDA START3 ;LSTART3=START3  
0650 STA LSTART3  
0651 LDA #01  
0652 STA TEST  
0660 END RTS  
0670 .EN

## 7. Update-routine called by Create Table module

>LOAD UPDAT

```
>PR
0010      .BA $2000
0020      .OS
0040 ;THIS PROGRAM IS CALLED BY MASTER.
0050 ;IT WILL UPDATE THE PROPER COLUMNS IN THE TABLE.
0060 TABLE1    .DE $E000
0070 TABLE2    .DE $E100
0080 TABLE3    .DE $E200
0090 TABLE4    .DE $E300
0100 COLTT1    .BY 28      ;COLUMN FOR HI BYTE OF TIME
0110 COLTT2    .BY 29      ;COLUMN FOR MID BYTE OF TIME
0120 COLTT3    .BY 30      ;COLUMN FOR LO BYTE OF TIME
0130 COLFXL    .BY 31      ;COL FOR NUM OF FIXATIONS
0140 COLFXH    .BY 32
0150 TEMP      .DE $2160
0160 LAST      .DE $1837
0170 TOTIM1   .DE $182C
0180 TOTIM2   .DE $182D
0190 TOTIM3   .DE $182E
0200 UPDAT1   CLC
0210 TXA      ;TRANSFER X TO ACC
0220 ADC COLTT1
0230 TAX      ;TRANSFER ACC TO X
0240 CLC
0250 LDA TOTIM1
0260 ADC TABLE1,X
0270 STA TABLE1,X
0280 INX
0290 LDA TOTIM2
0300 ADC TABLE1,X
0310 STA TABLE1,X
0320 INX
0330 LDA TOTIM3
0340 ADC TABLE1,X
0350 STA TABLE1,X
0360 INX
0370 CLC
0380 LDA #01
0390 ADC TABLE1,X
0400 STA TABLE1,X
0410 INX
0420 LDA #00
0430 ADC TABLE1,X
0440 STA TABLE1,X
0450 LDX TEMP
0460 CLC
0470 TXA
0480 ADC LAST
0490 TAX
```

0500 INC TABLE1,X  
0510 RTS  
0520 UPDATE2 CLC  
0530 TXA ;TRANSFER X TO ACC  
0540 ADC COLTT1  
0550 TAX ;TRANSFER ACC TO X  
0560 CLC  
0570 LDA TOTIM1  
0580 ADC TABLE2,X  
0590 STA TABLE2,X  
0600 INX  
0610 LDA TOTIM2  
0620 ADC TABLE2,X  
0630 STA TABLE2,X  
0640 INX  
0650 LDA TOTIM3  
0660 ADC TABLE2,X  
0670 STA TABLE2,X  
0680 INX  
0690 CLC  
0700 LDA #01  
0710 ADC TABLE2,X  
0720 STA TABLE2,X  
0730 INX  
0740 LDA #00  
0750 ADC TABLE2,X  
0760 STA TABLE2,X  
0770 LDX TEMP  
0780 CLC  
0790 TXA  
0800 ADC LAST  
0810 TAX  
0820 INC TABLE2,X  
0830 RTS  
0840 UPDATE3 CLC  
0850 TXA ;TRANSFER X TO ACC  
0860 ADC COLTT1  
0870 TAX ;TRANSFER ACC TO X  
0880 CLC  
0890 LDA TOTIM1  
0900 ADC TABLE3,X  
0910 STA TABLE3,X  
0920 INX  
0930 LDA TOTIM2  
0940 ADC TABLE3,X  
0950 STA TABLE3,X  
0960 INX  
0970 LDA TOTIM3  
0980 ADC TABLE3,X  
0990 STA TABLE3,X  
1000 INX  
1010 CLC  
1020 LDA #01  
1030 ADC TABLE3,X  
1040 STA TABLE3,X

1050 INX  
1060 LDA #00  
1070 ADC TABLE3,X  
1080 STA TABLE3,X  
1090 LDX TEMP  
1100 CLC  
1110 TXA  
1120 ADC LAST  
1130 TAX  
1140 INC TABLE3,X  
1150 RTS  
1160 UPDAT4 CLC  
1170 TXA ;TRANSFER X TO ACC  
1180 ADC COLTT1  
1190 TAX ;TRANSFER ACC TO X  
1200 CLC  
1210 LDA TOTIM1  
1220 ADC TABLE4,X  
1230 STA TABLE4,X  
1240 INX  
1250 LDA TOTIM2  
1260 ADC TABLE4,X  
1270 STA TABLE4,X  
1280 INX  
1290 LDA TOTIM3  
1300 ADC TABLE4,X  
1310 STA TABLE4,X  
1320 INX  
1330 CLC  
1340 LDA #01  
1350 ADC TABLE4,X  
1360 STA TABLE4,X  
1370 INX  
1380 LDA #00  
1390 ADC TABLE4,X  
1400 STA TABLE4,X  
1410 LDX TEMP  
1420 CLC  
1430 TXA  
1440 ADC LAST  
1450 TAX  
1460 INC TABLE4,X  
1470 RTS  
.EN

3. Incr-routine called by Create Table module

```
>LOAD INCR  
>FF  
0010      .BA $2130  
0020      .DS  
0050 TEMP    .DE $2160  
0060 TEMSTO   .DS 1  
0090 INCR    DEC TEMSTO ;STORAGE FOR  
0091          LDA TEMSTO  
0100          BEQ DONE   ; INSTRUMENT NUMBER  
0110          CLC  
0120          LDA #22  
0130          ADC TEMP  ;TEMP IS THE  
0140          STA TEMP  ; PROPER ADDRESS  
0150          JMP INCR  ; IN THE TABLE  
0160 DONE    LDX TEMP  
0170          RTS  
0180          .EN
```

#### 9. Module: Create Table

>LOAD MASTER

```
>PP
0010 ;MASTER ALGORITHM. THIS ALGORITHM WILL PUT THE INFORMATION
0020 ;IN THE DATA SAMPLES INTO THE FINAL DATA TABLE. THE DATA
0030 ;COMING IN IS IN THE FORM OF:
0040 ; INSTNM = INSTRUMENT NUMBER
0050 ; TOTIM1,TOTIM2,TOTIM3 = NUMBER OF TIME INTERVALS SPENT
0060 ;ON THAT INSTRUMENT.
0070 ;
0080 .BA $2160
0090 .DS
0110 TEMP .DS 1
0120 ; DEFINE SPACE FOR TABLE
0130 TABLE1 .DE $6000 ;FOR GLICH,BLINK,DATA GONE
0140 ;AND INST 1-4
0150 TABLE2 .DE $6100 ;FOR INSTS 5-11
0160 TABLE3 .DE $6200 ;FOR INSTS 12-18
0170 TABLE4 .DE $6300 ;FOR INSTS 19-25
0180 UPDAT1 .DE $2005
0190 UPDAT2 .DE $2049
0200 UPDAT3 .DE $2080
0210 UPDAT4 .DE $20D1
0220 INCR .DE $2131
0230 TEMSTO .DE $2130
0240 COMMA .DE $833A
0250 INST .DE $182F ;INST NUM THROUGH MASTER
0260 ; THIS IS LASTIN FROM MODULE COMPARE
0270 TOTIM1 .DE $182C ;TOTAL NUMBER OF TIME INCREMENTS
0280 TOTIM2 .DE $182D ; ON INSTNM
0290 TOTIM3 .DE $182E
0291 LAST .DE $1837 ;LAST INST NUM THROUGH CREATE TABLE
0300 ;
0310 MASTER TXA
0320 PHA ;SAVE X REGISTER
0330 LDA TOTIM3
0340 BNE NOGLIT ;IF TOTIM3 NOT 0,CANNOT BE A GLITCH
0350 LDA TOTIM2
0360 BNE NOGLIT ;IF TOTIM2 NOT 0,CANNOT BE A GLITCH
0370 SEC
0380 LDA #$32
0390 SBC TOTIM1 ;IF TOTIM1>50 IT IS
0400 BCC TEST1 ;NOT A GLITCH
0410 LDX #00
0420 LDA #00
0430 STA TEMP
0440 JSR UPDAT1 ;UPDATE TABLE
0450 JMP END
0460 ;NOW SEE IF THE INST NUM IS OUT-OF-TRACK
0470 TEST1 LDA INST ;ALREADY KNOW TOTIM2+3 = 0.
0480 BNE FIND ;IF INSTNM NOT ZERO,IT IS AN INST
```

```

0490      SEC
0500      LDA #$B7
0510      SBC TOTIM1 ;183-TOTIM1
0520      BCC NOGLIT ;NO GLITCH IF TOTIM1>183
0530      LDX #$22 ;IF TOTIM1<183, IT IS A BLINK
0540      LDA #$22
0550      STA TEMP
0560      JSR UPDAT1
0570      JMP END
0580      NOGLIT
0590      LDA INST
0600      BNE FIND ;GO TO FIND IF IT IS AN INST
0610      LDX #$44 ;ELSE IT IS OUT-OF-TRACK
0620      LDA #$44
0630      STA TEMP
0640      JSR UPDAT1
0650      LDA INST
0660      STA LAST
0670      JMP END
0680      ; FIND THE CORRECT SPOT IN TABLE FOR THAT INST
0690      FIND
0700      SEC
0710      LDA #$04
0720      SBC INST ;IF INSTNM<5, THEN THAT INST
0730      BCC TEST2 ; IS IN TABLE1
0740      LDA #$66
0750      STA TEMSTO
0760      JSR INCR ;FIND CORRECT ROW IN TABLE
0770      JSR UPDAT1
0780      LDA INST
0790      STA LAST
0800      JMP END
0810      TEST2
0820      SEC
0830      LDA #$08
0840      SBC INST ;IF INSTNM<12, THEN THAT INST
0850      BCC TEST3 ; IS IN TABLE2
0860      LDA #$00
0870      STA TEMP
0880      SEC
0890      LDA INST
0900      SBC #$04
0910      STA TEMSTO
0920      JSR INCR
0930      JSR UPDAT2
0940      LDA INST
0950      STA LAST
0960      JMP END
0970      TEST3
0980      SEC
0990      LDA #$12
1000      SBC INST ;IF INSTNM<18, THAT INST IS
1010      BCC TEST4 ; IN TABLE3
1020      LDA #$00
1030      STA TEMP
1040      SEC
1050      LDA INST

```

1040 SBC #\$08  
1050 STA TEMSTO  
1060 JSR INCR  
1070 JSR UPDAT3  
1080 LDA INST  
1090 STA LAST  
1100 JMP END  
1110 TEST4  
1120 LDA #\$1A  
1130 SBC INST ; IF INSTNM<26, IT IS  
1140 BCC TEST5 ; IN TABLE4  
1150 LDA #\$00  
1160 STA TEMP  
1170 SEC  
1180 LDA INST  
1190 SBC #\$12  
1200 STA TEMSTO  
1210 JSR INCR  
1220 JSR UPDAT4  
1230 LDA INST  
1240 STA LAST  
1250 JMP END  
1260 TEST5 JSR COMM4 ; HAVE AN ERROR  
1270 END PLA  
1280 TAX RTS  
1290 .EN

## 10. Module: Main Subsystem

: LOAD MAIN

```
PR
0010      .BA $6400
0020      .DS
0040 DATA   .DE $6490 ;LOCATION OF SIMULATED OCULOMETER DATA
0050 INIT    .DE $19D8 ;INITIALIZATION MODULE
0060 STORE   .DE $1A70 ;STORE DATA FROM OCULOMETER
0070 TIMING  .DE $1B50
0080 INSTNM .DE $1BB8
0090 COMPAR  .DE $1C80
0100 MASTER  .DE $2161
0110 OUTCHR  .DE $8A47 ;OUTPUT A CHARACTER
0120 INCHR   .DE $8A1B ;INPUT A CHARACTER
0130 CRLF    .DE $8340 ;CARRIAGE RETURN AND LINE FEED
0140 START   .BY 'HIT S TO START MISSION'
0150 COUNT1  .BY 23
0160 S       .BY '0'
0170 COUNT2  .DS 1
0180 LO      .DS 1
0190 HI      .DS 1
0191 TEST   .DS 1      ;TEST TO SEE IF MODULE MASTER IS CALLED
0200 D       .BY 'D'
0210 ;PRINT OUT PROMPT TO START PROGRAM
0220 MAIN    JSR CRLF
0230          LDX #00
0240 LOOP1   LDA START,X
0250          JSR OUTCHR
0260          INX
0270          CPX COUNT1
0280          BNE LOOP1
0290          JSR INCHR
0300          CMP S
0310          BNE MAIN
0311          LDX #00
0320 ;DATA MISSION HAS STARTED
0330          JSR INIT   ;TIMER IS RUNNING
0340          LDY #00   ;DON'T USE Y IN ANY OTHER MODULES
0350 ;THE FOLLOWING IS A TIMING LOOP TO SIMULATE
0360 ;OCULOMETER DATA SAMPLES
0370 NEXT    LDA #$40   ;LO BYTE OF 832
0380          STA LO
0390          LDA #$03   ;HI BYTE OF 832
0400          STA HI
0410 LOOP2   SEC ;THIS LOOP IS APPROX
0420          LDA LO   ; APPROX 20 MSEC LONG
0430          SBC #01
0440          STA LO
0450          NOP
0460          LDA HI
```

0470 SBC #00  
0480 STA HI  
0490 BNE LOOP2  
0500 ;NOW STORE A DATA SAMPLE  
0510 JER STORE  
0520 JER TIMING  
0530 JER INSTMN  
0540 JER COMPAR  
0541 LDA TEST  
0542 BEQ OVER  
0550 JER MASTER  
0560 OVER LDA DATA,Y  
0570 CMP D ;ARE AT END OF DATA?  
0580 BNE NEXT ;IF NOT, TIME NEXT SAMPLE  
0591 SEI  
05A0 RTC  
.EN

The following modules are used by the Print Results module.

## 11. Module: Three

### LOAD THREE

```
FF
0010 :THREE
0020 ; THIS IS A GROUPING OF THREE ROUTINES USED BY
0030 ;THE PRINT RESULTS ROUTINE.
0040     .BA $2000
0050     .03
0070 VALUE     .DE $0000
0080 ;ROTATE RIGHT
0090 ; THIS ROUTINE ROTATES Y (INDEX REGISTER) BYTES TO
0100 ;THE RIGHT. THE X REGISTER IS THE LOCATION OF THE
0110 ;LS BYTE OF THE DATA TO BE ROTATED.
0120 ROTATL    CLC ;CLEAR CARRY
0130 ROTL      PCL VALUE,X ;ROTATE THE BYTE LEFT
0140           DEY ;DECREMENT BYTE COUNTER
0150           BNE MORRTL ;NOT ZERO, CONTINUE ROTATE
0160           RTS ;DONE, RETURN
0170 MORRTL    INX ;ADVANCE MEMORY POINTER
0180           JMP ROTL ;CONTINUE TO ROTATE LEFT
0190 ;
0200 ;ROTATE RIGHT
0210 ; THE SAME PARAMETERS ARE USED AS IN ROTATE LEFT.
0220 ROTATR    CLC ;CLEAR CARRY
0230 ROTR      PCL VALUE,X ;ROTATE THE BYTE RIGHT
0240           DEY ;DECREMENT BYTE COUNTER
0250           BNE MORRTR ;NOT ZERO, CONTINUE ROTATE
0260           RTS ;DONE, RETURN
0270 MORRTR    DEX ;DECREMENT MEMORY POINTER
0280           JMP ROTR ;CONTINUE ROTATE RIGHT
0290 ;
0300 ;COMPLEMENT
0310 ; THIS PERFORMS THE TWO'S COMPLEMENT OF Y NUMBER
0320 ;OF BYTES. THE X REGISTER CONTAINS THE LS BYTE OF THE
0330 ;VALUE TO BE COMPLEMENTED
0340 COMPLM    SEC ;SET CARRY
0350 COMPL    LDH #FF    ;LOAD $FF FOR COMPLEMENT OP
0360           EOR VALUE,X ;COMPLEMENT BYTE
0370           ADC #00    ;IF CARRY=1, TWO'S COMPLEMENT
0380           STA VALUE,X ;STORE BYTE IN MEMORY
0390           INX ;ADVANCE MEMORY POINTER
0400           DEY ;DECREMENT BYTE COUNTER
0410           BNE COMPL ;NOT ZERO, CONTINUE
0420           RTS ;RETURN TO CALLING PROGRAM
0430 .EN
```

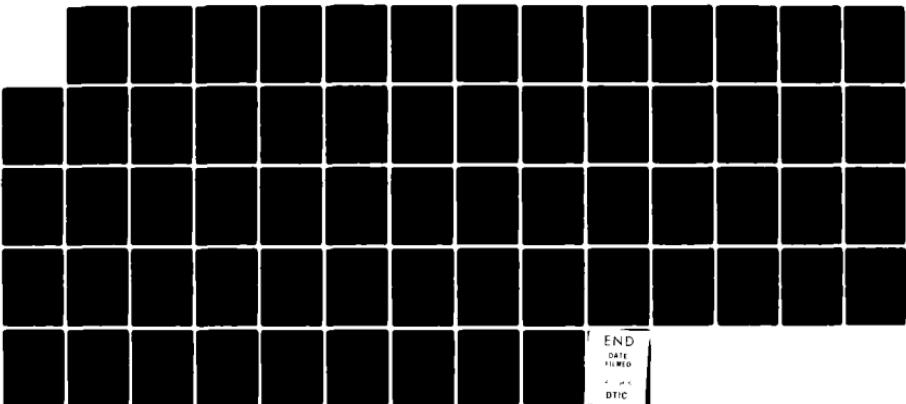
AD-A124 700 DEVELOPMENT OF AN OCULOMETER DATA COLLECTION SUBSYSTEM  
(U) AIR FORCE INST OF TECH WRIGHT-PATTERSON AFB OH  
SCHOOL OF ENGINEERING N L WOOD DEC 82

2/2

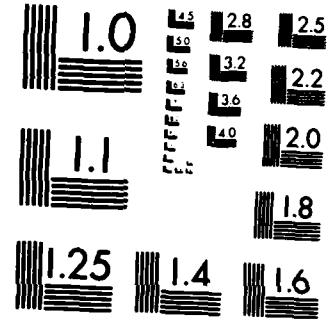
UNCLASSIFIED AFIT/GE/EE/82D-72

F/G 9/2

NL



END  
DATE  
FILED  
PAC  
DTIC



MICROCOPY RESOLUTION TEST CHART  
NATIONAL BUREAU OF STANDARDS-1963-A

## 12. Module: Seven

### LOAD SEVEN

PP

0010 .BH \$2030

0030 .D1

0040 ;SUBROUTINE SEVEN

0050 ; THESE ARE SEVEN ROUTINES NEEDED FOR THE FLOATING

0060 ;POINT ROUTINES.

0070 ;

0080 FMPNT .DE \$0000 ;FROM POINTER

0090 TOPNT .DE \$0002 ;TO POINTER

0100 SIGNS .DE \$0006 ;SIGN INDICATOR

0110 FPLOW .DE \$0008 ;FPACC LS BYTE

0120 FPNW .DE \$0009 ;FPACC NEXT SIGNIFICANT BYTE

0130 FPMOW .DE \$000A ;FPACC MOST SIGNIFICANT BYTE

0140 MCAND0 .DE \$000C ;MULTIPLICATION WORK AREA

0150 FOPLESW .DE \$0010 ;FPOP LEAST SIGNIFICANT BYTE

0160 FOPNEW .DE \$0011 ;FPOP NEXT SIGNIFICANT BYTE

0170 FOPMEW .DE \$0012 ;FPOP MOST SIGNIFICANT BYTE

0180 FOPEXP .DE \$0013 ;FPOP EXPONENT

0190 WORK0 .DE \$0014 ;WORK AREA

0200 IOLSW .DE \$001F ;I/O WORK AREA LS BYTE

0210 IOSTR .DE \$0023 ;I/O STORAGE

0220 IOSTR3 .DE \$0026 ;I/O STORAGE

0230 IOEXP0 .DE \$0027 ;I/O EXPONENT STORAGE

0240 ROTATL .DE \$2000 ;ROTATE LEFT

0241 COMPLM .DE \$2018 ;COMPLEMENT

0250 FPMULT .DE \$2110 ;FLOATING POINT MULTIPLY

0260 ;

0270 ;CLEAR A SECTION OF MEMORY

0280 CLRMEM LDA #00 ;SET UP ZERO VALUE

0290 TAY ;INITIALIZE INDEX POINTER

0300 CLRM1 STA (TOPNT),Y ;CLEAR MEMORY LOCATION

0310 INY ;ADVANCE INDEX POINTER

0320 DEX ;DECREMENT COUNTER

0330 BNE CLRM1 ;NOT ZERO,CONTINUE CLEARING

0340 RTS ;RETURN

0350 ;

0360 ;TRANSFER A SECTION OF MEMORY

0370 MOVIND LDY #00 ;INITIALIZE INDEX POINTER

0380 MOVIN1 LDA (FMPNT),Y ;FETCH BYTE TO TRANSFER

0390 STA (TOPNT),Y ;STORE BYTE IN NEW LOCATION

0400 INY ;ADVANCE INDEX POINTER

0410 DEX ;DECREMENT BYTE COUNTER

0420 BNE MOVIN1 ;NOT ZERO, CONTINUE

0430 RTS ;RETURN

0440 ;

0450 ;MULTIPLE PRECISION ADDITION

0460 ADDER CLC ;CLEAR CARRY FLAG

0470 ADDR1 LDA (TOPNT),Y ;FETCH BYTE FROM ONE VALUE

0480 ADC (FMPNT),Y ;ADD BYTE OF OTHER VALUE

```

0430 STA (TOPNT),Y      ;STORE RESULT
0500 INY ;INCREMENT INDEX POINTER
0510 DEX ;DECREMENT COUNTER
0520 BNE ADDR1 ;NOT ZERO, CONTINUE ADDITION
0530 RTS ;RETURN
0540 ;
0830 ;MULTIPLY FPACC BY TEN
0840 FPX10 LDA #$04      ;LOAD FPOP WITH A VALUE OF TEN
0850 STA FOPEXP      ;BY SETTING THE EXPONENT TO FOUR
0860 LDA #$50      ;AND THE MANTISSA TO $50,$00,$00
0870 STA FOPMSW
0880 LDA #$00
0890 STA FOPNSW
0900 STA FOPLSW
0910 JSR FPMULT      ;MULTIPLY FPACC BY FPOP
0920 DEC IDEXPD      ;DECREMENT DECIMAL EXPONENT
0930 RTS ;RETURN TO TEST FOR COMPLETION
0940 ;
0950 ;MULTIPLY FPACC BY 0.1
0960 FPD10 LDA #$FD      ;PLACE 0.1 IN FPOP BY
0970 STA FOPEXP      ;SETTING FPOP EXPONENT TO -3
0980 LDA #$66      ;AND LOADING MANTISSA
0990 STA FOPMSW      ;WITH $66,$66,$67
1000 STA FOPNSW
1010 LDA #$67
1020 STA FOPLSW
1030 JSR FPMULT      ;MULTIPLY FPACC BY FPOP
1040 INC IDEXPD      ;INCREMENT DECIMAL EXPONENT
1050 RTS ;RETURN
1060 ;
1070 DECBIN LDA #$00      ;CLEAR MS BYTE+1 OF RESULT
1080 STA IOCTR3      ;SET POINTER TO I/O WORK AREA
1090 LDX #IOLSW
1100 STX TOPNT
1110 LDW #IOSTR
1120 STX FMPNT
1130 LDW #104
1140 JSR MOVIND
1150 LDW #IOSTR
1160 LDY #$04
1170 JSR ROTATL
1180 LDW #IOSTR
1190 LDY #$04
1200 JSR ROTATL
1210 LDW #IOLSW
1220 STX FMPNT
1230 LDW #IOSTR
1240 STX TOPNT
1250 LDW #104
1260 JSR ADDER
1270 LDW #IOSTR
1280 LDY #$04
1290 JMP ROTATL
1300 .EN

```

## 1 Module: Floating Point Multiply

>LOAD FPMUL

>PR		
0010 :FLOATING POINT MULTIPLY		
0020	.BA \$2110	
0030	.DS	
0050 FMPNT	.DE \$0000	:FPDM POINTER
0060 TOPNT	.DE \$0002	:TO POINTER
0070 CNTR	.DE \$0004	:COUNTER STORAGE
0080 SIGNS	.DE \$0006	:SIGNS INDICATOR
0090 FPLSWE	.DE \$0007	:FPACC EXTENSION
0100 FPLOSW	.DE \$0008	:FPACC LEAST SIGNIFICANT BYTE
0110 FPNNEW	.DE \$0009	:FPACC NEXT SIGNIFICANT BYTE
0120 FPMWSW	.DE \$000A	:FPACC MOST SIGNIFICANT BYTE
0130 FPACCE	.DE \$000B	:FPACC EXPONENT
0140 MCAND0	.DE \$000C	:MULTIPLICATION WORK AREA
0150 MCAND1	.DE \$000D	:MULTIPLICATION WORK AREA
0160 FOPLSW	.DE \$0010	:FPOP LEAST SIGNIFICANT BYTE
0170 FOPMSW	.DE \$0012	:FPOP MOST SIGNIFICANT BYTE
0180 FOPEXP	.DE \$0013	:FPOP EXPONENT
0190 WORK0	.DE \$0014	:WORK AREA
0200 WORK1	.DE \$0015	:WORK AREA
0210 WORK3	.DE \$0017	:WORK AREA
0220 WORK6	.DE \$001A	:WORK AREA
0230 PAGE0	.DE \$0000	
0250 ROTATR	.DE \$2000	:ROTATE RIGHT
0360 ADDER	.DE \$2045	:ADDITION ROUTINE
0370 MOVIND	.DE \$203A	:ROUTINE TO MOVE BYTES
0280 COMPLM	.DE \$2018	:COMPLEMENT BYTES
0290 CLRMEM	.DE \$2030	:CLEAR AN AREA OF MEMORY
0300 FPNORM	.DE \$21FA	:FLOATING POINT NORMALIZATION
0310 FPMULT	JSR CNSIGN	:SET UP AND CHECK SIGN OF MANTISSAS
0320	LDA FOPEXP	:GET FPOP EXPONENT
0330	CLC :ADD FPACC EXPONENT	
0340	ADC FPACCE	:TO FPOP EXPONENT
0350	STA FPACCE	:SAVE IN FPACC EXPONENT
0360	INC FPACCE	:ADD ONE FOR ALGORITHM COMPENSATION
0370 SETMCT	LDA #\\$17	:SET BIT COUNTER
0380	STA CNTR	:STORE BIT COUNTER
0390 MULTIP	LDX #FPMWSW	:SET POINTER TO FPACC MS BYTE
0400	LDY #\\$3	:SET PRECISION COUNTER
0410	JSR ROTATR	:ROTATE FPACC RIGHT
0420	BCC NADOPP	:CARRY=0, DON'T ADD PARTIAL PRODUCT
0430 ADOPP	LDX #MCAND1	:POINTER TO LS BYTE OF MULTIPLICAND
0440	STX FMPNT	:STORE POINTER
0450	LDX #WORK1	:POINTER TO LS BYTE OF PARTIAL PRODUCT
0460	STX TOPNT	:STORE POINTER
0470	LDX #\\$6	:SET PRECISION COUNTER
0480	JSR ADDER	:ADD MULTIPLICAND TO PARTIAL PRODUCT

0490	MADOPP	LDX #WORK6	;SET POINTER TO MS BYTE OF PARTIAL
0500	; PRODUCT		
0510		LDY #\$6	;SET PRECISION COUNTER
0520		JSR ROTATR	;ROTATE PARTIAL PRODUCT RIGHT
0530		DEC CNTR	;DECREMENT BIT COUNTER
0540		BNE MULTIP	;NOT ZERO, CONTINUE MULTIPLYING
0550		LDX #WORK6	;ELSE, SET POINTER TO PARTIAL PRODUCT
0560		LDY #\$6	;SET PRECISION COUNTER
0570		JER ROTATR	;MAKE ROOM FOR POSSIBLE ROUNDING
0580		LDX WORK3	;SET POINTER TO 24TH BIT OF
0590	; PARTIAL PRODUCT		
0600		LDA PAGE0,X	;FETCH LS BYTE-1 OF RESULT
0610		ROL A	;ROTATE 24TH BIT TO SIGN
0620		BPL PPEXFR	;IF 24TH BIT=0, BRANCH AHEAD
0630		CLC ;CLEAR CARRY FOR ADDITION	
0640		LDY #\$3	;SET PRECISION COUNTER
0650		LDA #\$40	;ADD ONE TO 23RD BIT OF PARTAIL-PRODUCT
0660		ADC PAGE0,X	;TO ROUND OFF RESULT
0670		STA WORK3	;STORE SUM IN MEMORY
0680	CROUND	LDA #\$0	;CLEAR A WITHOUT CHANGING CARRY
0690		ADC PAGE0,X	;ADD WITH CARRY TO PROPAGATE
0700		STA PAGE0,X	;STORE IN PARTIAL-PRODUCT
0710		INX ;INCREMENT INDEX POINTER	
0720		DEY ;INCREMENT COUNTER	
0730		BNE CROUND	;NOT ZERO, ADD NEXT BYTE
0740	PPEXFR	LDX #FPLSW	;SET POINTER TO FPACC LSW-1
0750		STX TOPNT	;STORE IN TOPNT
0760		LDX #WORK3	;SET POINTER TO PARTIAL PRODUCT
0770	; LSW-1		
0780		STX FMPNT	;STORE IN FMPNT
0790		LDX #\$4	;SET PRECISION COUNTER
0800	EXMLDV	JSR MOVIND	;MOVE PARTIAL PRODUCT TO FPACC
0810		JCR FPNORM	;NORMALIZE RESULT
0820		LDA SIGNS	;GET SIGN STORAGE
0830		BNE MULTEX	;IF NOT ZERO, SIGN IS POSITIVE
0840		LDX #FPLSW	;ELSE, SET POINTER TO FPACC LS BYTE
0850		LDY #\$3	;SET PRECISION COUNTER
0860		JCR COMPLM	;COMPLEMENT RESULT
0870	MULTEX	RTS ;EXIT FPMUL	
0880	CKSIGN	LDA #\$0	;SET PAGE PORTION OF POINTERS
0890		STA TOPNT+1	;STORE IN TOPNT
0900		STA FMPNT+1	;STORE IN FMPNT
0910		LDA #WORK0	;SET POINTER TO WORK AREA
0920		STA TOPNT	;STORE IN TOPNT
0930		LDX #\$8	;SET PRECISION COUNTER
0940		JCR CLRMEM	;CLEAR WORK AREA
0950		LDA #MCANDO	;SET POINTER TO MULTIPLICAND STORAGE
0960		STA TOPNT	;STORE IN TOPNT
0970		LDX #\$4	;SET PRECISION COUNTER
0980		JCR CLRMEM	;CLEAR MULTIPLICAND STORAGE
0990		LDA #\$1	;INITIALIZE SIGN INDICATOR
1000		STA SIGNS	;BY STORING ONE IN SIGNS
1010		LDA FPMSW	;FETCH FPACC MS BYTE
1020		BPL DPCGNT	;POSITIVE, CHECK FPDP

1030	NEGFP	DEC SIGNS	; IF NEGATIVE, DECREMENT SIGNS
1040		LDX #FPLSW	; SET POINTER TO FPACC LS BYTE
1050		LDY #\$3	; SET PRECISION COUNTER
1060		JSR COMPLM	; MAKE POSITIVE FOR MULTIPLICATION
1070	OPSGNT	LDA FOPMSW	; IS FPOP NEGATIVE?
1080		BMI NEGOP	; YES, COMPLEMENT VALUE
1090		RTS ;ELSE, RETURN	
1100	NEGOP	DEC SIGNS	;DECREMENT SIGNS INDICATOR
1110		LDX #FOPLSW	;SET POINTER TO FPOP LS BYTE
1120		LDY #\$3	;SET PRECISION COUNTER
1130		JMP COMPLM	;COMPLEMENT FPOP AND RETURN
1140		.EN	

Module: Convert to Floating Point

>LOAD CONVE

```

>FIR
0010 :CONVERT
0020 ; THIS CONVERTS A THREE BYTE NUMBER TO FLOATING POINT
0030 ;FORMAT. THE NUMBER TO BE CONVERTED IS IN NUM1, 2, AND 3
0040 ;WITH NUM1 THE LOB. THE RESULT IS IN THE FPLSW, FPNSW, FPACCE.
0050 .BH $21E0
0060 .03
0070 TSIGN .DE $0005 ;SIGN INDICATOR
0080 FPLSW .DE $0008 ;FPACC LEAST SIG BYTE
0090 FPNSW .DE $0009 ;FPACC NEXT SIG BYTE
0100 FPMRW .DE $000A ;FPACC MOST SIG BYTE
0110 FPACCE .DE $000B ;FPACC EXPONENT
0120 NUM1 .DS 1 ;LO BYTE OF NUMBER TO BE CONVERTED
0130 NUM2 .DS 1 ;MIDDLE BYTE OF NUMBER TO BE CONVERTED
0140 NUM3 .DS 1 ;HIGH BYTE OF NUMBER TO BE CONVERTED
0150 PAGE0 .DE $0000
0160 FPLSWE .DE $0007
0170 COMPLM .DE $2018 ;COMPLEMENT SUBROUTINE
0180 ROTATL .DE $2000 ;ROTATE LEFT SUBROUTINE
0190 ROTATR .DE $2000 ;ROTATE RIGHT SUBROUTINE
0200 ;
0210 CONVER LDA NUM1 ;LOAD THE NUMBER TO
0220 STA FPLSW ; BE CONVERTED INTO
0230 LDA NUM2 ; THE FLOATING POINT
0240 STA FPNSW ; ACCUMULATOR
0250 LDA NUM3
0260 STA FPMRW
0270 LDA #23
0280 STA FPACCE
0290 ;
0300 FPNORM LDX #TSIGN ;SET POINTER TO SIGN REGISTER
0310 LDA FPMRW ;FETCH FPACC MS BYTE
0320 BMI ACCMIN ;IF NEGATIVE, BRANCH
0330 LDY #$00 ;IF POS, CLEAR SIGN REGISTER
0340 TYA
0350 STA PAGE0,X ;BY STOPING ZERO
0360 JMP ACZERT ;THEN TEST IF FPACC=0
0370 ACCMIN STA PAGE0,X ;SET SGN INDICATOR IF MINUS
0380 LDY #04 ;SET PRECISION COUNTER
0390 LDX #FPLSWE ;SET POINTER TO FPACC LS BYTE-1
0400 JSR COMPLM ;TWO'S COMPLEMENT FPACC
0410 ACZERT LDX #FPMRW ;SET POINTER TO FPACC MS BYTE
0420 LDY #04 ;SET PRECISION COUNTER
0430 LOOK0 LDA PAGE0,X ;SEE IF FPACC=0
0440 BNE ACNONZ ;BRANCH IF NONZERO
0450 DEX ;DECREMENT INDEX POINTER
0460 DEY ;DECPEMENT BYTE COUNTER
0470 BNE LOOK0 ;IF COUNTER NOT ZERO, CONTINUE

```

0480 STY FPACCE ;FPACC=0, CLEAR EXPONENT TOO  
1190 NORMEX PTS ;EXIT NORMALIZATION ROUTINE  
1200 ACNONZ LDX #FPLSWE ;SET POINTER TO FPACC LS BYTE-1  
0510 LDY #\$04 ;SET PRECISION COUNTER  
0520 JSR ROTATL ;ROTATE FPACC LEFT  
0530 LDA PAGE0,X ;SEE IF ONE IN MS BIT  
0540 BMI ACCSET ;IF MINUS, PROPERLY JUSTIFIED  
0550 DEC FPACCE ;IF POSITIVE, DECREMENT FPACC EXPONENT  
0560 JMP ACNONZ ;CONTINUE ROTATING  
0570 ACCSET LDX #PPMSW ;SET POINTER TO FPACC MS BYTE  
0580 LDY #103 ;SET PRECISION COUNTER  
0590 JSR ROTATR ;COMPENSATING ROTATE RIGHT FPACC  
0600 LDA TSIGN ;IS ORIGINAL SIGN POSITIVE  
0610 BEQ NORMEX ;YES, SIMPLY RETURN  
0620 LDY #103 ;WITH POINTER AT LS BYTE  
0630 ;SET PRECISION COUNTER  
0640 JMP COMPLM ;RESTORE FPACC TO NEG AND RETURN  
0650 .EN

: Module: Floating Point Divide

>LOAD FPDIV

```

>PR
0010 ;FLOATING POINT DIVIDE
0020 ; DIVIDENT=FPACC
0030 ; DIVISOR=FPPOP
0040 ; RESULT=FPACC
0050 .BA $2260
0060 .03
0080 OUTCHR .DE $8A47 ;OUTPUT A CHARACTER
0090 FMPNT .DE $0000 ;FROM POINTER
0100 TOPNT .DE $0002 ;TO POINTER
0110 CNTR .DE $0004 ;COUNTER STORAGE
0120 SIGNS .DE $0006 ;SIGN INDICATOR
0130 FPLSWE .DE $0007 ;FPACC EXTENSION
0140 FPLSW .DE $0008 ;FPACC LEAST SIG BYTE
0150 FPNSW .DE $0009 ;FPACC NEXT SIG BYTE
0160 FPMNW .DE $000A ;FPACC MOST SIG BYTE
0170 FPACCE .DE $000B ;FPACC EXPONENT
0180 FOLSWE .DE $000F ;FPPOP EXTENSION
0190 FOPLSW .DE $0010 ;FPPOP LEAST SIG BYTE
0200 FOPNSW .DE $0011 ;FPPOP NEXT SIG BYTE
0210 FOPMSW .DE $0012 ;FPPOP MOST SIG BYTE
0220 FOPEXP .DE $0013 ;FPPOP EXPONENT
0230 WORK0 .DE $0014 ;WORK AREA
0240 WORK1 .DE $0015
0250 WORK2 .DE $0016
0260 WORK3 .DE $0017
0270 WORK4 .DE $0018
0280 WORK5 .DE $0019
0290 WORK6 .DE $001A
0300 CKSIGN .DE $218F ;CHECK SIGN
0310 MOVIND .DE $203A ;MOVE BYTES
0320 ROTL .DE $2001 ;ROTATE LEFT
0330 ROTATL .DE $2000 ;ROTATE LEFT
0340 ROTATR .DE $200C ;ROTATE RIGHT
0341 COMPLM .DE $2018 ;TWO'S COMPLEMENT BYTES
0350 FPNORM .DE $21FA ;FLOATING POINT NORMALIZATION
0360 ;
0370 FPDIV JSR CKSIGN ;CLEAR WORK AREA AND SET SIGNS
0380 LDA FPMNW ;CHECK FOR DIVIDE BY ZERO
0390 BEQ DERROR ;DIVISOR=0, DIVIDE BY ZERO ERROR
0400 SUBEXP LDA FOPEXP ;GET DIVIDEND EXPONENT
0410 SEC ;SET CARRY FOR SUBTRACTION
0420 SBC FPACCE ;SUBTRACT DIVISOR EXPONENT
0430 STA FPACCE ;STORE RESULT IN FPACC EXPONENT
0440 INC FPACCE ;COMPENSATE FOR DIVIDE ALGORITHM
0450 SETDCT LDA #17 ;SET BIT COUNTER STORAGE
0460 STA CNTR ; TO 17 HEXADECIMAL
0470 DIVIDE JSR SETSUB ;SUBTRACT DIVISOR FROM DIVIDEND

```

0480	BMI NOGO	; IF RESULT MINUS, ROTATE ZERO
0490	; IN QUOTIENT	
0500	LDX #FOPLSW	; SET POINTER TO DIVIDEND
0510	STX TOPNT	; STORE IN TOPNT
0520	LDX #WORK0	; SET POINTER TO QUOTIENT
0530	STX FMPNT	; STORE IN FMPNT
0540	LDX #\$03	; SET PRECISION COUNTER
0550	JEP MOVIND	; MOVE QUOTIENT TO DIVIDEND
0560	SEC	; SET CARRY FOR POSITIVE RESULTS
0570	JMP QUOPROT	; ROTATE INTO QUOTIENT
0580	DEPPOR	LDA #1BF ;SET ASCII FOR ?
0590		JEP OUTCHR
0600		RTS
0610	NOGO	CLC ;NEGATIVE RESULT, CLEAR CARRY
0620	QUOPROT	LDX #WORK4 ;SET POINTER TO QUOTIENT LS BYTE
0630		LDY #13 ;SET PRECISION COUNT
0640		JEP ROTL ;ROTATE CARRY INTO LSB OF QUOTIENT
0650		LDX #FOPLSW ;SET POINTER TO DIVIDEND LS BYTE
0660		LDY #13 ;SET PRECISION COUNTER
0670		JEP ROTATE ;ROTATE DIVIDEND LEFT
0680		DEC CNTR ;DECREMENT BIT COUNTER
0690		BNE DIVIDE ;IF NOT ZERO, CONTINUE
0700		JEP SETSUB ;DO ONE MORE FOR ROUNDING
0710		BMI DVEXIT ;IF MINUS, NO ROUNDING
0720		LDA #1 ;IF 0 OR +, ADD 1 TO 23RD BIT
0730		CLC ;CLEAR CARRY FOR ADDITION
0740		ADC WORK4 ;ROUND LS BYTE OF QUOTIENT
0750		STA WORK4 ;RESTORE BYTE IN WORK AREA
0760		LDA #0 ;CLEAR A, NOT THE CARRY
0770		ADC WORK5 ;ADD CARRY TO 2ND BYTE OF QUOTIENT
0780		STA WORK5 ;STORE RESULT
0790		LDA #0 ;CLEAR A, NOT THE CARRY
0800		ADC WORK6 ;ADD CARRY TO MS BYTE
0810	; OF QUOTIENT	
0820		STA WORK6 ;STORE RESULT
0830		BPL DVEXIT ;IF MSB=0, EXIT
0840		LDX #WORK6 ;ELSE PREPARE TO ROTATE RIGHT
0850		LDY #13 ;SET PRECISION COUNTER
0860		JEP ROTATE ;CLEAR SIGN BIT COUNTER
0870		INC FPACCE ;COMPENSATE EXP FOR ROTATE
0880	DVEXIT	LDX #FFPLSW ;SET POINTER TO FPACC
0890		STX TOPNT ;STORE IN TOPNT
0900		LDX #WORK3 ;SET POINTER TO QUOTIENT
0910		STX FMPNT ;STORE IN FMPNT
0920		LDX #14 ;SET PRECISION COUNTER
0930		JMP EXMLDY ;MOVE QUOTIENT TO FPACC
0940	SETSUB	LDX #WORK0 ;SET POINTER TO WORK AREA
0950		STX TOPNT ;STORE IN TOPNT
0960		LDX #FFPLSW ;SET POINTER TO FPACC
0970		STX FMPNT ;STORE IN FMPNT
0980		LDX #13 ;SET PRECISION COUNTER
0990		JEP MOVIND ;MOVE FPACC TO WORK AREA
1000		LDX #WORK0 ;PREPARE FOR SUBTRACTION
10		STX TOPNT ;STORE POINTER TO DIVISOR
1020		LDX #FOPLSW ;SET POINTER TO FPOP LS BYTE-1

1030 STX FMPNT ;STORE POINTER TO DIVIDEND  
1040 LDY #\$0 ;INITIALIZE INDEX POINTER  
1050 LDX #3 ;SET PRECISION COUNTER  
1060 SEC ;SET CARRY FOR SUBTRACTION  
1070 SUBR1 LDA (FMPNT),Y ;FETCH FPOP BYTE (DIVIDEND)  
1080 SBC (TOPNT),Y ;SUBTRACT FPACC BYTE (DIVISOR)  
1090 STA (TOPNT),Y ;STORE IN PLACE OF DIVISOR  
1100INY ;ADVANCE INDEX POINTER  
1110DEX ;DECREMENT PRECISION COUNTER  
1120BNE SUBR1 ;NOT ZERO, CONTINUE SUBTR  
1130LDA WORK2 ;SET SIGN BIT RESULT IN N FLAG  
1140RTS ;RETURN WITH FLAG CONDITIONED  
1150 EXMLDV JSR MOVIND ;MOVE PARTIAL PRODUCT TO FPACC  
1160JSR FPNORM ;NORMALIZE RESULT  
1170LDA SIGNS ;GET SIGN STORAGE  
1180BNE MULTEX ;IF NOT ZERO, SIGN IS POSITIVE  
1190LDX #FPSEN ;ELSE, SET POINTER TO FPACC LS BYTE  
1200LDY #3 ;SET PRECISION COUNTER  
1210JSR COMPLM ;COMPLEMENT RESULT  
1220 MULTEX RTS ;EXIT FFDIV  
.EN

## Module: Floating Point Output

LOAD FPOUT

SPP

```

0010 :FLOATING POINT OUTPUT ROUTINE
0020 ; THIS ROUTINE PRINTS OUT A FLOATING POINT BINARY NUMBER
0030 ;IN DECIMAL.
0040      .BH $2340
0050      .D1
0070 IOEXPD  .DE $0027 ;I/O EXPONENT STORAGE
0080 FPMEM   .DE $000A ;FPACC MOST SIGNIFICANT BYTE
0090 FFLSM   .DE $0008 ;FPACC LEAST SIGNIFICANT BYTE
0100 FMPNT   .DE $0000 ;FROM POINTER
0110 FPACCE  .DE $000B ;FPACC EXPONENT
0120 CNTR    .DE $0004 ;COUNTER STORAGE
0130 TOPNT   .DE $0002 ;TO POINTER
0140 IOSTR   .DE $0023 ;I/O STORAGE
0150 IOSTR1  .DE $0024 ;I/O STORAGE
0160 IOSTR2  .DE $0025 ;I/O STORAGE
0170 IOSTR3  .DE $0026 ;I/O STORAGE
0180 COMPLM  .DE $2018 ;COMPLEMENT ROUTINE
0190 ROTATEL .DE $2000 ;ROTATE LEFT
0200 ROTATR  .DE $2000 ;ROTATE RIGHT
0210 FPX10   .DE $2051 ;MULTIPLY FPACC BY 10
0220 FPD10   .DE $206A ;MULTIPLY FPACC BY 0.1
0230 MOVIND  .DE $203A ;TRANSFER A SECTION OF MEMORY
0240 DECBIN  .DE $2083
0250 OUTCHR  .DE $8A47 ;OUTPUT A CHARACTER
0260 FPOUT   LDA #$0
0270      STA IOEXPD ;CLEAR DECIMAL EXPONENT STORAGE
0280      LDA FPMEM ;IS VALUE TO BE OUTPUT NEG?
0290      BMI OUTNEG ;YES, MAKE POS AND OUTPUT '-'
0300      LDA #$AB ;ELSE, SET ASCII CODE FOR '+'
0310      BNE AHEAD1 ;GO DISPLAY + SIGN
0320 OUTNEG  LDW #FFLOW ;SET POINTER TO LS BYTE OF FPACC
0330      LDY #13 ;SET PRECISION COUNTER
0340      JSR COMPLM ;MAKE FPACC POSITIVE
0350      LDA #$AD ;SET ASCII CODE FOR '-'
0360 AHEAD1  JSR OUTCHR ;OUTPUT SIGN OF RESULT
0370      LDA #$B0 ;SET UP ASCII ZERO
0380      JSR OUTCHR ;OUTPUT ZERO TO DISPLAY
0390      LDA #$AE ;SET UP ASCII DECIMAL POINT
0400      JSR OUTCHR ;OUTPUT DECIMAL POINT
0410      DEC FPACCE ;DECREMENT FPACC EXPONENT
0420 DECEXT  BPL DECEXD ;IF COMPENSATED, EXP>=0
0430      LDA #$4 ;EXPONENT NEG, ADD FOUR TO FPACCE
0440      CLC ;CLEAR CARRY FOR ADDITION
0450      ADC FPACCE ;ADD FOUR TO FPACC EXPONENT
0460      BPL DECOUT ;IF EXP>=0, OUTPUT MANTISSA
0470      JSR FPX10 ;ELSE MULTIPLY MANISSA BY TEN
0480 DECPER  LDA FPACCE ;GET EXPONENT

```

0490	JMP DECEXD	JMP DECEXT	;REPEAT TEST FOR $x \geq 0$
0500	DECExD	JSR FPDI0	;MULTIPLY FPACC BY 0.1
0510		JMP DECREP	;CHECK STATUS OF FPACC EXPONENT
0520	DECOUT	LDX #IOSTR	;SET UP FOR MOVE OPERATION
0530		STX TOPNT	;SET TOPNT TO WORKING REGISTER
0540		LDX #FFPLSM	;SET POINTER TO FPACC LS BYTE
0550		STX FMPNT	;STORE IN FMPNT
0560		LDX #13	;SET PRECISION COUNTER
0570		JSR MOVIND	;MOVE FPACC TO OUTPUT REGISTERS
0580		LDA #\$0	
0590		STA IO3TP3	;CLEAR OUTPUT REGISTER MS BYTE+1
0600		LDX #IOSTR	;SET POINTER TO OUTPUT LS BY
0610		LDY #13	;SET PRECISION COUNTER
0620		JSR ROTATE	;ROTATE TO COMPENSATE FOR SIGN BIT
0630		JSR DECBIN	;OUTPUT REGISTER X 10, OVERFLOW
0640	FIN MS BYTE +1		
0650	CMPEN	INC FPACCE	;INCREMENT FPACC EXPONENT
0660		BEO OUTDIG	;OUTPUT A DIGIT WHEN COMPENSATION DONE
0670		LDX #IOSTRP3	;ELSE ROTATE RIGHT TO COMPENSATE
0680		LDY #14	;FOR ANY REMAINDER IN BINARY EXP
0690		JSR ROTATP	;PERFORM ROTATE RIGHT OPERATION
0700		JMP COMPEN	;PREPARE LOOP UNTIL EXP=0
0710	OUTDIG	LDA #37	;SET DIGIT COUNTER TO SEVEN
0720		STA CNTR	;FOR OUTPUT OPERATION
0730		LDA IO3TP3	;FETCH BCD, SEE IF FIRST DIGIT = 0
0740		BEO ZERODG	;YES, CHECK REMAINDER OF DIGITS
0750	OUTDGS	LDA IOSTR3	;GET BCD FROM OUTPUT REGISTER
0760		ORA #\$80	;FORM ASCII CODE FOR NUMBERS
0770		JSR OUTCHR	;AND OUTPUT DIGIT
0780	DECRDG	DEC CNTR	;DECREMENT DIGIT COUNTER
0790		BEO EXPOUT	;=0, DONE OUTPUT EXPONENT
0800		JSR DECBIN	;ELSE GET NEXT DIGIT
0810		JMP OUTDGS	;FORM ASCII AND OUTPUT
0820	ZERODG	DEC IOEXPD	;DECREMENT EXP FOR SKIPPING DISPLAY
0830		LDA IOSTR2	;CHECK IF MANTISSA = 0
0840		BNE DECRDG	;IF NOT ZERO, CONTINUE OUTPUT
0850		LDA IO3TR1	
0860		BNE DECPDG	
0870		LDA IOSTR	
0880		BNE DECPDG	
0890		LDA #\$0	;MANTISSA ZERO, CLEAR EXPONENT
0900		STA IOEXPD	
0910		BEO DECPDG	;BEFORE FINISHING DISPLAY
0920	EXPOUT	LDA #\$05	;SET UP ASCII CODE FOR E
0930		JSR OUTCHR	;DISPLAY E FOR EXPONENT
0940		LDA IOEXPD	;TEST IF NEGATIVE
0950		BMI EXOUTN	;YES, DISPLAY '-' AND NEGATE
0960		LDA #\$AB	;NO, SET ASCII CODE FOR '+'
0970		JMP AHEAD2	;DISPLAY EXPONENT VALUE
0980	EXOUTN	EOR #\$FF	;TWO'S COMPLEMENT EXPONENT
0990		STA IOEXPD	;TO MAKE NEG VALUE POS
1000		INC IOEXPD	;FOR OUTPUT OF EXPONENT VALUE
1010		LDA #1AD	;SET ASCII CODE FOR '-'
1020	AHEAD2	JSR OUTCHR	;OUTPUT SIGN OF EXPONENT
1030		LDY #\$0	;CLEAR TEN'S COUNTER

1040	LDA IDEXPD	;FETCH EXPONENT
1050	SUB12	SEC ;SET CARRY FOR SUBTRACTION
1060		SBC #10A ;SUBTRACT TEN'S FROM EXPONENT
1070		BMI TOMUCH ;IF MINUS,READY FOR OUTPUT
1080		STA IDEXPD ;STORE POSITIVE RESULT
1090		INY ;ADVANCE TEN'S COUNTER
1100		JMP SUB12 ;CONTINUE SUBTRACTION
1110	TOMUCH	TYA ;PUT MS DIGIT INTO A
1120		OPA #\\$B0 ;FORM ASCII CODE
1130		JCR OUTCHP ;OUTPUT TEN'S DIGIT TO DISPLAY
1140		LDA IDEXPD ;FETCH UNIT'S DIGIT
1150		OPA #\\$B0 ;FORM ASCII CODE
1160		JCR OUTCHP ;OUTPUT DIGIT
1170		RTS
1180		.EN

. Module: Convert, Divide and Output Floating Point.

LOAD PRINT

SPP

0110	.BR \$2430
0120	.DS
0130	:THIS MODULE WILL CONVERT A THREE BYTE DIVISOR AND DIVIDEND
0140	:TO FLOATING POINT FORMAT. DO A FLOATING POINT DIVIDE, AND
0150	:OUTPUT THE RESULT IN DECIMAL FLOATING POINT FORMAT.
0160	DIVIS1 .DS 1 :LO BYTE OF DIVISOR
0170	DIVIS2 .DS 1 :MIDDLE BYTE OF DIVISOR
0180	DIVIS3 .DS 1 :HIGH BYTE OF DIVISOR
0190	DVDND1 .DS 1 :LO BYTE OF DIVIDEND
0200	DVDND2 .DS 1 :MIDDLE BYTE OF DIVIDEND
0210	DVDND3 .DS 1 :HIGH BYTE OF DIVIDEND
0220	CONVE .DE \$21E3 :CONVERT TO FLOATING POINT
0230	FPDIV .DE \$2260 :FLOATING POINT DIVISION
0240	FPOUT .DE \$2340 :OUTPUT FP IN DECIMAL
0250	FPLSW .DE \$0008 :FFPAC LEAST SIGNIFICANT BYTE
0260	FPMNW .DE \$0009 :FFPHLQ NEXT SIGNIFICANT BYTE
0270	FPMSW .DE \$000A :FFPAC MOST SIGNIFICANT BYTE
0280	FPAcce .DE \$000B :FFPAC EXPONENT
0290	FOPLSW .DE \$0010 :FFPOP LEAST SIGNIFICANT BYTE
0300	FOPNWM .DE \$0011 :FFPOP NEXT SIGNIFICANT BYTE
0310	FOPMSW .DE \$0012 :FFPOP MOST SIGNIFICANT BYTE
0320	FOPEXP .DE \$0013 :FFPOP EXPONENT
0330	NUM1 .DE \$21E0
0340	NUM2 .DE \$21E1
0350	NUM3 .DE \$21E2
0360	:
0370	PRINT TXA
0380	PHA
0390	TYA
0400	PHA
0410	LDA DVDND1 :PUT DVDND1, 2, AND 3
0420	STA NUM1 : INTO NUM1, 2, AND 3
0430	LDA DVDND2
0440	STA NUM2
0450	LDA DVDND3
0460	STA NUM3
0470	JSR CONVE :CONVERT DIVIDEND TO FP
0480	LDA FPLSW :PUT FP RESULT INTO
0490	STA FOPLSW : FPPOP
0500	LDA FPNWM
0510	STA FOPNWM
0520	LDA FPMNW
0530	STA FOPMSW
0540	LDA FPAcce
0550	STA FOPEXP
0560	LDA DIVIS1 :PUT DIVIS1, 2, AND 3
0570	STA NUM1 : INTO NUM1, 2 AND 3

0480	LDA DIV12
30	STA NUM2
0500	LDA DIV13
0510	STA NUM3
0520	JSR CONVE     ;CONVERT DIVISOR TO FP
0530	JSR FPDIV     ;FP DIVISION
0540	JSR FPDOUT   ;PRINT OUT RESULT OF DIVISION
0550	PLA
0560	TAY
0570	PLA
0580	TAX
0590	RTS
0600	.EN

Module: Total Mission Parameters.

>LOAD TOVAL

>PP

0010	.BA \$2700	
0020	.00	
0040 TOTFX1	.DE 1	:LO BYTE OF TOTAL MISSION FIXATIONS
0050 TOTFX2	.DE 1	:MID BYTE OF TOTAL MISSION FIXATIONS
0060 TOTFX3	.DE 1	:HI BYTE OF TOTAL MISSION FIXATIONS
0070 TODWL1	.DE 1	:LO BYTE OF TOTAL MISSION DWELL TIME
0080 TODWL2	.DE 1	:MID BYTE OF TOTAL MISSION DWELL TIME
0090 TODWL3	.DE 1	:HI BYTE OF TOTAL MISSION DWELL TIME
0100 TABLE1	.DE \$6000	:LOCATION OF
0110 TABLE2	.DE \$6100	: FINAL DATA
0120 TABLE3	.DE \$6200	: TABLE
0130 TABLE4	.DE \$6300	
0140 :		
0150 :		ADD UP THE TOTAL NUMBER OF FIXATIONS AND THE TOTAL
0160 :		MISSION DWELL TIME FOR THE DATA MISSION. THIS IS
0170 :		FINISHED FOR INSTS 0-25. NOT FOR BLINK, GLITCH AND
0180 :		DATA GONE.
0190 TOVAL	LDA #00	:INITIALIZE TOTAL FIXATIONS
0200	STA TOTFX1	:AND TOTAL DWELL TIME
0210	STA TOTFX2	
0220	STA TOTFX3	
0230	STA TODWL1	
0240	STA TODWL2	
0250	STA TODWL3	
0260	LDX #182	:LOCATION OF THE LOW BYTE OF THE
0270	:	: DWELL TIME FOR INST 1
0280 LOOP1	LDA TABLE1,X	:ADD THE DWELL TIME
0290	ADC TODWL1	: FOR AN INSTRUMENT
0300	ADC TODWL1	: TO THE TOTAL
0310	STA TODWL1	: MISSION DWELL TIME
0320	INX	
0330	LDA TABLE1,X	
0340	ADC TODWL2	
0350	STA TODWL2	
0360	INX	
0370	LDA TABLE1,X	
0380	ADC TODWL3	
0390	STA TODWL3	
0400	INX	
0410	CLC	
0420	LDA TABLE1,X	:ADD THE NUMBER OF
0430	ADC TOTFX1	: FIXATIONS FOR AN
0440	STA TOTFX1	: INSTRUMENT TO THE
0450	INX	: TOTAL MISSION DWELL
0460	LDA TABLE1,X	: TIME
0470	ADC TOTFX2	
0480	STA TOTFX2	

```

0490      LDA #00
0500      ADC TOTFX3
0510      STA TOTFX3
0520      CPX #$EC    ;ARE AT THE END OF TABLE 1?
0530      BEQ TAB2    ;IF SO, GO TO TABLE2
0540      CLC
0550      TXA ;TRANSFER X TO ACC
0560      ADC #$1E    ;GO TO NEXT INST IN TABLE 1
0570      TAX
0580      JMP LOOP1
0590      TAB2    ;LOOK AT FIRST INST IN TABLE 2
0600      LOOP2   ;ADD THE DWELL TIME
0610      CLC ; FOR AN INSTRUMENT
0620      ADC TODML1 ; TO THE TOTAL
0630      STA TODML1 ; MISSION DWELL TIME
0640      INX
0650      LDA TABLE2,X
0660      ADC TODML2
0670      STA TODML2
0680      INX
0690      LDA TABLE2,X
0700      ADC TODML3
0710      STA TODML3
0720      INX
0730      CLC
0740      LDA TABLE2,X    ;ADD THE NUMBER OF
0750      ADC TOTFX1 ; FIXATIONS FOR AN
0760      STA TOTFX1 ; INSTRUMENT TO THE
0770      INX ; TOTAL MISSION DWELL
0780      LDA TABLE2,X    ; TIME
0790      ADC TOTFX2
0800      STA TOTFX2
0810      LDA #00
0820      ADC TOTFX3
0830      STA TOTFX3
0840      CPX #$EC    ;ARE AT THE END OF TABLE 2?
0850      BEQ TAB3    ;IF SO, GO TO TABLE2
0860      CLC
0870      TXA ;TRANSFER X TO ACC
0880      ADC #$1E    ;GO TO NEXT INST IN TABLE 2
0890      TAX
0900      JMP LOOP2
0910      TAB3    ;LOOK AT FIRST INST IN TABLE 2
0920      LOOP3   ;ADD THE DWELL TIME
0930      CLC ; FOR AN INSTRUMENT
0940      ADC TODML1 ; TO THE TOTAL
0950      STA TODML1 ; MISSION DWELL TIME
0960      INX
0970      LDA TABLE3,X
0980      ADC TODML2
0990      STA TODML2
1000      INX
1010      LDA TABLE3,X
1020      ADC TODML3
1030      STA TODML3

```

```

1040      INX
1050      CLC
1060      LDA TABLE3+X      ;ADD THE NUMBER OF
1070      ADC TOTFX1      ; FIXATIONS FOR AN
1080      STA TOTFX1      ; INSTRUMENT TO THE
1090      INX    ; TOTAL MISSION DWELL
1100      LDA TABLE3+X      ; TIME
1110      ADC TOTFX2
1120      STA TOTFX2
1130      LDA #00
1140      ADC TOTFX3
1150      STA TOTFX3
1160      CPX #REC      ;ARE AT THE END OF TABLE 3?
1170      BEQ TAB4      ;IF SO, GO TO TABLE4
1180      CLC
1190      TXA    ;TRANSFER X TO ACC
1200      ADC #$1E      ;GO TO NEXT INST IN TABLE 3
1210      TAX
1220      JMP LOOP3
1230      TAB4      ;LOOK AT FIRST INST IN TABLE 4
1240      LOOP4      ;ADD THE DWELL TIME
1250      CLC    ; FOR AN INSTRUMENT
1260      ADC TODML1      ; TO THE TOTAL
1270      STA TODML1      ; MISSION DWELL TIME
1280      INX
1290      LDA TABLE4+X
1300      ADC TODML2
1310      STA TODML2
1320      INX
1330      LDA TABLE4+X
1340      ADC TODML3
1350      STA TODML3
1360      INX
1370      CLC
1380      LDA TABLE4+X      ;ADD THE NUMBER OF
1390      ADC TOTFX1      ; FIXATIONS FOR AN
1400      STA TOTFX1      ; INSTRUMENT TO THE
1410      INX    ; TOTAL MISSION DWELL
1420      LDA TABLE4+X      ; TIME
1430      ADC TOTFX2
1440      STA TOTFX2
1450      LDA #00
1460      ADC TOTFX3
1470      STA TOTFX3
1480      CPX #REC      ;ARE AT THE END OF TABLE 4?
1490      BEQ DONE      ;IF SO, DONE
1500      CLC
1510      TXA    ;TRANSFER X TO ACC
1520      ADC #$1E      ;GO TO NEXT INST IN TABLE 4
1530      TAX
1540      JMP LOOP4
1550      DONE      RTS
1560      .EN

```

. Module: First Table Header.

>LOAD OUTPT

FP  
0010 .BA \$2850  
0020 .05  
0030 ; THIS ROUTINE PRINTS OUT THE FIRST TABLE  
0040 ; COLUMN HEADERS, THE TOTAL NUMBER OF FIXATIONS  
0050 ; IN THE DATA MISSION AND THE TOTAL MISSION DWELL TIME.  
0060 SPACE .BY 1  
0070 HEAD1 .BY 'INST'  
0080 HEAD2 .BY 'TOTAL NUMBER'  
0090 HEAD3 .BY 'TOTAL DWELL'  
0100 HEAD4 .BY 'MEAN DWELL'  
0110 HEAD5 .BY 'PROPORTION OF'  
0120 HEAD6 .BY 'PROPORTION OF'  
0130 HEAD7 .BY 'NUM'  
0140 HEAD8 .BY 'OF FIXATIONS'  
0150 HEAD9 .BY 'TIME'  
0160 HEAD10 .BY 'TIME'  
0170 HEAD11 .BY 'TOTAL TIME'  
0180 HEAD12 .BY 'TOTAL FIXATION'  
0190 UNDER .BY 1  
0200 NUM1 .DE \$21E0 ;LO BYTE OF NUMBER TO BE CONVERTED TO FP  
0210 NUM2 .DE \$21E1 ;MIDDLE BYTE OF NUMBER TO BE CONVERTED  
0220 NUM3 .DE \$21E2 ;HI BYTE OF NUMBER TO BE CONVERTED  
0230 TOTFX1 .DE \$2700 ;LO BYTE OF TOTAL MISSION FIXATIONS  
0240 TOTFX2 .DE \$2701 ;MIDDLE BYTE OF TOTAL MISSION FIXATIONS  
0250 TOTFX3 .DE \$2702 ;HI BYTE OF TOTAL MISSION FIXATIONS  
0260 TODWLL1 .DE \$2703 ;LO BYTE OF TOTAL MISSION DWELL TIME  
0270 TODWLL2 .DE \$2704 ;MIDDLE BYTE OF TOTAL MISSION DWELL TIME  
0280 TODWLL3 .DE \$2705 ;HI BYTE OF TOTAL MISSION DWELL TIME  
0290 TOTFX .BY 'TOTAL NUMBER OF FIXATIONS IN THE DATA MISSION= '  
0300 TOTDWL .BY 'TOTAL DWELL TIME IN THE DATA MISSION= '  
0310 CPLF .DE \$B34D ;CARRIAGE RETURN AND LINE FEED  
0311 CONVE .DE \$21E3 ;CONVERT TO FP  
0312 FPOUT .DE \$2340 ;PRINT FP RESULT  
0320 OUTCHR .DE \$8A47 ;OUTPUT A CHARACTER  
0330 OUTPT1 LDY #47  
0340 LDX \$00  
0350 JER CPLF ;GO TO NEXT LINE  
0360 LOOPA LDA TOTFX,X ;PRINT OUT THE  
0370 JER OUTCHR ; TOTAL NUMBER OF  
0380 INC ; FIXATIONS IN THE  
0390 DEY ;DATA MISSION  
0400 BNE LOOPA  
0410 LDA SPACE  
0420 JER OUTCHR  
0430 LDA TOTFX1  
0440 STA NUM1  
0450 LDA TOTFX2

0460	STA NUM2	
70	LDA TOTFX3	
0480	STA NUM3	
0490	JSR CONVE	:CONVERT FIXATIONS TO FP
0500	JSR FFOUT	:PRINT FLOATING POINT RESULT
0510	JSR CPLF	:GO TO NEXT LINE
0520	LDY #38	
0530	LDX #00	
0540	LOOPB LDA TOTDWL,X	:PRINT OUT THE
0550	JSR OUTCHP	: TOTAL MISSION DWELL
0560	INX TIME	
0570	DEY	
0580	BNE LOOPB	
0590	LDA SPACE	
0600	JSR OUTCHP	
0610	LDA TOTDWL1	
0620	STA NUM1	
0630	LDA TOTDWL2	
0640	STA NUM2	
0650	LDA TOTDWL3	
0660	STA NUM3	
0670	JSR CONVE	:CONVERT DWELL TIME TO FP
0680	JSR FFOUT	:OUTPUT THE RESULT
0690	JSR CPLF	
0700	JSR CPLF	:SKIP A LINE
0710	;	
0720	SPRINT OUT HEADER	
730	JSR CPLF	
0740	LDX #00	
0750	LDY #4	IX IS THE POSITION IN HEAD1-12
0760	JSR HOUT	HY IS THE NUM OF CHARS OR SPACES TO PRINT
0770	LDY #02	:PRINT OUT PORTION OF HEADER
0780	JSR PRSP	:PRINT OUT 2 SPACES
0790	LDY #12	
0800	JSR HOUT	:PRINT 12 CHARS OF HEADER
0810	LDY #4	
0820	JSR PRSP	:PRINT OUT 4 SPACES
0830	LDY #11	
0840	JSR HOUT	:PRINT 11 CHARS OF HEADER
0850	LDY #4	
0860	JSR PRSP	:PRINT 4 SPACES
0870	LDY #10	
0880	JSR HOUT	:PRINT 10 CHARS OF HEADER
0890	LDY #4	
0900	JSR PRSP	:PRINT 4 SPACES
0910	LDY #13	
0920	JSR HOUT	:PRINT 13 CHARS OF HEADER
0930	LDY #2	
0940	JSR PRSP	:PRINT 2 SPACES
0950	LDY #13	
0960	JSR HOUT	:PRINT 13 CHARS OF HEADER
0970	JSR CPLF	:GO TO NEXT LINE
0980	LDY #1	
0990	JSR PRSP	:PRINT 1 SPACE
1000	LDY #3	

1010	JEP HOUT	PRINT 3 CHARS OF HEADER
20	LDY #2	
1030	JEP PRSP	PRINT 2 SPACES
1040	LDY #12	
1050	JEP HOUT	PRINT 3 CHARS OF HEADER
1060	LDY #7	
1070	JEP PRSP	PRINT 7 SPACES
1080	LDY #4	
1090	JEP HOUT	PRINT 4 CHARS OF HEADER
1100	LDY #11	
1110	JEP PRSP	PRINT 11 SPACES
1120	LDY #4	
1130	JEP HOUT	PRINT 4 CHARS OF HEADER
1140	LDY #8	
1150	JEP PRSP	PRINT 8 SPACES
1160	LDY #10	
1170	JEP HOUT	PRINT 10 CHARS OF HEADER
1180	LDY #3	
1190	JEP PRSP	PRINT 3 SPACES
1200	LDY #14	
1210	JEP HOUT	PRINT 14 CHARS OF HEADER
1220	JEP CRLF	
1240	LDY #79	
1250	LOOP1 LDA UNDER	UNDERLINE THE HEADER
1260	JEP OUTCHR	
1270	DEY	
1280	BNE LOOP1	
1290	JEP CRLF	TO NEXT LINE
1300	JEP CRLF	TO NEXT LINE
1301	RTS	
1310	SUBROUTINE TO PRINT Y CHARS FROM HEAD	
1320	HOUT LDA HEAD1+X	
1330	JEP OUTCHR	
1340	INX	
1350	DEY	
1360	BNE HOUT	
1370	RTS	
1380	SUBROUTINE TO PRINT OUT Y SPACES	
1390	PRSP LDA SPACE	
1400	JEP OUTCHR	
1410	DEY	
1420	BNE PRSP	
1430	RTS	
1440	.EN	

. Module: Output First Table.

>LOAD OUTTB

>PP

0010	.BR \$2B40
0020	.D1
0030	CPLF .DE \$8340 :CARRIAGE RETURN AND LINE FEED
0040	OUTCHR .DE \$8H47 :OUTPUT A CHARACTER
0050	NUMBER .BY 01 02 03 04 05 06 07 08 09 10 11 12 13 14
0060	NUMBI .BY 15 16 17 18 19 20 21 22 23 24 25
0070	SPACE .BY
0080	GLITCH .BY 'GLIT'
0090	BLINK .BY 'BLINK'
0100	DATAGN .BY 'DAGN'
0110	RESTB .DE \$2BF2
0120	LOTAB .DE \$0020
0130	HITAB .DE \$002E
0140	:
0150	: PRINT OUT THE INFO FOR EACH INST, GLITCH, BLINK,
0160	:AND DATA GONE ROW BY ROW
0170	OUTTR LDY #4
0180	LDX #00
0190	LOOP2 LDA GLITCH,X
0200	JSR OUTCHR
0210	INX
0220	DEY
0230	BNE LOOP2
0240	LDA SPACE :PRINT 1 SPACE
0250	JSR OUTCHR
0260	LDX #00
0270	LDA #00
0280	STA LOTAB
0290	LDA #\$E0
0300	STA HITAB :POINT TO TABLE!
0310	JSP RESTB :PRINT OUT ROW FOR BLINK
0320	JSP CRLF :GO TO NEXT LINE
0330	LDX #00
0340	LDY #4
0350	LOOP3 LDA BLINK,X
0360	JSR OUTCHR :PRINT HEADER FOR BLINK
0370	INX
0380	DEY
0390	BNE LOOP3
0400	LDA SPACE
0410	JSR OUTCHR :PRINT 1 SPACE
0420	LDX #422
0430	LDA #00
0440	STA LOTAB
0450	LDA #\$E0
0460	STA HITAB
0470	JSP RESTB :PRINT OUT ROW FOR BLINK

0480	JSR CPLF	:GO TO NEXT LINE
0490	LDX #00	
0500	LDY #4	
0510	LOOP4 LDA DATA4N.X	
0520	JSP OUTCHR	:PRINT HEADER FOR DATA GONE
0530	INX	
0540	DEY	
0550	BNE LOOP4	
0560	LDA SPACE	
0570	JSP OUTCHR	
0580	LDX #\$44	
0590	LDA #00	
0600	STA LOTAB	
0610	LDA #\$E0	
0620	STA HITAB	:POINT AT TABLE1
0630	JSP RESTB	:PRINT ROW FOR DATA GONE
0640	JSR CPLF	:GO TO NEXT LINE
0650	LDX #\$E6	
0660	LDY #00	
0670	BACK1 JSR FORMAT	:PRINT HEADER FOR THE INST
0680	LDA #00	
0690	STA LOTAB	
0700	LDA #\$E0	
0710	STA HITAB	:POINT AT TABLE1
0720	JSP RESTB	:PRINT OUT ROW FOR THAT INST
0730	JSP CPLF	
0740	CPX #\$00	
0750	BED NEXT2	:GO TO TABLE2 IF DONE WITH TABLE1
0760	TXA	
0770	CLC	
0780	ADC #\$22	:GO TO NEXT INST IN TABLE1
0790	TAX	
0800	JMP BACK1	
0810	NEXT2 LDX #00	
0820	BACK2 JSR FORMAT	:PRINT HEADER FOR THE INST
0830	LDA #00	
0840	STA LOTAB	
0850	LDA #\$E1	
0860	STA HITAB	:POINT TO TABLE2
0870	JSP RESTB	:PRINT OUT ROW FOR AN INSTRUMENT
0880	JSP CPLF	
0890	CPX #\$00	
0900	BED NEXT3	:IF DONE WITH TABLE2 GO TO TABLE3
0910	TXA	
0920	CLC	
0930	ADC #\$22	:GO TO NEXT INST IN TABLE2
0940	TAX	
0950	JMP BACK2	
0960	NEXT3 LDX #00	
0970	BACK3 JSR FORMAT	:PRINT HEADER FOR THE INST
0980	LDA #00	
0990	STA LOTAB	
1000	LDA #\$E2	
1010	STA HITAB	
1020	JSP RESTB	:PRINT OUT ROW FOR AN INST

```

1030      JSR CPLF
1040      CPX #$CC
1050      BEQ NEXT4    ;GO TO TABLE4 IF DONE WITH TABLE3
1060      TXA
1070      CLC
1080      ADC #$22    ;GO TO NEXT INST IN TABLE3
1090      TAX
1100      JMP BACK3
1110      NEXT4
1120      BACK4    ;PRINT OUT HEADER FOR THE INST
1130      LDX #00
1140      STA LOTAB
1150      LDA #$E3
1160      STA HITAB
1170      JSR FEETB   ;PRINT OUT ROW FOR AN INST
1180      JSR CPLF
1190      CPX #$CC
1200      BEQ DONE    ;DONE WITH ALL FOUR TABLES
1210      TXA
1220      CLC
1230      ADC #$22    ;GO TO NEXT INST IN TABLE4
1240      TAX
1250      JMP BACK4
1260      DONE      RTS
1270      ; ROUTINE TO PRINT THE HEADER FOR EACH INST NUMBER
1280      FORMAT     LDA SPACE
1290                  JSR DUTCHR
1300                  LDA NUMBER,Y
1310                  JSR DUTCHR
1320                  INY
1330                  LDA NUMBER,Y
1340                  JSR DUTCHR
1350                  INY
1360                  LDA NUMBER,Y
1370                  JSR DUTCHR
1380                  INY
1390                  JSR DUTCHR
1400                  RTS
1410      .EN

```

. Module: Output Row of First Table - called by Output First Table module.

>LOAD RESTB

>PP

0010	.BA	828E0	
0020	.DS		
0030	NUM1	.DE	821E0 :NUMBER TO BE CONVERTED TO FLOATING PT
0040	NUM2	.DE	821E1
0050	NUM3	.DE	821E2
0060	PRINT	.DE	82436 :ROUTINE TO CONVERT TO FP, DIVIDE, AND PRINT
0070	DIVIS1	.DE	82430 :LO BYTE OF DIVISOR
0080	DIVIS2	.DE	82431 :MID BYTE OF DIVISOR
0090	DIVIS3	.DE	82432 :HI BYTE OF DIVISOR
0100	DVDND1	.DE	82433 :LO BYTE OF DIVIDEND
0110	DVDND2	.DE	82434 :MID BYTE OF DIVIDEND
0120	DVDND3	.DE	82435 :HI BYTE OF DIVIDEND
0130	TOTFX1	.DE	82700 :LO BYTE OF TOTAL MISSION FIXATIONS
0140	TOTFX2	.DE	82701 :MID BYTE OF TOTAL MISSION FIXATIONS
0150	TOTFX3	.DE	82702 :HI BYTE OF TOTAL MISSION FIXATIONS
0160	TODWLL1	.DE	82703 :LO BYTE OF TOTAL MISSION DWELL TIME
0170	TODWLL2	.DE	82704 :MID BYTE OF TOTAL MISSION DWELL TIME
0180	TODWLL3	.DE	82705 :HI BYTE OF TOTAL MISSION DWELL TIME
0190	CONVE	.DE	821E3 :CONVERT TO FP
0200	FPOUT	.DE	82340 :PRINT FP RESULT
0210	SPACE	.BY	"
0220	OUTCHR	.DE	88A47 :OUTPUT A CHARACTER
0230	ZEROFX	.DS	1 :SET TO ZERO IF FIXATIONS=0
0240	ZERODL	.DS	1 :SET TO ZERO IF DWELL TIME=0
0250	ZEROUT	.BY	+0.0000000E+00/
0251	COUNT	.DS	1
0260	:		
0270	:ROUTINE TO PRINT OUT RESULTS FOR THE INSTS IN TABLEI		
0280	RESTB	TYA	
0290		PHA :SAVE Y ON STACK	
0300		LDA #FFF	
0310		STA ZEROFX	
0320		STA ZERODL	
0330		TXA :PRINT OUT THE TOTAL	
0340		CLC :NUMBER OF FIXATIONS	
0350		ADC #31	
0360		TAY	
0370		LDA (\$2D),Y :LO BYTE OF FIXATIONS	
0380		STA NUM1	
0390		INY	
0400		LDA (\$2D),Y	
0410		STA NUM2	
0420		LDA #00	
0430		STA NUM3	
0440		LDA NUM1 :SEE IF NUMBER OF	
0450		BNE NOZER1 : FIXATIONS = 0	
0460		LDA NUM2	
0470		BNE NOZER1	

```

0480      LDA NUM3
1490      BNE NOZER1
0500      LDA #00      ;IF SO, PRINT OUT ZEROS
0510      STA ZEROPX
0520      JSR PRZERO
0530      JMP NEXT1
0540      NOZER1    TXA
0550      PHA
0551      TYA
0552      PHA
0560      JSR CONVE
0570      JSR FPOUT   ;PRINT RESULT
0571      PLA
0572      TAY
0580      PLA
0590      TAX
0600      NEXT1    LDA SPACE
0610      JSR OUTCHP  ;PRINT A SPACE
0620      TXA      ;PRINT OUT TOTAL
0630      CLC      ;DWELL TIME
0640      ADC #28
0650      TAY
0660      LDA $02D0,Y ;DWELL TIME FOR INST
0670      STA NUM1
0680      INY
0690      LDA $02D1,Y ;MID BYTE OF DWELL TIME
0700      STA NUM2
0710      INY
0720      LDA $02D2,Y ;HI BYTE OF DWELL TIME
0730      STA NUM3
0740      LDA NUM1      ;SEE IF DWELL TIME
0750      BNE NOZER2  ;IS ZERO
0760      LDA NUM2
0770      BNE NOZER2
0780      LDA NUM3
0790      BNE NOZER2
0800      LDA #00      ;IF SO, PRINT OUT ZEROS
0810      STA ZEROPD
0820      JSR PRZERO
0830      JMP NEXT2
0840      NOZER2    TXA
0850      PHA
0851      TYA
0852      PHA
0860      JSR CONVE
0870      JSR FPOUT   ;PRINT RESULT
0871      PLA
0872      TAY
0880      PLA
0890      TAX
0900      NEXT2    LDA SPACE
0910      JSR OUTCHP  ;PRINT A SPACE
0920      ;PRINT MEAN DWELL TIME=DWELL TIME/NUM OF FIXATIONS
( 30
0940      TXA
          CLC

```

0750 ADC #28  
 0760 TAY  
 0770 LDA ZERODL  
 0780 BNE NOZEP3 ;JUMP IF RESULT NOT ZERO  
 0791 LDA ZEROFX  
 0792 BNE NOZEP3  
 0793 JPF PZERO ;PRINT OUT ZEROS  
 1000 JMP NEXT3  
 1010 NOZEP3 LDA #2D0+Y ;LOW BYTE OF DWELL TIME  
 1020 STA DIVND1  
 1030 INY  
 1040 LDA #2D0+Y ;MID BYTE OF DWELL TIME  
 1050 STA DIVND2  
 1060 INY  
 1070 LDA #2D0+Y ;HI BYTE OF DWELL TIME  
 1080 STA DIVND3  
 1090 INY  
 1100 LDA #2D0+Y ;LO BYTE OF NUMBER OF FIXATIONS  
 1110 STA DIVD1  
 1120 INY  
 1130 LDA #2D0+Y ;HI BYTE OF NUMBER OF FIXATIONS  
 1140 STA DIVD2  
 1150 LDA #000  
 1160 STA DIVD3  
 1170 JPF PRINT ;DWELL TIME/NUM OF FIXATIONS-  
 1180 ;OUTPUT RESULT IN FP  
 1190 NEXT3 LDA SPACE  
 1200 JPF OUTCHP ;PRINT A SPACE  
 1210 ;PRINT PROPORTION OF TOTAL TIME=DWELL TIME/TOTAL MISSION  
 1220 ;DWELL TIME  
 1230 TXA  
 1240 CLC  
 1250 ADC #28  
 1260 TAY  
 1270 LDA ZERODL  
 1280 BNE NOZEP4  
 1290 JPF PZERO  
 1300 JMP NEXT4  
 1310 NOZEP4 LDA #2D0+Y ;LO BYTE OF DWELL TIME  
 1320 STA DIVND1  
 1330 INY  
 1340 LDA #2D0+Y ;MID BYTE OF DWELL TIME  
 1350 STA DIVND2  
 1360 INY  
 1370 LDA #2D0+Y ;HI BYTE OF DWELL TIME  
 1380 STA DIVND3  
 1390 LDA TDMIL1 ;PUT TOTAL MISSION  
 1400 STA DIVD1 ; DWELL TIME INTO  
 1410 LDA TDMIL2 ; THE DIVISOR  
 1420 STA DIVD2  
 1430 LDA TDMIL3  
 1440 STA DIVD3  
 1450 JPF PRINT ;DWELL TIME/TOTAL MISSION DWELL TIME-  
 1460 ;RESULT PRINT IN FP FORMAT  
 1470 NEXT4 LDA SPACE

```

1480      JSR OUTCHR  ;PRINT A SPACE
1490  *PRINT PERCENTAGE OF TOTAL FIXATIONS=NUM OF FIXATIONS/
1500  *TOTAL MISSION FIXATIONS
1510      TXA
1520      CLC
1530      ADC #31
1540      TAY
1550      LDA ZEROFX
1560      BNE NOZERS
1570      JSR PRZERO
1580      JMP NEXT5
1590 NOZERS  LDA %$D01,Y  FLOW BYTE OF NUMBER OF FIXATIONS
1600      STA DIVND1
1610      INY
1620      LDA %$D01,Y  HIGH BYTE OF NUMBER OF FIXATIONS
1630      STA DIVND2
1640      LDA $00
1650      STA DIVND3
1660      LDA TOTFX1  ;PUT THE TOTAL NUMBER OF
1670      STA DIV11   ; FIXATIONS FOR THE
1680      LDA TOTFX2  ; MISSION INTO
1690      STA DIV12   ; THE DIVISOR
1700      LDA TOTFX3
1710      STA DIV13
1720      JSR PRINT  ;FIXATIONS/TOTAL MISSION FIXATION-
1730  *PRINT RESULT IN FP FORMAT
1740 NEXT5   PLA
1750      TAY  ;RESTORE Y FROM STACK
1760      RTS
1770  *SUBROUTINE TO PRINT OUT A ZERO RESULT
1780 PRZERO  TXA
1790      PHA  ;SAVE X REGISTER
1800      LDA #14
1810      STA COUNT
1820      LDY $00
1830 LOOP    LDA ZEROUT+X
1840      JSR OUTCHR  ;PRINT A CHAR
1850      INX
1860      DEC COUNT
1870      BNE LOOP
1880      PLA
1890      TAX  ;RESTORE X
1900      RTS
1910      .EN

```

Module: Output Second Table

>LOAD OUTTC

```

>PR
0010      .BA $3500
0020      .DS
0030  TRANS  .BY 'TRANSITIONS BETWEEN TWO INSTRUMENTS'
0040  SOURCE  .BY 'SOURCE'
0050  BLANK   .BY ''
0060  UNDER   .BY ''
0070  HEAD1   .BY 'NO D6 01 02 03 04 05 06 07 08 09 10 '
0080  HEAD2   .BY '11 12 '
0090  COL     .BY 'GLBLDG0102030405060708091011121314151617181920'
0100  COL1    .BY '2122232425E'
0110  TABLE1  .DE $6000
0120  TABLE2  .DE $6100
0130  TABLE3  .DE $6200
0140  TABLE4  .DE $6300
0150  OUTBYT  .DE $82FA  ;OUTPUT A BYTE
0160  OUTCHR  .DE $8H47  ;OUTPUT A CHARACTER
0170  CRLF    .DE $834D  ;CARRIAGE RETURN AND LINE FEED
0180  COUNT1  .DS 1
0190  COUNT2  .BY 6
0200  BINDEC  .DE $39B1
.10  TEMP    .DS 1
.220  ;
0230  ;PRINT OUT HEADER FOR THE SECOND TABLE OF RESULTS
0240  OUTTC   LDX #00
0250          LDY #35
0260          JSR CRLF
0270  LOOPC   LDA TRANS,X
0280          JSR OUTCHR ;PRINT HEADER
0290          INX
0300          DEY
0310          BNE LOOPC
0320          JSR CRLF
0330          JSR CRLF
0340          LDX #00
0350          LDY #32
0360  LOOPA   LDA BLANK
0370          JSR OUTCHR ;PRINT A SPACE
0380          DEY
0390          BNE LOOPA
0400  LOOPB   LDA SOURCE,X
0410          JSR OUTCHR ;PRINT 'SOURCE'
0420          INX
0430          DEC COUNT2
0440          BNE LOOPB
0450          JSR CRLF
.460          JSR CRLF ;SKIP A LINE
.70          LDX #00
0480          LDY #00

```

0490	LOOP1	LDA BLANK JSR OUTCHR INX	:PRINT A BLANK :PRINT A BLANK
0500		LDA HEAD1,X	:PRINT ONE CHAR OF HEADER
0510		JSR OUTCHR INX	
0520		LDA HEAD1,X	
0530		JSR OUTCHR INX	:PRINT ONE CHAR OF HEADER
0540		LDA HEAD1,X	
0550		JSR OUTCHR INX	:PRINT ONE CHAR OF HEADER
0560		LDA HEAD1,X	
0570		JSR OUTCHR INX	:PRINT OUT ONE CHAR OF HEADER
0580		LDA HEAD1,X	
0590		JSR OUTCHR INX	
0600		INY	
0610		CPY #14	
0620		BNE LOOP1	
0630		LDY #00	:DEFINES LOCATION ON COL
0640		LDX #70	
0650		JSR CRLF	
0660	LOOPU	LDA UNDER	
0670		JSR OUTCHR	:UNDERLINE THE HEADER
0680		DEM	
0690		BNE LOOPU	
0700		JSR CRLF	
0710		LDX #00	
0720		LDA #13	
0730	OUTL01	STA COUNT1	
0740		JSR CRLF	:GO TO NEXT LINE
0750		JSR OUTBG	:OUTPUT BEGINNING OF ROW
0760	VLOOP1	JSR VOUT1	:PRINT DATA FOR AN INST
0770		DEC COUNT1	
0780		BNE VLOOP1	
0790		CPX #\$D9	
0800		BEO NEXT2	:GO TO NEXT TABLE
0810		TXA	
0820		CLC	
0830		ADC #21	:GO TO NEXT INST IN TABLE
0840		TAX	:GO TO NEXT INST
0850		JMP OUTL01	
0860	NEXT2	LDX #00	
0870	OUTL02	LDA #13	
0880		STA COUNT1	:REINITIALIZE COUNT1
0890		JSR CRLF	:GO TO NEXT LINE
0900		JSR OUTBG	:PRINT OUT COLUMN HEADER
0910	VLOOP2	JSR VOUT2	:PRINT ROW FOR AN INST
0920		DEC COUNT1	
0930		BNE VLOOP2	
0940		CPX #\$D9	
0950		BEO NEXT3	:GO TO NEXT TABLE IF DONE WITH THIS ONE
0960		TXA	
0970		CLC	
0980		ADC #21	:GO TO NEXT INST IN TABLE
0990		TAX	
1000		JMP OUTL02	
1010	NEXT3	LDX #00	
1020	OUTL03	LDA #13	

1040	STA COUNT1	:REINITIALIZE COUNT1	
1050	JSR CRLF	:GO TO NEXT LINE	
1060	JSR OUTBG	:PRINT OUT COLUMN HEADER	
1070	JSR YOUT3	:PRINT OUT A ROW FOR AN INST	
1080	DEC COUNT1		
1090	BNE VLOOP3		
1100	CPX #\$D9		
1110	BED NEXT4	:GO TO NEXT TABLE IF DONE WITH THIS ONE	
1120	TXA		
1130	CLC		
1140	ADC #21	:GO TO NEXT INST IN TABLE	
1150	TAX		
1160	JMP OUTL03		
1170	LDA #00		
1180	LDA #13		
1190	STA COUNT1	:REINITIALIZE COUNT1	
1200	JSR CRLF	:GO TO NEXT LINE	
1210	JSR OUTBG	:PRINT OUT COLUMN HEADER	
1220	JSR YOUT4	:PRINT ROW FOR AN INST	
1230	DEC COUNT1		
1240	BNE VLOOP4		
1250	CPX #\$D9		
1260	BED NEXT5	:DONE WITH THE FOUR TABLES IF DONE WITH THIS ONE	
1270	TXA		
1280	CLC		
1290	ADC #21	:GO TO NEXT INST IN TABLE	
1300	TAX		
1310	JMP OUTL04		
1320	RTS		
1330	:		
1340	OUTBG	LDA BLANK	
1350		JSR OUTCHR	:PRINT A BLANK
1360		JSR OUTCHR	:PRINT A BLANK
1370		LDA COL_Y	
1380		JSR OUTCHR	:PRINT OUT COLUMN HEADER
1390		INY	
1400		LDA COL_Y	
1410		JSR OUTCHR	
1420		INY	
1430		LDA BLANK	
1440		JSR OUTCHR	
1450		RTS	
1460	:		
1470	YOUT1	LDA TABLE1,X	
1480		STA TEMP	
1490		TYA	
1500		PHA :PUT INDEX Y ON STACK	
1510		TXA	
1520		PHA	
1530		LDA TEMP	
1540		JSR BINDEC	:CONVEPT NUMBER TO DECIMAL
1550		JSR OUTBYT	:PRINT HI BYTE OF DECIMAL NO
1560		TYA	
70		JSR OUTBYT	:PRINT LO BYTE OF DECIMAL NO
1580		LDA BLANK	

```

1590      JER OUTCHR  :PRINT A BLANK
1600      PLA
1610      TAX
1620      PLA
1630      TAY  :RESTORE INDEX Y FROM STACK
1640      INX
1650      RTS
1660      :
1670  VOUT2    LDA TABLE2,X
1680      STA TEMP
1690      TYA
1700      PHA  :PUT INDEX Y ON STACK
1710      TXA
1720      PHA
1730      LDA TEMP
1740      JCR BINDEC :CONVERT NUMBER TO DECIMAL
1750      JCR OUTBYT :PRINT HI BYTE OF DECIMAL NO
1760      TYA
1770      JCR OUTBYT :PRINT LO BYTE OF DECIMAL NO
1780      LDA BLANK
1790      JER OUTCHR  :PRINT A BLANK
1800      PLA
1810      TAX
1820      PLA
1830      TAY  :RESTORE INDEX Y FROM STACK
1840      INX
1850      RTS
1860      :
1870  VOUT3    LDA TABLE3,X
1880      STA TEMP
1890      TYA
1900      PHA  :PUT INDEX Y ON STACK
1910      TXA
1920      PHA
1930      LDA TEMP
1940      JCR BINDEC :CONVERT NUMBER TO DECIMAL
1950      JCR OUTBYT :PRINT HI BYTE OF DECIMAL NO
1960      TYA
1970      JCR OUTBYT :PRINT LO BYTE OF DECIMAL NO
1980      LDA BLANK
1990      JER OUTCHR  :PRINT A BLANK
2000      PLA
2010      TAX
2020      PLA
2030      TAY  :RESTORE INDEX Y FROM STACK
2040      INX
2050      RTS
2060      :
2070  VOUT4    LDA TABLE4,X
2080      STA TEMP
2090      TYA
2100      PHA  :PUT INDEX Y ON STACK
2110      TXA
2120      PHA
2130      LDA TEMP

```

2140	JSR BINDEC	:CONVEPT NUMBER TO DECIMAL
2150	JSR OUTBYT	:PRINT HI BYTE OF DECIMAL NO
2160	TYA	
2170	JSR OUTBYT	:PPINT LO BYTE OF DECIMAL NO
2180	LDA BLANK	
2190	JEP OUTCHR	:PPINT A BLANK
2200	PLA	
2210	THX	
2220	PLA	
2230	TAY	:RESTORE INDEX Y FROM STACK
2240	INX	
2250	RTS	
2260	.EN	

22. Module: Output Third Table.

>LOAD OUTTD

```

SPP
0010      .BR $3750
0020      .02
0030  BLANK   .BY 1
0040  UNDER   .BY 1
0050  HEAD1   .BY 10 13 14 15 16 17 18 19 20 21 22 23 '
0060  HEAD2   .BY 24 25 '
0070  COL     .BY 161BLD050102030405060708091011121314151617181920'
0080  COLI    .BY 12122232425E'
0090  TABLE1  .DE $6000
0100  TABLE2  .DE $6100
0110  TABLE3  .DE $6200
0120  TABLE4  .DE $6300
0130  OUTBYT  .DE $82FA ;OUTPUT A BYTE
0140  OUTCHR  .DE $8A47 ;OUTPUT A CHARACTER
0150  CPLF    .DE $834D ;CARRIAGE RETURN AND LINE FEED
0160  COUNT1  .DS 1
0170  RINDEC  .DE $39B1
0180  TEMP    .DS 1
0190  ;
0200  ;PRINT OUT HEADER FOR THE SECOND TABLE OF RESULTS
0210  OUTTD  JSR CPLF
0220      JSR CPLF
0230      JSR CPLF ;SKIP A LINE
0240      LDY #00
0250      LDY #00
0260  LOOP1   LDA BLANK
0270      JSR OUTCHR ;PRINT A BLANK
0280      JSR OUTCHR ;PRINT A BLANK
0290      LDA HEAD1,X
0300      JSR OUTCHR ;PRINT ONE CHAR OF HEADER
0310      INX
0320      LDA HEAD1,X
0330      JSR OUTCHR ;PRINT ONE CHAR OF HEADER
0340      INX
0350      LDA HEAD1,X
0360      JSR OUTCHR ;PRINT OUT ONE CHAR OF HEADER
0370      INX
0380      INY
0390      CPY #14
0400      RNE LOOP1
0410      LDY #00 ;DEFINES LOCATION ON COL
0420      LDX #70
0430      JSR CPLF
0440  LOOPU   LDA UNDER
0450      JSR OUTCHR ;UNDERLINE THE HEADER
0460      DEX
0470      BNE LOOPU

```

0480	JEP CPLF	
0490	LDX #\$00	
0500 OUTL01	LDA #13	
0510	STA COUNT1	
0520	JEP CPLF	:GO TO NEXT LINE
0530	JEP OUTBG	:OUTPUT BEGINNING OF ROW
0540 VLOOP1	JEP VOUT1	:PRINT DATA FOR AN INST
0550	DEC COUNT1	
0560	BNE VLOOP1	
0570	CPX #1E6	
0580	BEO NEXT2	:GO TO NEXT TABLE
0590	TXA	
0600	CLC	
0610	ADC #21	:GO TO NEXT INST IN TABLE
0620	TAX :GO TO NEXT INST	
0630	JMP OUTL01	
0640 NEXT2	LDX #\$00	
0650 OUTL02	LDA #13	
0660	STA COUNT1	:REINITIALIZE COUNT1
0670	JEP CPLF	:GO TO NEXT LINE
0680	JEP OUTBG	:PRINT OUT COLUMN HEADER
0690 VLOOP2	JEP VOUT2	:PRINT ROW FOR AN INST
0700	DEC COUNT1	
0710	BNE VLOOP2	
0720	CPX #1F6	
0730	BEO NEXT3	:GO TO NEXT TABLE IF DONE WITH THIS ONE
0740	TXA	
0750	CLC	
0760	ADC #21	:GO TO NEXT INST IN TABLE
0770	TAX	
0780	JMP OUTL02	
0790 NEXT3	LDX #\$00	
0800 OUTL03	LDA #13	
0810	STA COUNT1	:REINITIALIZE COUNT1
0820	JEP CPLF	:GO TO NEXT LINE
0830	JEP OUTBG	:PRINT OUT COLUMN HEADER
0840 VLOOP3	JEP VOUT3	:PRINT OUT A ROW FOR AN INST
0850	DEC COUNT1	
0860	BNE VLOOP3	
0870	CPX #1E6	
0880	BEO NEXT4	:GO TO NEXT TABLE IF DONE WITH THIS ONE
0890	TXA	
0900	CLC	
0910	ADC #21	:GO TO NEXT INST IN TABLE
0920	TAX	
0930	JMP OUTL03	
0940 NEXT4	LDX #\$00	
0950 OUTL04	LDA #13	
0960	STA COUNT1	:REINITIALIZE COUNT1
0970	JEP CPLF	:GO TO NEXT LINE
0980	JEP OUTBG	:PRINT OUT COLUMN HEADER
0990 VLOOP4	JEP VOUT4	:PRINT ROW FOR AN INST
1000	DEC COUNT1	
110	BNE VLOOP4	
120	CPX #1E6	

1030	BED NEXT5	:DONE WITH THE FOUR TABLES IF DONE WITH THIS ONE
1040	TXA	
1050	CLC	
1060	ADC #21	:GO TO NEXT INST IN TABLE
1070	TAX	
1080	JMP OUTL04	
1090	NEXT5	RTS
1100	:	
1110	OUTB6	LDA BLANK
1120		JEP OUTCHR :PRINT A BLANK
1130		JEP OUTCHR :PRINT A BLANK
1140		LDA COL+Y
1150		JSP OUTCHR :PRINT OUT COLUMN HEADER
1160		INY
1170		LDA COL+Y
1180		JEP OUTCHR
1190		INY
1200		LDA BLANK
1210		JEP OUTCHR
1220		RTS
1230	:	
1240	VOUT1	LDA TABLE1+X
1250		STA TEMP
1260		TYA
1270		PHA :PUT INDEX Y ON STACK
1280		TXA
1290		PHA
1300		LDA TEMP
1310		JSR BINDEC :CONVERT NUMBER TO DECIMAL
1320		JSR OUTBYT :PRINT HI BYTE OF DECIMAL NO
1330		TYA
1340		JSP OUTBYT :PRINT LO BYTE OF DECIMAL NO
1350		LDA BLANK
1360		JEP OUTCHR :PRINT A BLANK
1370		PLA
1380		TAX
1390		PLA
1400		TAY :RESTORE INDEX Y FROM STACK
1410		INX
1420		RTS
1430	:	
1440	VOUT2	LDA TABLE2+X
1450		STA TEMP
1460		TYA
1470		PHA :PUT INDEX Y ON STACK
1480		TXA
1490		PHA
1500		LDA TEMP
1510		JSR BINDEC :CONVERT NUMBER TO DECIMAL
1520		JSR OUTBYT :PRINT HI BYTE OF DECIMAL NO
1530		TYA
1540		JSP OUTBYT :PRINT LO BYTE OF DECIMAL NO
1550		LDA BLANK
1560		JEP OUTCHR :PRINT A BLANK
1570		PLA

1580	TAX
1590	PLA
1600	TAY ;RESTORE INDEX Y FROM STACK
1610	INX
1620	RTS
1630 :	
1640 VOUT3	LDA TABLE3,X
1650	STA TEMP
1660	TYA
1670	PHA ;PUT INDEX Y ON STACK
1680	TXA
1690	PHA
1700	LDA TEMP
1710	JSR BINDEC ;CONVERT NUMBER TO DECIMAL
1720	JSR OUTBYT ;PRINT HI BYTE OF DECIMAL NO
1730	TYA
1740	JSR OUTBYT ;PRINT LO BYTE OF DECIMAL NO
1750	LDA BLANK
1760	JSR OUTCHR ;PRINT A BLANK
1770	PLA
1780	TAX
1790	PLA
1800	TAY ;RESTORE INDEX Y FROM STACK
1810	INX
1820	RTS
1830 :	
1840 VOUT4	LDA TABLE4,X
1850	STA TEMP
1860	TYA
1870	PHA ;PUT INDEX Y ON STACK
1880	TXA
1890	PHA
1900	LDA TEMP
1910	JSR BINDEC ;CONVERT NUMBER TO DECIMAL
1920	JSR OUTBYT ;PRINT HI BYTE OF DECIMAL NO
1930	TYA
1940	JSR OUTBYT ;PRINT LO BYTE OF DECIMAL NO
1950	LDA BLANK
1960	JSR OUTCHR ;PRINT A BLANK
1970	PLA
1980	TAX
1990	PLA
2000	TAY ;RESTORE INDEX Y FROM STACK
2010	INX
2020	RTS
2030	.EN

24. Module: Convert From Binary to Decimal - called by Output  
 Second Table and Output Third Table modules.

SLDIAD BINDEC

```

$PF
0010      .BA $3980
0020      .DE
0030 ; THIS ROUTINE CONVERTS A ONE BYTE HEX NUMBER TO
0040 ;A TWO BYTE DECIMAL NUMBER. THE HEX NUMBER IS IN THE
0050 ;ACC. THE HI BYTE OF THE DECIMAL NUMBER IS IN THE
0060 ;ACC AND THE LOW BYTE IN REGISTER Y
0070 TEMP    .DE 1      ;TEMPORARY STORAGE
0080 BINDEC LDY #FF    ;START QUOTIENT AT -1
0090 SEC     ;SET CARRY FOR INITIAL SUBTRACTION
0100 D100LP INY ;ADD 1 TO QUOTIENT
0110 SBC #100   ;SUBTRACT 100
0120 BCS D100LP ;BRANCH IF A IS STILL LARGER THAN 100
0130 ADC #100   ;ADD THE LAST 100 BACK
0140 TAX     ;SAVE REMAINDER
0150 TYA
0160 PHA     ;SAVE 100'S DIGIT ON THE STACK
0170 TXA     ;GET REMAINDER
0180 ; CALCULATE 10'S AND 1'S DIGITS. DIVIDE REMAINDER
0190 ;OF THE 100'S DIGIT BY 10.
0200 ;Y = 10'S DIGIT
0210 ;A = 1'S DIGIT
0220 LDY #FF    ;START QUOTIENT AT -1
0230 SEC     ;SET CARRY FOR INITIAL SUBTRACTION
0240 D10LP INY ;ADD 1 TO QUOTIENT
0250 SBC #10
0260 BCS D10LP ;BRANCH IF A IS STILL LARGER THAN 10
0270 ADC #10   ;ADD THE LAST 10 BACK
0280 ;COMBINE 1'S AND 10'S DIGITS
0290 STA TEMP
0300 TYA
0310 ASL A
0320 ASL A
0330 ASL A
0340 ASL A      ;MOVE 10'S TO HIGH NIBBLE OF A
0350 ORA TEMP    ;OR IN THE 1'S DIGIT
0360 ;RETURN WITH Y = LOW BYTE A = HIGH BYTE
0370 TAY     ;PLACE IN REG Y
0380 PLA     ;GET 100'S DIGIT
0390 RTS
0400 .EN

```

## 25. Module: Print Results.

1 LOAD FINAL

```
>PP
0010      .BA $39F0
0020      .OS
0030  ; THIS ROUTINE WILL PRINT OUT THE FINAL THREE TABLES
0040  OUTTC  .DE $3591  ;FIRST TABLE THAT PRINTS OUT TRANSITIONS
0050  ;BETWEEN INSTRUMENTS
0060  OUTTD  .DE $37B7  ;SECOND TABLE THAT PRINTS OUT TRANSITIONS
0070  ;BETWEEN INSTRUMENTS
0080  TOVAL  .DE $2706  ;ADD UP TOTAL MISSION FIXATIONS AND
0090  ;TOTAL MISSION DWELL TIME
0100  OUTPT1  .DE $2915  ;PRINT OUT HEADER FOR FIRST TABLE
0110  OUTTB  .DF $2H98  ;PRINT OUT BODY OF FIRST TABLE
0120  FINAL   JCR TOVAL
0130          JCR OUTPT1
0140          JCR OUTTB
0150          JCR OUTTC
0160          JCR OUTTD
0170          PTC
0180
0190      .EN
```

APPENDIX E  
Module Validation Data

This appendix shows the data used to test each module or portion of a module. A "\$" in front of a number means that number is in base 16.

1. Division subroutine for Add Timing

Table 5  
Division Validation Data

<u>Dividend</u>	<u>Divisor</u>	<u>Quotient</u>	<u>Remainder</u>
60000	1000	60	0
60000	50	1200	0
50000	300	16	200
60000	90	666	60

2. Module Add Timing

Table 6  
Add Timing Validation Data

<u>Number of Sample</u>	<u>Number of Time Intervals</u>			<u>Num of Intervals Since Last Sample</u>
	<u>Hexidecimal</u>	<u> </u>	<u>Decimal</u>	
01	00 00	11	17	
02	00 00	23	35	18
03	00 00	35	53	18
04	00 00	48	72	19
05	00 00	5A	90	18
06	00 00	6C	108	18
07	00 00	7E	126	18
08	00 00	91	145	19
09	00 00	A3	163	18
\$0A	00 00	B5	181	18
\$0B	00 00	C6	198	17
\$0C	00 00	DA	218	20
\$0D	00 00	EC	236	18
\$0E	00 00	FE	254	18
\$0F	00 01	0F	271	17
\$10	00 01	21	289	18
\$11	00 01	33	307	18
\$12	00 01	46	326	19
\$13	00 01	58	344	18
\$14	00 01	6A	362	18

3. Module Determine Instrument Number

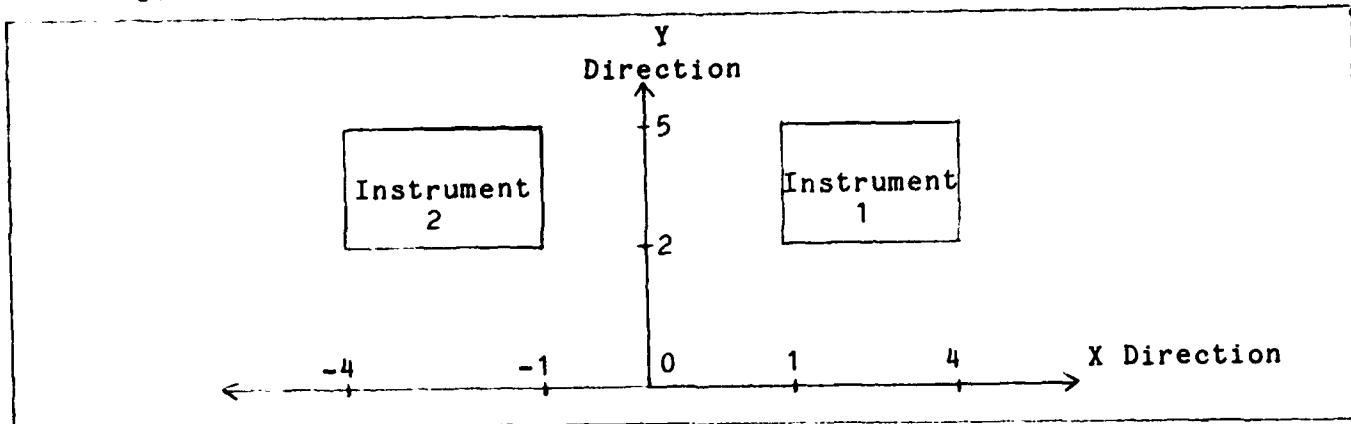


Fig. 6. Test Instrument Boundaries

Table 7

Determine Instrument Number Validation Data

<u>X eye direction</u>	<u>Y eye direction</u>	<u>Instrument Number</u>
2	3	01
5	3	No instrument
6	3	No instrument
-2	3	02
-2	6	No instrument
16383	3	No instrument
1	3	No instrument
4	3	01
-1	3	02
-4	3	No instrument
0	0	No instrument
3	2	No instrument
3	5	01

4. Module Compare Data Samples

Table 8  
Compare Data Samples Validation Data

<u>Input Data Samples</u>				<u>Output</u>			
Instrument Number	Data Sample Time(Hexidecimal)			Instrument Number	Total Time On Inst(Hexidecimal)		
<b>1st test:</b>							
01	00	00	11	00	00	00	11
01	00	00	22				
01	00	00	33				
02	00	00	44	01	00	00	33
02	00	00	55				
03	00	00	66	02	00	00	11
01	00	00	77				
01	00	00	88				
03	00	00	99	01	00	00	22
<b>2nd test:</b>							
\$10	00	00	14	00	00	00	14
05	00	01	11	10	00	00	FD
05	00	01	A1				
03	01	CF	00	05	01	CD	EF
03	02	00	00				
03	02	11	01				
\$AA	02	11	A1	03	00	42	A1
\$AA	02	11	C0				
01	0C	D0	54	AA	0A	BE	BC
02	0C	D0	64	01	00	00	10

5. Module Create Table

Table 9  
Create Table Validation Data

<u>Inst Number</u>	<u>Total Time On Inst(Hexidecimal)</u>	<u>Last Instrument (Determined by Create Table)</u>
<b>Test 1:</b>		
01	00 00 31	00
01	00 00 33	00
00	00 00 B6	01
00	00 00 B8	01
10	00 00 FC	00
13	00 11 00	10
20	00 00 CD	13
10	00 01 00	20
<b>Test 2:</b>		
11	00 00 FF	00
11	00 01 11	11
11	00 00 20	11
00	00 00 CC	11
22	00 20 14	00
23	00 20 14	22
24	00 30 14	23
19	00 32 00	24
12	00 A0 00	19
<b>Test 3:</b>		
08	00 8C 00	00
03	00 01 00	08
04	00 04 00	03
02	00 02 00	04
05	00 05 01	02
06	00 00 E6	05
07	00 00 F7	06
09	01 01 11	07
14	01 01 00	09

Table 10  
Create Table Validation Results

<u>Starting Mem Location</u>	<b>Consecutive Mem contents (if location between 6000 and 63FF is not listed, it is zero)</b>
--------------------------------------	---

**Test 1:**

6000	01 00 00 00 00 00 00 00 00 00
6018	00 00 00 00 00 31 00 00 00 01
6020	00 00 00 01 00 00 00 00 00 00
6038	00 00 00 00 00 00 00 00 B6 00
6040	00 01 00 00 00 00 01 00 00 00
6060	B8 00 00 01 00 00 00 01 00 00
6080	33 00 00 01 00 00 00 00 00 00
61A8	00 00 01 00 00 00 00 00 00 00
61B8	00 00 00 00 00 00 00 01 00 00
61C0	00 00 00 00 00 00 00 FC 01 01
61C8	00 02 00 00 00 00 00 00 00 00
6228	00 00 00 00 01 00 00 00 00 00
6238	00 00 00 00 00 00 00 CD 11 00
6340	00 01 00 00 00 00 00 00 00 00

**Test 2:**

6008	00 00 00 01 00 00 00 00 00 00
6018	00 00 00 00 00 20 00 00 00 01
6048	00 00 00 00 00 00 00 00 00 01
6060	CC 00 00 01 00 00 00 00 00 00
61C8	00 00 00 00 01 00 00 00 00 00
61D0	00 00 00 00 00 00 00 00 00 01
61E8	10 02 00 02 00 00 00 00 00 00
6210	00 00 00 01 00 00 00 00 00 00
6218	00 00 00 00 00 00 A0 00 01 01
6318	01 00 00 00 00 00 32 00 00 01
6360	00 00 00 00 00 00 00 01 00 00
6380	00 00 14 20 00 01 00 00 00 00
6398	00 00 00 00 00 00 00 01 00 00
63A0	00 00 00 00 00 14 20 00 00 01
63C0	00 01 00 00 00 00 00 14 30 00
63C8	00 01 00 00 00 00 00 00 00 00

Test 3

6088	00	00	00	00	01	00	00	00
60A0	00	00	00	00	00	02	00	01
60B0	00	00	01	00	00	00	00	00
60C0	00	00	00	00	00	00	00	01
60C8	00	01	00	00	00	00	00	01
60E8	00	04	00	01	00	00	00	00
6100	00	00	01	00	00	00	00	00
6118	00	00	00	00	01	05	00	01
6120	00	00	00	00	00	00	00	01
6138	00	00	00	00	00	00	E6	00
6140	00	01	00	00	00	00	00	00
6148	00	00	01	00	00	00	00	00
6160	F7	00	00	01	00	00	01	00
6180	00	00	00	8C	00	01	00	00
6188	00	00	00	00	00	00	00	01
61A0	00	00	00	00	11	01	01	01
6248	00	00	00	00	00	01	00	00
6260	00	01	01	01	00	00	00	00

Appendix F  
Simulated Oculometer Input for Subsystem Validation

Track/Out-of Track Status	X Eye Direction (hex)	Y Eye Direction (hex)
<hr/>		
Test 1:		
01	00 3C	01 2C
01	00 3C	01 2C
01	00 04	01 2C
01	00 04	01 2C
01	00 04	01 2C
01	00 04	01 2C
01	00 04	01 2C
01	00 04	01 2C
01	00 04	01 2C
01	00 00	01 90
01	00 00	01 90
01	FF 9C	01 3C
01	FF 9C	00 3C
01	FF 9C	00 3C
01	FF 9C	00 3C
01	FF 9C	00 3C
01	FF 9C	00 3C
01	FF 9C	00 3C
00	FF 9C	00 3C
00	FF 9C	00 3C
00	FF 9C	00 3C
01	FF 9C	00 64
01	FF 9C	00 64
01	FF 9C	00 64
01	FF 9C	00 64
01	FE D4	00 C8
01	FE D4	00 C8
01	FE D4	00 C8
01	FE D4	01 2C
01	FE D4	00 2C
01	FE D4	01 2C
01	FE D4	01 2C
01	FE D4	01 2C
01	00 00	01 90
01	00 00	01 90
01	00 00	01 90
01	00 00	01 90

01	00	00	00	90
01	00	64	00	64
01	00	64	00	64
01	00	64	00	64
01	00	64	00	64
00	00	01	00	01

Test 2:

01	FF	38	01	90
01	FF	38	01	90
01	FF	38	01	90
01	FF	38	01	90
01	00	64	01	DB
01	00	64	01	DB
01	00	64	01	DB
01	00	64	01	DB
01	00	64	01	DB
01	00	C8	00	7D
01	00	C8	00	7D
01	00	C8	00	7D
01	00	C8	00	7D
01	00	C8	00	7D
01	01	90	00	64
01	01	90	00	64
01	01	90	00	64
00	01	90	00	3C
00	01	90	00	3C
01	FF	9C	01	2C
01	FF	9C	01	2C
01	FF	9C	01	2C
01	00	64	01	E0
01	00	64	01	E0
01	00	64	01	E0
01	00	64	01	DB
01	00	64	01	DB
01	00	64	01	DB

## APPENDIX G

### Final Data Tables and Outputs

1. The following are the results of Test 1 inputs of Appendix F.

a. Final Data Table in memory locations 6000 (hex) to 6400 (hex).

```
.E 6000,6400
6000 01 00 00 00 00 00 00 00,01
6008 00 00 00 00 00 00 00 00,01
6010 00 00 00 00 00 00 00 00,01
6018 00 00 00 00 11 00 00 01,13
6020 00 00 00 00 00 00 00 01,14
6028 00 00 00 00 00 00 00 00,14
6030 00 00 00 00 00 00 00 00,14
6038 00 00 00 00 00 00 37 00,4B
6040 00 01 00 00 00 00 00 00,4C
6048 00 00 00 00 00 00 00 00,4C
6050 00 00 00 00 00 00 00 00,4C
6058 00 00 00 00 00 00 00 00,4C
6060 00 00 00 00 00 01 00 00,4D
6068 00 00 00 00 00 00 00 00,4D
6070 00 00 00 00 00 00 00 00,4D
6078 00 00 00 00 00 00 00 00,4D
6080 00 00 00 00 00 01 00 00,DE
6088 00 00 00 00 00 00 00 00,DE
6090 00 00 00 00 00 00 00 00,DE
6098 00 00 00 00 00 00 00 00,DE
60A0 00 00 00 00 00 00 00 00,DE
60A8 00 00 00 00 00 01 00,DF
60B0 00 00 00 00 00 00 00 00,DF
60B8 00 00 00 00 00 00 00 00,DF
60C0 00 00 00 00 00 00 6E 00,4D
60C8 00 01 00 00 00 00 00 00,4E
60D0 00 01 00 00 00 00 00 00,4F
60D8 00 00 00 00 00 00 00 00,4F
60E0 00 00 00 00 00 00 00 00,4F
60E8 39 00 00 01 00 00 00 00,89
60F0 00 00 00 00 00 00 00 00,89
60F8 00 00 00 00 00 00 00 00,89
6100 00 00 00 00 01 00 00,8A
6108 00 00 00 00 00 00 00 00,8A
6110 00 00 00 00 00 00 00 00,8A
6118 00 01 00 00 C8 00 00 02,58
6120 00 00 00 00 00 00 00 00,58
6128 00 00 00 00 00 00 00 00,58
6130 00 00 00 00 00 00 00 00,58
6138 00 00 00 00 00 00 00 00,58
6140 00 00 00 00 00 00 00 00,58
6148 00 00 00 00 00 00 00 00,58
6150 00 00 00 00 00 00 00 00,58
6158 00 00 00 00 00 00 00 00,58
```



6:18 00 00 00 00 00 00 00 00,58  
6:20 00 00 00 00 00 00 00 00,58  
6:28 00 00 00 00 00 00 00 00,58  
6:30 00 00 00 00 00 00 00 00,58  
6:33 00 00 00 00 00 00 00 00,58  
6:34 00 00 00 00 00 00 00 00,58  
6:348 00 00 00 00 00 00 00 00,58  
6:350 00 00 00 00 00 00 00 00,58  
6:358 00 00 00 00 00 00 00 00,58  
6:360 00 00 00 00 00 00 00 00,58  
6:368 00 00 00 00 00 00 00 00,58  
6:370 00 00 00 00 00 00 00 00,58  
6:378 00 00 00 00 00 00 00 00,58  
6:380 00 00 00 00 00 00 00 00,58  
6:388 00 00 00 00 00 00 00 00,58  
6:390 00 00 00 00 00 00 00 00,58  
6:398 00 00 00 00 00 00 00 00,58  
6:3A0 00 00 00 00 00 00 00 00,58  
6:3A8 00 00 00 00 00 00 00 00,58  
6:3B0 00 00 00 00 00 00 00 00,58  
6:3B8 00 00 00 00 00 00 00 00,58  
6:3C0 00 00 00 00 00 01 00 01,58  
6:3D0 00 00 00 00 00 00 00 00,58  
6:3D8 00 00 00 00 00 00 00 00,58  
6:3E0 00 00 00 00 00 00 00 00,58  
6:3E8 FB 00 00 02 00 00 00 00,57  
6:3F0 00 00 00 00 00 00 00 00,57  
78 00 00 00 00 00 00 00 00,57

b. Output of first table.

>MIN FINAL

TOTAL NUMBER OF FIXATIONS IN THE DATA MISSION= +0.7001953E+01  
 TOTAL DWELL TIME IN THE DATA MISSION= +0.7650545E+03

INIT NUM	TOTAL NUMBER OF FIXATIONS	TOTAL DWELL TIME	MEAN DWELL TIME	PROPORTION OF TOTAL TIME	PROPORTION OF TOTAL FIXATION
GLIT	+0.1945312E+01	+0.1735938E+02	+0.1735938E+02	+0.2269199E-01	+0.2142857E+00
BLNK	+0.1000000E+01	+0.5500001E+02	+0.5521876E+02	+0.724469E-01	+0.1428571E+00
DHGN	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
01	+0.1000000E+01	+0.1440000E+03	+0.1442500E+03	+0.1885621E+00	+0.1428571E+00
02	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
03	+0.1000000E+01	+0.1100000E+03	+0.1103281E+03	+0.1447304E+00	+0.1428571E+00
04	+0.1000000E+01	+0.5699999E+02	+0.5764064E+02	+0.748366E-01	+0.1428571E+00
05	+0.2000000E+01	+0.2029999E+03	+0.1019140E+03	+0.2656454E+00	+0.2857142E+00
06	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
07	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
08	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
09	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
10	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
11	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
12	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
13	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
14	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
15	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
16	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
17	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
18	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
19	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
20	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
21	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
22	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
23	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
24	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
25	+0.2000000E+01	+0.2510000E+03	+0.1256757E+03	+0.3282884E+00	+0.2857142E+00

c. Output of second table.

TRANSITIONS BETWEEN TWO INSTRUMENTS

SOURCE

NO	D6	01	02	03	04	05	06	07	08	09	10	11	12
GL	0001	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
BL	0000	0000	0000	0000	0000	0001	0000	0000	0000	0000	0000	0000	0000
D6	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
01	0001	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
02	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
03	0000	0000	0000	0001	0000	0000	0000	0000	0000	0000	0000	0000	0000
04	0000	0000	0000	0000	0001	0000	0000	0000	0000	0000	0000	0000	0000
05	0000	0000	0000	0000	0001	0000	0000	0000	0000	0000	0000	0000	0000
06	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
07	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
08	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
09	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
10	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
11	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
12	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
13	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
4	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
15	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
16	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
17	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
18	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
19	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
20	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
21	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
22	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
23	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
24	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
25	0000	0001	0001	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000

d. Output of third table.

2. The following are the results of Test 2 inputs of Appendix F.

a. Final Data Table in memory locations 6000 (hex) to 6400 (hex)

.V 6000.6400  
6000 01 00 00 00 00 00 00 00.01  
6008 00 00 00 00 00 00 00 00.01  
6010 00 00 00 00 00 00 00 00.01  
6018 00 01 00 00 38 00 00 02.38  
6020 00 00 00 00 00 00 00 00.38  
6028 00 00 00 00 00 00 00 00.38  
6030 00 00 00 00 00 00 00 00.38  
6038 00 00 00 00 00 00 00 00.38  
6040 00 00 00 00 00 00 00 00.38  
6048 00 00 00 00 00 00 00 00.38  
6050 00 00 00 00 00 00 00 00.38  
6058 00 00 00 00 00 00 00 00.38  
6060 00 00 00 00 00 00 00 00.38  
6068 00 00 00 00 00 00 00 00.38  
6070 00 00 00 00 00 00 00 00.38  
6078 00 00 00 00 00 00 00 00.38  
6080 00 00 00 00 00 00 00 00.38  
6088 00 00 00 00 00 00 00 00.38  
6090 00 00 00 00 00 00 00 00.38  
6098 00 00 00 00 00 00 00 00.38  
60A0 00 00 00 00 49 00 00 01.85  
60A8 00 00 00 00 00 00 00 00.85  
60B0 00 00 00 00 00 00 00 00.85  
60B8 00 00 00 00 00 00 00 00.85  
60C0 00 00 00 00 00 00 00 00.85  
60C8 00 00 00 00 00 00 00 00.85  
60D0 00 00 00 00 00 00 00 00.85  
60D8 00 00 00 00 00 00 00 00.85  
60E0 00 00 00 00 00 00 00 00.85  
60E8 00 00 00 00 00 00 00 00.85  
60F0 00 00 00 00 00 00 00 00.85  
60F8 00 00 00 00 00 00 00 00.85  
6100 00 00 00 00 00 00 00 00.85  
6108 00 00 00 00 00 00 00 00.85  
6110 00 00 00 00 00 00 00 00.85  
6118 00 00 00 00 00 00 00 00.85  
6120 00 00 00 01 00 00 00.86  
6128 00 00 00 00 00 00 00 00.86  
6130 00 00 00 00 00 00 00 00.86  
6138 00 00 00 01 00 00 F7 00.7E  
6140 00 02 00 00 00 00 00 00.80  
6148 00 00 01 00 00 00 00 00.81  
6150 00 00 00 00 00 00 00 00.81  
6158 00 00 00 00 00 00 00 00.81



6:18 00 00 00 00 00 00 00 00 00, F4  
6 0 00 00 00 00 00 00 00 00, F4  
6:28 00 00 00 00 00 00 00 00 00, F4  
6:30 00 00 00 00 00 00 00 00 00, F4  
6:38 00 00 00 00 00 00 00 00 00, F4  
6:40 00 00 00 00 00 00 00 00 00, F4  
6:48 00 00 00 00 00 00 00 00 00, F4  
6:50 00 00 00 00 00 00 00 00 00, F4  
6:58 00 00 00 00 00 00 00 00 00, F4  
6:60 00 00 00 00 00 00 00 00 00, F4  
6:68 00 00 00 00 00 00 00 00 00, F4  
6:70 00 00 00 00 00 00 00 00 00, F4  
6:78 00 00 00 00 00 00 00 00 00, F4  
6:80 00 00 00 00 00 00 00 00 00, F4  
6:88 00 00 00 00 00 00 00 00 00, F4  
6:90 00 00 00 00 00 00 00 00 00, F4  
6:98 00 00 00 00 00 00 00 00 00, F4  
6:00 00 00 00 01 00 00 00 00 00, F5  
6:08 00 00 00 00 00 00 00 00 00, F5  
6:09 00 00 00 00 00 01 00 00 00, F6  
6:0F8 84 00 00 02 00 00 00 00 00, 7C  
6:0F0 00 00 00 00 00 00 00 00 00, 7C  
18 00 00 00 00 00 00 00 00 00, 7C

b. Output of first table.

>RUN FINAL

TOTAL NUMBER OF FIXATIONS IN THE DATA MISSION= +0.6001952E+01  
 TOTAL DWELL TIME IN THE DATA MISSION= +0.5667657E+03

INT NUM	TOTAL NUMBER OF FIXATIONS	TOTAL DWELL TIME	MEAN DWELL TIME	PROPORTION OF TOTAL TIME	PROPORTION OF TOTAL FIXATION
GLIT	+0.2250000E+01	+0.5475000E+02	+0.2710937E+02	+0.964829E-01	+0.3333334E+00
BLNK	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
DHGT	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
01	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
02	+0.1000000E+01	+0.7299999E+02	+0.7348437E+02	+0.1291547E+00	+0.1666667E+00
03	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
04	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
05	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
06	+0.2000000E+01	+0.2469999E+03	+0.1237812E+03	+0.4363957E+00	+0.3333334E+00
07	+0.1000000E+01	+0.1139999E+03	+0.1145625E+03	+0.2016894E+00	+0.1666667E+00
08	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
09	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
10	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
11	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
12	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
13	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
14	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
15	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
16	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
17	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
18	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
19	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
20	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
21	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
22	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
23	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
24	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00	+0.0000000E+00
25	+0.2000000E+01	+0.1320000E+03	+0.6649219E+02	+0.2342645E+00	+0.3333334E+00

Output of second table.

TRANSITIONS BETWEEN TWO INSTRUMENTS

	SOURCE	01	02	03	04	05	06	07	08	09	10	11	12
NO	DG	0001	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
1	GL	0001	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
2	BL	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
3	DG	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
4	01	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
5	02	0001	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
6	03	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
7	04	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
8	05	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
9	06	0000	0001	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
10	07	0000	0000	0000	0000	0000	0001	0000	0000	0000	0000	0000	0000
11	08	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
12	09	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
13	10	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
14	11	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
15	12	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
16	13	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
17	14	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
18	15	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
19	16	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
20	17	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
21	18	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
22	19	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
23	20	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
24	21	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000	0000
25	22	0000	0000	0000	0000	0000	0000	0001	0000	0000	0000	0000	0000

#### d. Output of third table.

VITA

Nancy Lillian Wood was born on 13 May 1955 in Bronx, New York. She graduated from high school in Theills, New York in 1973 and attended the University of New Hampshire from which she received the degree of Bachelor of Electrical Engineering in December 1977. Upon graduation, she received a commission in the USAF through the ROTC program. She entered active duty in January 1978 and was assigned to the 475th Test Squadron, Tyndall AFB, Florida. There, she was an engineering project officer and a flight test engineer, flying in F-101, F-106, T-33, and CH-3 aircraft. She was assigned to the Test and Evaluation branch of the Air Defense Weapons Center, Tyndall AFB, Florida, Sep 80, as a project Engineer. She was assigned to the school of Engineering, Air Force Institute of Technology, in June 1981. She is a member of IEEE, Tau Beta Phi, and Eta Kappa Nu.

Permanent address: 29 Fay Rd

New City, New York

10923

~~UNCLASSIFIED~~

SECURITY CLASSIFICATION OF THIS PAGE (When Data Entered)

REPORT DOCUMENTATION PAGE		READ INSTRUCTIONS BEFORE COMPLETING FORM
1. REPORT NUMBER AFIT/GE/EE/82D-72	2. GOVT ACCESSION NO. AD-A124700	3. RECEIPT'S CATALOG NUMBER
4. TITLE (and Subtitle)  DEVELOPMENT OF AN OCULOMETER DATA COLLECTION SUBSYSTEM		5. TYPE OF REPORT & PERIOD COVERED
7. AUTHOR(s)  Nancy L. Wood Capt USAF		6. PERFORMING ORG. REPORT NUMBER
9. PERFORMING ORGANIZATION NAME AND ADDRESS  Air Force Institute of Technology(AFIT-EN) Wright-Patterson AFB, Ohio 45433		10. PROGRAM ELEMENT, PROJECT, TASK AREA & WORK UNIT NUMBERS
11. CONTROLLING OFFICE NAME AND ADDRESS  Flight Dynamics Laboratory(AFWAL/FIGD) Wright-Patterson AFB, Ohio 45433		12. REPORT DATE  December, 1982
14. MONITORING AGENCY NAME & ADDRESS(if different from Controlling Office)		13. NUMBER OF PAGES  146
		15. SECURITY CLASS. (of this report)  Unclassified
		15a. DECLASSIFICATION/DOWNGRADING SCHEDULE
16. DISTRIBUTION STATEMENT (of this Report)  Approved for public release; distribution unlimited.		
17. DISTRIBUTION STATEMENT (of the abstract entered in Block 20, if different from Report)		
18. SUPPLEMENTARY NOTES  Approved for public release: IAW AFR 190-19. <i>Lynne E. Wolaver</i> Lynne E. WOLAYER Dean for Research and Professional Development Air Force Institute of Technology (AFIT) Wright-Patterson AFB OH 45433 <i>4 JAN 1983</i>		
19. KEY WORDS (Continue on reverse side if necessary and identify by block number)  Oculometer SYM-1 6502 Assembly Language		
20. ABSTRACT (Continue on reverse side if necessary and identify by block number)  A SYM-1 microprocessor with dual 5-1/4 inch disk drives was used to develop software to gather and reduce data from a Cubic-Foot Remote Oculometer built by Honeywell, Inc. The primary function of the oculometer is to measure the look direction of a pilot's eye in a ground cockpit simulator. The output of the oculometer used for this effort is eye.		

~~SECRET~~ UNCLASSIFIED

SECURITY CLASSIFICATION OF THIS PAGE(When Data Entered)

lookpoint in azimuth and elevation and whether the oculometer is tracking the eye or not. The line-of-sight measurement covers a viewing field of plus and minus 30 degrees in azimuth and zero to plus 30 degrees in elevation. This viewing field is broken into instruments whose boundaries are defined by the data collection subsystem.

The following performance measures are printed out at the end of the data mission.

1. Total dwell time on each instrument.
2. Mean dwell time on each instrument.
3. Proportion of dwell time on each instrument.
4. Proportion of fixations on each instrument.
5. Transition probability from one instrument to another.
6. Number of fixes per minute for each instrument.

The software for the SYM-1 was developed modularly with each module tested separately and then the whole subsystem tested. Simulated oculometer data was used to test the software. The data collection subsystem was designed to run with minimal knowledge and interaction required by the user.

UNCLASSIFIED

SECURITY CLASSIFICATION OF THIS PAGE(When Data Entered)